

# Time-series Forecasting - Exponential Smoothing

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# Motivation

Extreme *recentivism*: The **Naive** forecast considers only the last value:

$$\hat{y}_{T+h|T} = y_T$$

Extreme *nostalgia*: The **Average** method equally considers all previous values:

$$\hat{y}_{T+h|T} = \frac{1}{T} \sum_{t=1}^T y_t$$

A middle way is needed: How to capture the influence of previous values while prioritizing recent measurements?

# Exponential Smoothing

An exponentially-weighted average for  $0 < \alpha \leq 1$ :

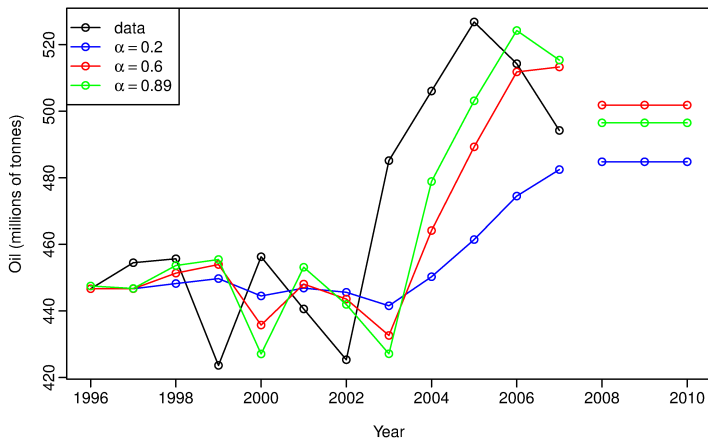
$$\hat{y}_{T+1|T} = \alpha y_T + \alpha(1 - \alpha)y_{T-1} + \alpha(1 - \alpha)^2 y_{T-2} + \dots$$

The weights decrease exponentially for past measurements:

Observation	$\alpha = 0.2$	$\alpha = 0.4$	$\alpha = 0.6$	$\alpha = 0.8$
$y_T$	0.2	0.4	0.6	0.8
$y_{T-1}$	0.16	0.24	0.24	0.16
$y_{T-2}$	0.128	0.144	0.096	0.032
$y_{T-3}$	0.1024	0.0864	0.0384	0.0064
$y_{T-4}$	0.08192	0.05184	0.01536	0.00128

The recentism is controlled by  $\alpha$ , where  $\sum_{t=1}^T \alpha(1 - \alpha)^{T-t} \approx 1, \forall \alpha \in (0, 1]$

# Example - Oil Production



Oil production in Saudi Arabia (1996–2007). Hyndman et al. 2014

# Weighted Average Form

Forecast of time  $T + 1$  is a weighted average of observation  $y_T$  and forecast  $\hat{y}_{T|T-1}$ :

$$\begin{aligned}\hat{y}_{T+1|T} &= \alpha y_T + (1 - \alpha)\hat{y}_{T|T-1} \\ \hat{y}_{T|T-1} &= \alpha y_{T-1} + (1 - \alpha)\hat{y}_{T-1|T-2} \\ &\dots \\ \hat{y}_{3|2} &= \alpha y_2 + (1 - \alpha)\hat{y}_{2|1} \\ \hat{y}_{2|1} &= \alpha y_1 + (1 - \alpha)l_0\end{aligned}$$

# Component and Error Correction Forms

The only component influencing forecast  $\hat{y}_{t|t-1}$  is the level  $l_t$ :

$$\text{Forecast Equation} \quad \hat{y}_{t+1|t} = l_t$$

$$\text{Smoothing Equation} \quad l_t = \alpha y_t + (1 - \alpha)l_{t-1}$$

Similarly we can derive the error ( $e_t$ ) correction form:

$$\begin{aligned} l_t &= l_{t-1} + \alpha(y_t - l_{t-1}) \\ &= l_{t-1} + \alpha(y_t - \hat{y}_{t|t-1}) \\ &= l_{t-1} + \alpha e_t \end{aligned}$$

# Holt's Linear Trend Method

Tackle trend in  $\hat{y}_{t+1|h}$  by decomposing out a slope/trend term  $b_t$ :

Forecast Equation  $\hat{y}_{t+h|t} = \ell_t + hb_t$

Level Equation  $\ell_t = \alpha y_t + (1 - \alpha)(\ell_{t-1} + b_{t-1})$

Trend Equation  $b_t = \beta^*(\ell_t - \ell_{t-1}) + (1 - \beta^*)b_{t-1}$

- ▶  $0 < \alpha \leq 1, 0 < \beta^* \leq 1$
- ▶  $\ell_t$  as a waited average of current observation  $y_t$  and estimation  $\hat{y}_{t|t-1} = \ell_{t-1} + b_{t-1}$
- ▶  $b_t$  as a weighted average of prediction differences  $\ell_t - \ell_{t-1}$  and previous trend  $b_{t-1}$

# Holt's Linear Trend Method - Error Correction

- ▶ Rewrite by taking  $l_t$  and  $b_t$  on the left side:

$$l_t = l_{t-1} + b_{t-1} + \alpha e_t$$

$$b_t = b_{t-1} + \alpha\beta^* e_t$$

- ▶ Where the isolated error is:

$$e_t = y_t - (l_{t-1} + b_{t-1}) = y_t - \hat{y}_{t|t-1}$$

- ▶ Set  $l_0 = y_1$  and  $b_0 = y_2 - y_1$  when making predictions



## Exercise

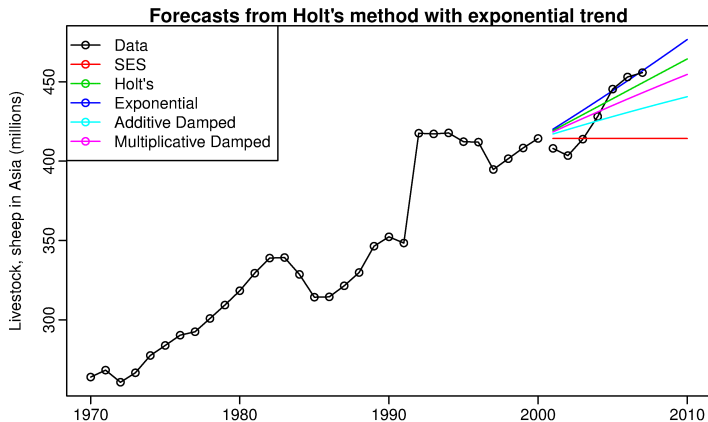
Given a series  $y_1 = 2, y_2 = -3, y_3 = 3, y_4 = -2$ , predict  $\hat{y}_{5|4} = ?$  using

- ▶ Holt's Linear Trend with  $\alpha = 0.5, \beta^* = 0.5$

In fact, it was later observed that  $y_5 = 2$ .

- ▶  $l_0 = 2, b_0 = -5$
- ▶  $l_1 = 0.5(2 + 2 - 5) = -0.5, b_1 = 0.5(-0.5 - 2 - 5) = -3.75$
- ▶  $l_2 = 0.5(-3 - 0.5 - 3.75) = -3.625, b_2 = 0.5(-3.625 + 0.5 - 3.75) = -3.4375$
- ▶  $l_3 = 0.5(3 - 3.625 - 3.4375) = -2.03125,$   
 $b_3 = 0.5(-2.03125 + 3.625 - 3.4375) = -0.92188$
- ▶  $l_4 = 0.5(-2 - 2.03125 - 0.92188) = -2.47656,$   
 $b_4 = 0.5(-2.47656 + 2.03125 - 0.92188) = -0.68359$
- ▶  $\hat{y}_{5|4} = -2.47656 - 0.68359 = -3.16016$

# Example - Livestock, sheep in Asia



Comparison of different forecasting approaches using non-seasonal exponential smoothing. Hyndman et al. 2014

# Exponential Trend Method

Replace an additive model (constant slope) with a multiplicative one (constant growth):

Forecast Equation  $\hat{y}_{t+h|t} = l_t b_t^h$

Level Equation  $l_t = \alpha y_t + (1 - \alpha)(l_{t-1} b_{t-1})$

Trend Equation  $b_t = \beta^* \frac{l_t}{l_{t-1}} + (1 - \beta^*) b_{t-1}$

- ▶  $b_t$  represents a multiplicative growth rate in relative terms  $\frac{l_t}{l_{t-1}}$
- ▶ Forecasts project a constant growth rate rather than a constant slope (as in the additive model)

# Exponential Trend Method - Error Correction

- ▶ Rewrite by taking  $l_t$  and  $b_t$  on the left side:

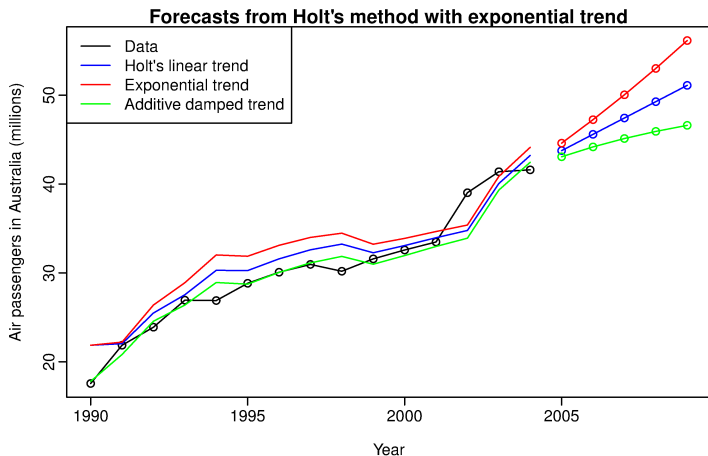
$$\begin{aligned}l_t &= l_{t-1}b_{t-1} + \alpha e_t \\b_t &= b_{t-1} + \alpha\beta^* \frac{e_t}{l_{t-1}}\end{aligned}$$

- ▶ Where the isolated error is:

$$e_t = y_t - (l_{t-1} b_{t-1}) = y_t - \hat{y}_{t|t-1}$$

- ▶ Set  $l_0 = y_1$  and  $b_0 = y_2/y_1$  when making predictions

# Example - Air Passengers (Hyndman et al. 2014)



Notice the over-forecast of the linear and exponential trend methods. The damped trend approach addresses the issue ...

# Damped Additive Trend Model

Include a damping/prohibitory parameter  $0 < \phi < 1$ :

$$\text{Forecast Equation} \quad \hat{y}_{t+h|t} = l_t + (\phi + \phi^2 + \dots + \phi^h)b_t$$

$$\text{Level Equation} \quad l_t = \alpha y_t + (1 - \alpha)(l_{t-1} + \phi b_{t-1})$$

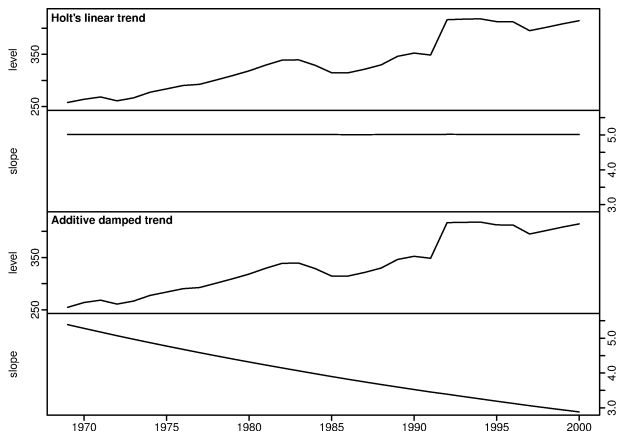
$$\text{Trend Equation} \quad b_t = \beta^*(l_t - l_{t-1}) + (1 - \beta^*)\phi b_{t-1}$$

- ▶  $\phi = 1$  leads Holt's additive linear trend model
- ▶ Error correction form:

$$l_t = l_{t-1} + \phi b_{t-1} + \alpha e_t$$

$$b_t = \phi b_{t-1} + \alpha \beta^* e_t$$

# Example - Livestock, sheep in Asia



Level  $l_t$  and trend  $b_t$  computed from a Livestock, sheep time series. Hyndman et al. 2014

## Damped Multiplicative Trend Model

Include a damping/prohibitory parameter  $0 < \phi < 1$  to the exponential trend:

$$\text{Forecast Equation} \quad \hat{y}_{t+h|t} = l_t b_t^{(\phi + \phi^2 + \dots + \phi^h)}$$

$$\text{Level Equation} \quad l_t = \alpha y_t + (1 - \alpha)(l_{t-1} b_{t-1}^\phi)$$

$$\text{Trend Equation} \quad b_t = \beta^* \frac{l_t}{l_{t-1}} + (1 - \beta^*) b_{t-1}^\phi$$

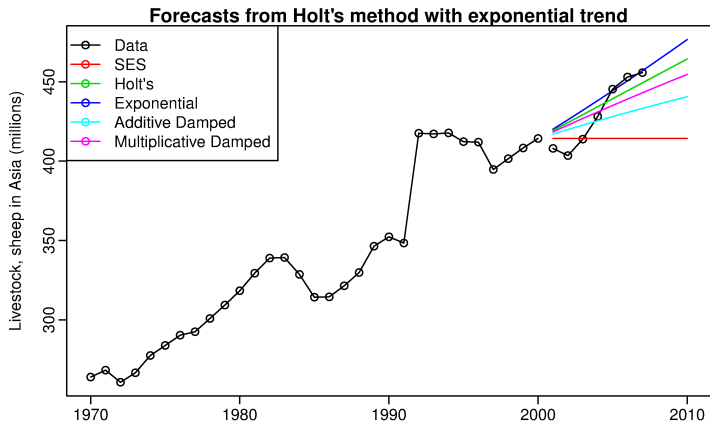
- ▶  $\phi = 1$  leads to exponential trend model
- ▶ Error correction form:

$$l_t = l_{t-1} b_{t-1}^\phi + \alpha e_t$$

$$b_t = b_{t-1}^\phi + \alpha \beta^* \frac{e_t}{l_{t-1}}$$



# Example - Livestock, sheep in Asia



Hyndman et al. 2014

## Exercise (2)

Given a series  $y_1 = 2, y_2 = -3, y_3 = 3, y_4 = -2$ , predict  $\hat{y}_{5|4} = ?$  using:

- ▶ Damped Additive Trend Model with  $\alpha = 0.5, \beta^* = 0.5, \phi = 0.5$

In fact, it was later observed that  $y_5 = 2$ .

Solve it at home!

# Setting parameters

- ▶ How to set  $\alpha, \beta^*, b_0, l_0, \phi$  ?
- ▶ Search for combinations that minimize the Sum of Squared Errors:

$$SSE = \sum_{t=1}^T e_t^2 = \sum_{t=1}^T (y_t - \hat{y}_{t|t-1})^2$$

# Holt-Winters Additive **Seasonal** Method

Forecast	$\hat{y}_{t+h t} = l_t + hb_t + s_{t-m+h_m^+}$
Level	$l_t = \alpha(y_t - s_{t-m}) + (1 - \alpha)(l_{t-1} + b_{t-1})$
Trend	$b_t = \beta^*(l_t - l_{t-1}) + (1 - \beta^*)b_{t-1}$
Seasonality	$s_t = \gamma(y_t - l_{t-1} - b_{t-1}) + (1 - \gamma)s_{t-m}$

- ▶  $h_m^+ = \lfloor (h - 1) \bmod m \rfloor + 1$  ensures estimates come from final year
- ▶  $l_t$  is the weighted average between seasonally-adjusted observation and non-seasonal forecast
- ▶  $b_t$  same as Holt's linear model
- ▶  $s_t$  is the weighted average between current seasonal value and the last season's ( $m$  periods ago)

## Holt-Winters Additive **Seasonal** Method (2)

With error correction forms:

$$l_t = l_{t-1} + b_{t-1} + \alpha e_t$$

$$b_t = b_{t-1} + \alpha\beta^* e_t$$

$$s_t = s_{t-m} + \gamma e_t$$

and residual errors:

$$e_t = y_t - (l_{t-1} + b_t + s_{t-m}) = y_t - \hat{y}_{t|t-1}$$

# Holt-Winters Multiplicative **Seasonal** Method

Forecast	$\hat{y}_{t+h t} = (l_t + hb_t)s_{t-m+h_m^+}$
Level	$l_t = \alpha \frac{y_t}{s_{t-m}} + (1 - \alpha)(l_{t-1} + b_{t-1})$
Trend	$b_t = \beta^*(l_t - l_{t-1}) + (1 - \beta^*)b_{t-1}$
Seasonality	$s_t = \gamma \frac{y_t}{l_{t-1} + b_{t-1}} + (1 - \gamma)s_{t-m}$

## Holt-Winters Multiplicative **Seasonal** Method (2)

With an error correction form:

$$l_t = l_{t-1} + b_{t-1} + \alpha \frac{e_t}{s_{t-m}}$$

$$b_t = b_{t-1} + \alpha\beta^* \frac{e_t}{s_{t-m}}$$

$$s_t = s_{t-m} + \gamma \frac{e_t}{l_{t-1} + b_{t-1}}$$

With residual errors:

$$e_t = y_t - (l_{t-1} + b_t)s_{t-m}$$

## Exercise (3)

Given a series  $y_1 = 2, y_2 = -3, y_3 = 3, y_4 = -2$ , predict  $\hat{y}_{5|4} = ?$  using:

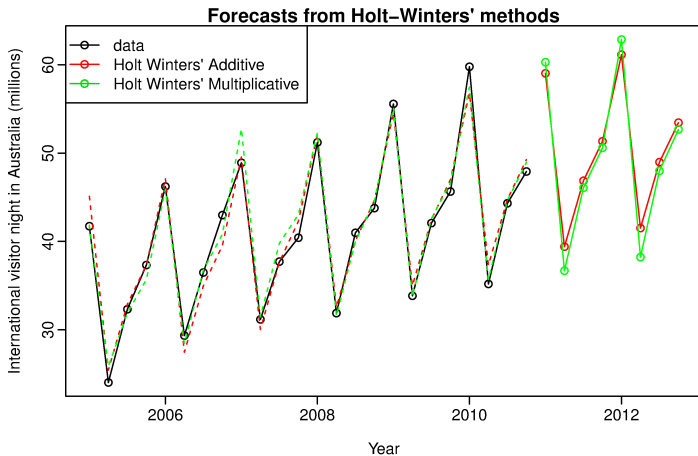
- ▶ Holt-Winters Additive Seasonal Model with  $\alpha = 0.5, \beta^* = 0.5, \gamma = 0.5, m = 2$

In fact, it was later observed that  $y_5 = 2$ .

$t$	$\ell$	$b$	$s$	$\hat{y}$
-1			2	
0	2	-5	2	
1	-1.5	-4.25	3.5	-1
2	-5.375	-4.0625	2.375	-3.75
3	-4.96875	-1.828125	7.96875	-5.9375
4	-5.5859375	-1.22265625	3.5859375	-4.421875
5				1.16015625

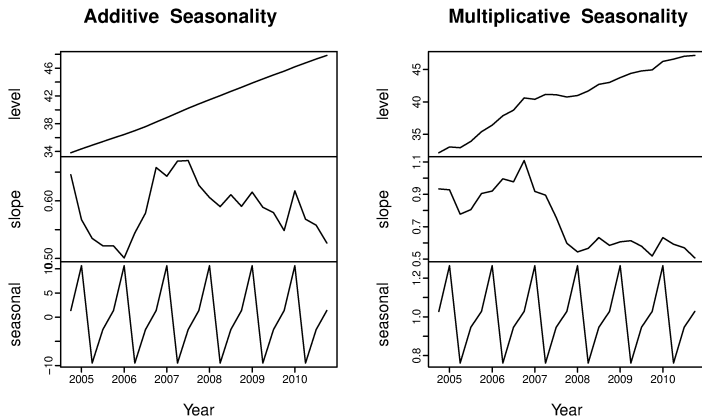


# Example - International Visitors in Australia



Hyndman et al. 2014

# Example - International Visitors in Australia (2)



Decomposing  $\ell_t$ ,  $b_t$  and  $s_t$ . Hyndman et al. 2014