

# Predictive Analytics: Ensemble of Gradient-Boosted Decision Trees

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# Predictive Analytics - Example

- ▶ For  $N$  existing bank customers and  $M = 23$  features, i.e. given  $X \in \mathbb{R}^{N \times 23}$  and ground truth  $Y \in \{0, 1\}^N$

$Y:$	Default credit card payment (Yes = 1, No = 0)
$X_{:,1}$	Amount of the given credit (NT dollar)
$X_{:,2}$	Gender (1 = male; 2 = female).
$X_{:,3}$	Education (1=graduate; 2=univ.; 3 = high school; 4 = others).
$X_{:,4}$	Marital status (1 = married; 2 = single; 3 = others).
$X_{:,5}$	Age (year)
$X_{:,6} - X_{:,11}$	Past Delays (-1=duly, . . . , 9=delay of nine months)
$X_{:,12} - X_{:,17}$	Amount of bill statements
$X_{:,18} - X_{:,23}$	Amount of previous payments

Table 1: Yeh, I. C., & Lien, C. H. (2009).

- ▶ Goal: Estimate the default of a new  $(N + 1)$ -th customer, i.e. given  $X_{N+1,:} \in \mathbb{R}^{23}$ , estimate  $Y_{N+1} = ?$

# Problem Definition

- ▶ *Data dimensions*:  $N$  instances having  $M$  features
- ▶ *Features*:  $x \in \mathbb{R}^{N \times M}$  and *Target*:  $y \in \mathbb{R}^N$
- ▶ A *prediction model*: having parameters  $\theta \in \mathbb{R}^K$  is  $f : \mathbb{R}^M \times \mathbb{R}^K \rightarrow \mathbb{R}$

$$\hat{y}_n := f(x_n, \theta)$$

- ▶ *Loss function*:  $\mathcal{L}(y_n, \hat{y}_n) : \mathbb{R} \times \mathbb{R} \rightarrow \mathbb{R}$
- ▶ *Regularization*:  $\Omega(\theta) : \mathbb{R}^K \rightarrow \mathbb{R}$
- ▶ *Objective function*:

$$\operatorname{argmin}_{\theta} \sum_{n=1}^N \mathcal{L}(y_n, \hat{y}_n) + \Omega(\theta)$$

# Prediction Models and Loss Functions

## ► Prediction model:

- Linear model, i.e.  $\hat{y}_n = \sum_{m=1}^M \theta_m X_{n,m}$
- Non-linear models, e.g.: Neural Networks, Kernel-space representation, **Decision Trees**

## ► Loss Function:

- Regression (target is real-values  $y_n \in \mathbb{R}$ ), e.g. least-squares:

$$\mathcal{L}(y_n, \hat{y}_n) := (y_n - \hat{y}_n)^2$$

- Binary Classification  $y_n \in \{0, 1\}$ , e.g. logistic loss:

$$\mathcal{L}(y_n, \hat{y}_n) := -y_n \log(\hat{y}_n) - (1 - y_n) \log(1 - \hat{y}_n)$$

## Multi-class loss - Softmax

- ▶ Re-express targets  $y_n \in \{1, \dots, C\}$  as one-vs-all, i.e.

$$y_{n,c} := \begin{cases} 1 & y_n = c \\ 0 & y_n \neq c \end{cases}$$

- ▶ Learn model parameters per class  $\theta \in \mathbb{R}^{C \times K}$
- ▶ Estimations expressed as probabilities among classes

$$\hat{y}_{n,c} = \frac{e^{f(x_n, \theta_c)}}{\sum_{q=1}^C e^{f(x_n, \theta_q)}}$$

- ▶ Logloss:

$$\mathcal{L}(y_{n,:}, \hat{y}_{n,:}) := - \sum_{c=1}^C y_{n,c} \log(\hat{y}_{n,c})$$

# Classification and Regression Trees (CART)

A prediction model  $\hat{y}_n := f(x_n, \theta)$  can be also a tree:

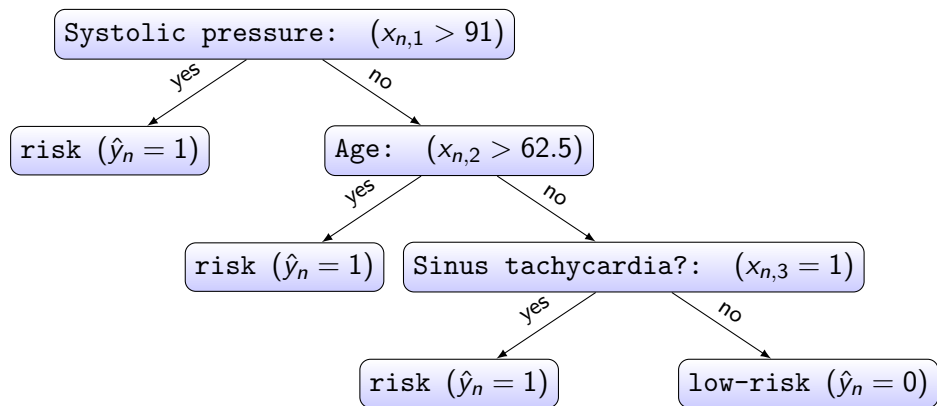


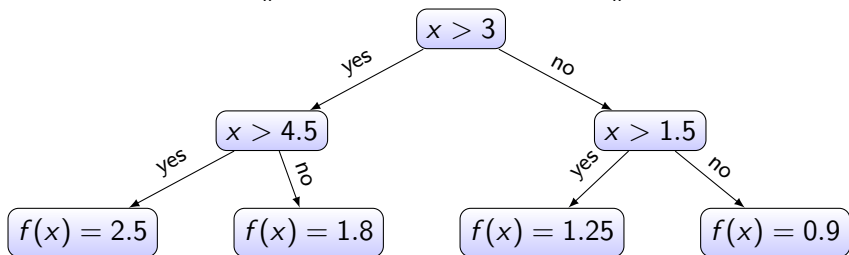
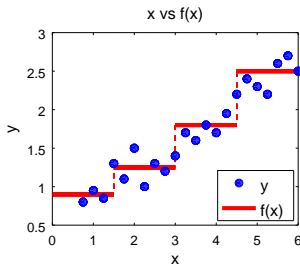
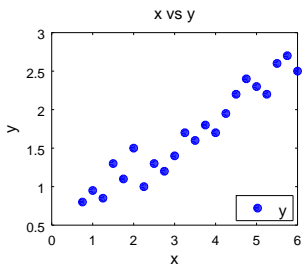
Figure 1: San Diego Medical Center

# Prediction Model of a Decision Tree

- ▶ A tree having  $T$  leaves outputs the weights  $w \in \mathbb{R}^T$ .
- ▶ Let  $q : \mathbb{R}^M \rightarrow \{1, \dots, T\}$  denote the leaf index  $q(x_n)$  where instance  $x_n$  belongs to, then
- ▶ The prediction model of a tree is:

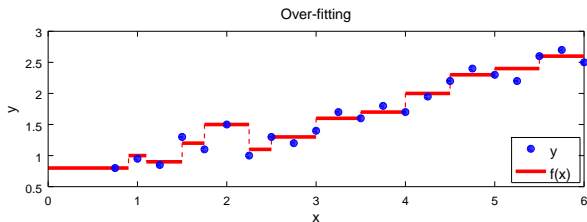
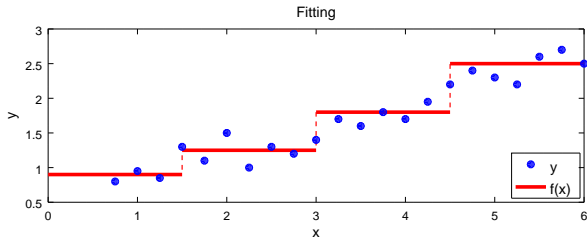
$$f(x_n) = w_{q(x_n)}$$

# Decision Tree as a Step-wise Function





# Tree Over-fitting



Tree over-fits if too many steps (nodes) and high jumps (large leaf weights)

# Tree Regularization

- ▶ *Note:* Too many steps  $\approx$  Too many leaves ( $T$ )
- ▶ *Note:* Too large step jumps  $\approx$  Too large leaves' output values ( $w$ )
- ▶ Penalize the number of leaves and leaves' weights, e.g.:

$$\Omega(f) = \gamma T + \frac{\lambda}{2} \sum_{j=1}^T w_j^2$$

# Boosting

- ▶ Can weak learners (single trees) be combined to create more expressive models?
  - ▶ Jean de La Fontaine: "All power is weak unless united" (1668)
- ▶ Unite single trees into an ensemble of  $k$  trees
- ▶ The estimation is aggregated over the individual trees' predictions:

$$\hat{y}_n^{(1)} := f^{(1)}(x_n), \quad \hat{y}_n^{(2)} := \hat{y}_n^{(1)} + f^{(2)}(x_n), \quad \dots$$

$$\hat{y}_n^{(k)} := \hat{y}_n^{(k-1)} + f^{(k)}(x_n) = \sum_{l=1}^k f^{(l)}(x_n)$$

# Boosted Ensemble Loss

- ▶ Add one tree at a time to the ensemble (greedy strategy)
- ▶ The loss created as a result of adding the contribution of the  $k$ -th tree is:

$$\begin{aligned} & \operatorname{argmin}_{f^{(k)}} \left[ \sum_{n=1}^N \mathcal{L}^{(k)}(Y, \hat{y}_n^{(k-1)} + f^{(k)}(x_n)) \right] + \Omega(f^{(k)}) \\ := & \operatorname{argmin}_{f^{(k)}} \left[ \sum_{n=1}^N \mathcal{L}_n^{(k)} \right] + \Omega(f^{(k)}) \end{aligned}$$

- ▶ How to find the optimal  $k$ -th tree  $f^{(k)}$ ?

# Taylor Approximation

Remember Taylor Expansion (2nd degree):

$$F(x + \Delta x) \approx F(x) + \frac{dF(x)}{dx} \Delta x + \frac{1}{2} \frac{d^2 F(x)}{dx^2} \Delta x^2$$

In our case  $F := \mathcal{L}^{(k)}$  and  $\Delta x = f^{(k)}$

$$\mathcal{L}_n^{(k)} \approx \mathcal{L}_n^{(k-1)} + \frac{\partial \mathcal{L}_n^{(k)}}{\partial \hat{y}_n^{(k-1)}} f^{(k)}(x_n) + \frac{1}{2} \frac{\partial^2 \mathcal{L}_n^{(k)}}{\partial \left(\hat{y}_n^{(k-1)}\right)^2} \left(f^{(k)}(x_n)\right)^2$$

$$\mathcal{L}_n^{(k)} \approx \mathcal{L}_n^{(k-1)} + G_n f^{(k)}(x_n) + \frac{1}{2} H_n \left(f^{(k)}(x_n)\right)^2$$

$$\text{where } G_n := \frac{\partial \mathcal{L}_n^{(k)}}{\partial \hat{y}_n^{(k-1)}}, \quad H_n := \frac{\partial^2 \mathcal{L}_n^{(k)}}{\partial \left(\hat{y}_n^{(k-1)}\right)^2}$$

## Rewrite Objective

Since  $\mathcal{L}_n^{(k-1)}$  is constant w.r.t.  $f^{(k)}$ , then rewrite objective as:

$$\operatorname{argmin}_{f^{(k)}} \sum_{n=1}^N \left[ G_n f^{(k)}(x_n) + H_n \left( f^{(k)}(x_n) \right)^2 \right] + \Omega(f^{(k)})$$

with regularization:

$$\Omega(f^{(k)}) = \gamma T + \frac{\lambda}{2} \sum_{j=1}^T w_j^2$$

## Rewrite objective in terms of leaves

- ▶ Remember  $f^{(k)}(x) := w_{q(x)}$  (previous slide).
- ▶ Let indices of all instances belonging into the  $j$ -th leaf be  $I_j := \{n \mid q(x_n) = j\}$ .

Then, the objective in terms of leaves' weights is:

$$\operatorname{argmin}_{w_1, \dots, w_T} \sum_{n=1}^N \left[ G_n w_{q(x_n)} + \frac{1}{2} H_n w_{q(x_n)}^2 \right] + \gamma T + \frac{\lambda}{2} \sum_{j=1}^T w_j^2$$

$$\operatorname{argmin}_{w_1, \dots, w_T} \sum_{j=1}^T \left[ \left( \sum_{n \in I_j} G_n \right) w_j + \frac{1}{2} \left( \lambda + \sum_{n \in I_j} H_n \right) w_j^2 \right] + \gamma T$$

# Optimal Tree Leaves

- ▶ Given the objective:

$$\operatorname{argmin}_{w_1, \dots, w_T} \sum_{j=1}^T \left[ \left( \sum_{n \in I_j} G_n \right) w_j + \frac{1}{2} \left( \lambda + \sum_{n \in I_j} H_n \right) w_j^2 \right] + \gamma T$$

- ▶ Knowing that:

$$\frac{-A}{B} = \operatorname{argmin}_x Ax + \frac{1}{2} Bx^2$$

- ▶ The optimal leaf weights  $w$  are:

$$w_j = -\frac{\sum_{n \in I_j} G_n}{\lambda + \sum_{n \in I_j} H_n}, \quad j = 1, \dots, T$$



# Ultimate Objective Function

- ▶ Given the objective:

$$\operatorname{argmin}_{w_1, \dots, w_T} \sum_{j=1}^T \left[ \left( \sum_{n \in I_j} G_n \right) w_j + \frac{1}{2} \left( \lambda + \sum_{n \in I_j} H_n \right) w_j^2 \right] + \gamma T$$

- ▶ Knowing that:

$$\frac{-A^2}{2B} = \min_x Ax + \frac{1}{2} Bx^2$$

- ▶ The final objective function is:

$$\mathcal{O}(G, H) := -\frac{1}{2} \sum_{j=1}^T \frac{\left( \sum_{n \in I_j} G_n \right)^2}{\left( \lambda + \sum_{n \in I_j} H_n \right)} + \gamma T$$

# How to grow trees?

- ▶ The objective per leaf  $j$  is:

$$\mathcal{O}_j := -\frac{1}{2} \frac{\left( \sum_{n \in I_j} G_n \right)^2}{\left( \lambda + \sum_{n \in I_j} H_n \right)} + \gamma$$

- ▶ When splitting leaf  $j$  after a decision split we yield two sub-leaves  $j^{(\text{Left})}$  and  $j^{(\text{Right})}$
- ▶ The gain in minimizing the global objective after splitting leaf  $j$ :

$$\text{Gain}_j := \mathcal{O}_j - \left( \mathcal{O}_{j^{(\text{Left})}} + \mathcal{O}_{j^{(\text{Right})}} \right)$$

## Gain of splitting a leaf

▶ Given:  $\mathcal{O}_j := -\frac{1}{2} \frac{\left(\sum_{n \in I_j} G_n\right)^2}{\left(\lambda + \sum_{n \in I_j} H_n\right)} + \gamma$ ,  $\text{Gain}_j := \mathcal{O}_j - \left(\mathcal{O}_{j(\text{Left})} + \mathcal{O}_{j(\text{Right})}\right)$

▶ Derive:

$$\text{Gain}_j := \frac{1}{2} \left[ \frac{\left(\sum_{n \in I_j^{(\text{Left})}} G_n\right)^2}{\left(\lambda + \sum_{n \in I_j^{(\text{Left})}} H_n\right)} + \frac{\left(\sum_{n \in I_j^{(\text{Right})}} G_n\right)^2}{\left(\lambda + \sum_{n \in I_j^{(\text{Right})}} H_n\right)} - \frac{\left(\sum_{n \in I_j} G_n\right)^2}{\left(\lambda + \sum_{n \in I_j} H_n\right)} \right] - \gamma$$

Objective of left child
Objective of right child
Objective of parent

$\gamma$   
 Regularize  
 additional  
 leaf

# Split rule search

- ▶ For each node, exhaustively visit all splitting rules:
  - ▶ For each feature  $m = 1, \dots, M$  of the data  $X \in \mathbb{R}^{N \times M}$ 
    - ▶ Sort the instances  $n = 1, \dots, N$  of the  $m$ -th feature  $x_{:,m} \in \mathbb{N}$
    - ▶ Denote the unique sort values  $\mathcal{V}_m \in \mathbb{R}^{N'}$ , where  $N' \leq N$
    - ▶ Generate all split rules:

$$\left[ x_{:,m}; \frac{\mathcal{V}_{m,n'} + \mathcal{V}_{m,n'+1}}{2} \right], \text{ for } n' = 1, \dots, N' - 1$$

- ▶ Select the split rule that maximizes the gain

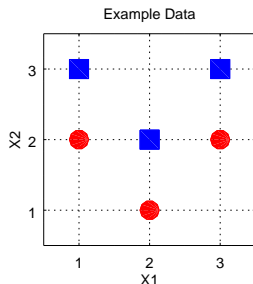
$$\underset{\substack{x_{:,m}; \frac{\mathcal{V}_{m,n'} + \mathcal{V}_{m,n'+1}}{2} \\ \forall m \in \{1, \dots, M\} \\ \forall n' \in \{1, \dots, |\mathcal{V}_{m,:}| - 1\}}}{\text{argmin}} \quad \mathcal{O}_j - (\mathcal{O}_{j(\text{Left})} + \mathcal{O}_{j(\text{Right})})$$

where

$$I_j^{(\text{Left})} = \left\{ n \mid x_{n,m} < \frac{\mathcal{V}_{m,n'} + \mathcal{V}_{m,n'+1}}{2} \right\}$$

$$I_j^{(\text{Right})} = \left\{ n \mid x_{n,m} > \frac{\mathcal{V}_{m,n'} + \mathcal{V}_{m,n'+1}}{2} \right\}$$

# Exercise



$n$	$x_1$	$x_2$	$y$
1	1	2	0
2	2	1	0
3	3	2	0
4	1	3	1
5	2	2	1
6	3	3	1

- ▶ Learn an ensemble of 2 trees to estimate:
  - ▶ Limit maximum depth of trees to two.
  - ▶ Use logistic loss
  - ▶ Set  $\gamma = 1$ ,  $\lambda = 1$ .

## Exercise - Step 1: Gradients and Hessians

- ▶ Before building each tree compute the gradients and Hessians:

$$\mathcal{L}_n = -y_n \log(\sigma(\hat{y}_n)) - (1 - y_n) \log(1 - \sigma(\hat{y}_n))$$

$$G_n = \frac{\partial \mathcal{L}_n}{\partial \hat{y}_n} = \sigma(\hat{y}_n) - y_n$$

$$H_n = \frac{\partial^2 \mathcal{L}_n}{\partial (\hat{y}_n)^2} = \frac{\partial G_n}{\partial \hat{y}_n} = \sigma(\hat{y}_n)(1 - \sigma(\hat{y}_n))$$

- ▶ Remember the prediction model of a boosted ensemble:

$$\hat{y}_n^{(k)} = \hat{y}_n^{(k-1)} + f^{(k)}(x_n)$$

- ▶ For the first tree, assume  $\hat{y}_n^{(0)} = 0$ , yielding

$$\hat{y}_n^{(1)} = f^{(1)}(x_n)$$

## Exercise - Step 1: Gradients and Hessians (II)

► Knowing

$$\sigma(\hat{y}_n) = (1 + e^{-\hat{y}_n})^{-1}, \quad G_n = \sigma(\hat{y}_n) - y_n, \quad H_n = \sigma(\hat{y}_n)(1 - \sigma(\hat{y}_n))$$

► Compute once before growing each tree:

$n$	$X_1$	$X_2$	$y$	$\hat{y}^{(0)}$	$\sigma(\hat{y}^{(0)})$	$G$	$H$
1	1	2	0	0	0.5	0.5	0.25
2	2	1	0	0	0.5	0.5	0.25
3	3	2	0	0	0.5	0.5	0.25
4	1	3	1	0	0.5	-0.5	0.25
5	2	2	1	0	0.5	-0.5	0.25
6	3	3	1	0	0.5	-0.5	0.25

## Exercise - Step 2: Enumerate split rules

- ▶ For first feature  $m = 1$ 
  - ▶ Unique sorted values  $\mathcal{V}_1 = \{1, 2, 3\}$
  - ▶ Rules  $[x_{:,1}; 1.5]$  and  $[x_{:,1}; 2.5]$
- ▶ For second feature  $m = 2$ :
  - ▶ Unique sorted values  $\mathcal{V}_2 = \{1, 2, 3\}$
  - ▶ Rules  $[x_{:,2}; 1.5]$  and  $[x_{:,2}; 2.5]$
- ▶ In the beginning there is only the root  $j = 1$ , where:
  - ▶ All instances belong to the root:  $I_1 = \{1, 2, 3, 4, 5, 6\}$
- ▶ Which rule  $[x_{:,1}; 1.5]$ ,  $[x_{:,1}; 2.5]$ ,  $[x_{:,2}; 1.5]$ ,  $[x_{:,2}; 2.5]$  maximizes the gain of splitting the root?



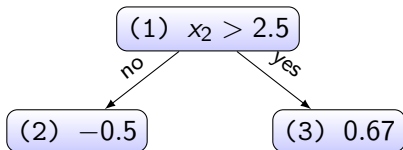
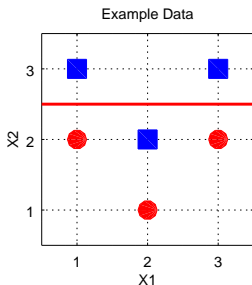
## Exercise - Step 3: Best split rule = Maximal Gain

$n$	$X_1$	$X_2$	$y$	$\hat{y}^{(0)}$	$\sigma(\hat{y}^{(0)})$	$G$	$H$
1	1	2	0	0	0.5	0.5	0.25
2	2	1	0	0	0.5	0.5	0.25
3	3	2	0	0	0.5	0.5	0.25
4	1	3	1	0	0.5	-0.5	0.25
5	2	2	1	0	0.5	-0.5	0.25
6	3	3	1	0	0.5	-0.5	0.25

- ▶ Rule  $[x_{:,1}; 1.5]$ :
  - ▶  $I_1^{(\text{Left})} = \{1, 4\}$  and  $I_1^{(\text{Right})} = \{2, 3, 5, 6\}$ , thus  $Gain_1 = -1$
- ▶ Rule  $[x_{:,1}; 2.5]$ :
  - ▶  $I_1^{(\text{Left})} = \{1, 2, 4, 5\}$  and  $I_1^{(\text{Right})} = \{3, 6\}$ , thus  $Gain_1 = -1$
- ▶ Rule  $[x_{:,2}; 1.5]$ :
  - ▶  $I_1^{(\text{Left})} = \{2\}$  and  $I_1^{(\text{Right})} = \{1, 3, 4, 5, 6\}$ , thus  $Gain_1 = -0.84$
- ▶ Rule  $[x_{:,2}; 2.5]$ :
  - ▶  $I_1^{(\text{Left})} = \{1, 2, 3, 5\}$  and  $I_1^{(\text{Right})} = \{4, 6\}$ , thus  $Gain_1 = -0.41$  (best)

# Our first tree with depth 1!

- ▶ The best rule we found  $[x_{:,2}; 2.5]$ :
  - ▶ Splits node ( $j = 1$ ) into  $I_1^{(\text{Left})} = \{1, 2, 3, 5\}$  and  $I_1^{(\text{Right})} = \{4, 6\}$
  - ▶ Left child ( $j = 2$ ) with weight  $w_2 = -\frac{G_1+G_2+G_3+G_5}{H_1+H_2+H_3+H_5+\lambda} = -0.5$
  - ▶ Right child ( $j = 3$ ) with weight  $w_3 = -\frac{G_4+G_6}{H_4+H_6+\lambda} = 0.66$



- ▶ Interpretation of the outcome  $y_n^{(1)} = f^{(1)}(x_n) = w_{q(x_n)}$ :
  - ▶  $\sigma(\hat{y}_n^{(1)}) = \sigma(-0.5) = 0.37, \forall n \in \{1, 2, 3, 5\}, q(x_n) = 2$
  - ▶  $\sigma(\hat{y}_n^{(1)}) = \sigma(0.67) = 0.66, \forall n \in \{4, 6\}, q(x_n) = 3$

# Grow the tree further

- ▶ Follow the same procedure to compute the best rules for further splitting node ( $j = 2$ ) and ( $j = 3$ )
- ▶ Proceed until the maximum allowed depth is reached.
- ▶ For subsequent trees in the ensemble follow the same procedure, but note that:
  - ▶ For the first tree  $\hat{y}_n^{(0)} = 0$
  - ▶ For the second tree  $\hat{y}_n^{(1)} = f^{(1)}(x_n)$
  - ▶ For the third tree  $\hat{y}_n^{(2)} = f^{(1)}(x_n) + f^{(2)}(x_n)$ , etc ...
- ▶ Finish the exercise at home!