

Big Data Analytics

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C. Distributed Computing Environments / 3. Computational Graphs (TensorFlow)

Syllabus

- | | | | |
|---------------------------------------------------|-------|------|---------------------------------------------|
| Tue. | 9.4. | (1) | 0. Introduction |
| A. Parallel Computing | | | |
| Tue. | 16.4. | (2) | A.1 Threads |
| Tue. | 23.4. | (3) | A.2 Message Passing Interface (MPI) |
| Tue. | 30.4. | (4) | A.3 Graphical Processing Units (GPUs) |
| B. Distributed Storage | | | |
| Tue. | 7.5. | (5) | B.1 Distributed File Systems |
| Tue. | 14.5. | (6) | B.2 Partitioning of Relational Databases |
| Tue. | 21.5. | (7) | B.3 NoSQL Databases |
| C. Distributed Computing Environments | | | |
| Tue. | 28.5. | (8) | C.1 Map-Reduce |
| Tue. | 4.6. | (9) | C.2 Resilient Distributed Datasets (Spark) |
| Tue. | 11.6. | — | — <i>Pentecoste Break</i> — |
| Tue. | 18.6. | (10) | C.3 Computational Graphs (TensorFlow) |
| D. Distributed Machine Learning Algorithms | | | |
| Tue. | 25.6. | (11) | D.1 Distributed Stochastic Gradient Descent |
| Tue. | 2.7. | (12) | D.2 Distributed Matrix Factorization |
| Tue. | 9.7. | (13) | Questions and Answers |

Outline

1. The Computational Graph
2. Variables
3. Example: Linear Regression
4. Automatic Gradients
5. Large Data I: Feeding
6. Large Data II: Reader Nodes
7. Debugging

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TensorFlow

- ▶ Computational framework
- ▶ multi-device, distributed
- ▶ Core in C/C++, standard interface in Python
 - ▶ several further language bindings, e.g., R, Java
- ▶ open source
 - ▶ developed by Google
 - ▶ initially released Nov. 2015
 - ▶ 2nd generation framework
 - ▶ 1st generation framework was called DistBelief
- ▶ alternative: pytorch
 - ▶ developed by facebook, since 2016, open source

Tensors

- ▶ tensor = multidimensional array
 - ▶ rank = number of dimensions
 - ▶ shape = vector of sizes,
one size for each dimension.

rank	common name	shape
0	scalar	()
1	vector	(size)
2	matrix	(numrows, numcols)
≥3	tensor of higher order	(numdim ₁ , numdim ₂ , ..., numdim _r)

- ▶ examples:

$$A = \begin{pmatrix} 1.0 & -3.0 & 2.3 & 1.7 \\ 5.6 & 0.0 & -1.3 & 3.4 \\ -7.7 & -3.3 & -2.1 & 5.2 \end{pmatrix}, \quad \text{shape}(A) = (3, 4), \quad \text{rank}(A) = 2$$

Computational Graphs

- ▶ TensorFlow organizes a computation as a directed graph.
- ▶ Nodes represent a tensor.
 - ▶ or a list of tensors.
- ▶ Tensors can be:
 - ▶ stored tensors
 - ▶ immutable, value provided at creation time: `tf.constant`
 - ▶ immutable, value provided when running the graph: `tf.placeholder`
 - ▶ mutable: `tf.Variable`
 - ▶ computed tensors (**operations**):
 - ▶ having one or more input tensors
 - ▶ having one or more output tensors
 - output index: `port`
- ▶ Edges represent dependencies.
 - ▶ Edge $x \rightarrow y$ if y is computed and x one of its inputs.

Sessions

- ▶ A session represents the state of an ongoing computation on a computational graph.
- ▶ create with default constructor `tf.Session`.
- ▶ compute the value of a tensor node with `run`.

Two Phases

1. Construct the Computational Graph
 - ▶ create tensor nodes
 - ▶ possibly referencing other tensor nodes as inputs
2. Compute values of a node of the Computation Graph (**running**)
 - ▶ usually specify target tensor(s)
 - ▶ computes all intermediate tensors required for this tensor
 - ▶ yield the value of the target tensor(s)

Hello TensorFlow: Add two Constants

```
1 import tensorflow as tf
2
3 a = tf.constant(3.0)
4 b = tf.constant(4.0)
5 x = tf.add(a, b)
6
7 print(a)
8 print(b)
9 print(x)
10
11 sess = tf.Session()
12 x_val = sess.run(x)
13 print(x_val)
```

Output:

```
1 Tensor("Const:0", shape=(), dtype=float32)
2 Tensor("Const_1:0", shape=(), dtype=float32)
3 Tensor("Add:0", shape=(), dtype=float32)
4 7
```

Hello TensorFlow: Add two Constants

```
1 import tensorflow as tf
2
3 a = tf.constant([3.0, -2.7, 1.2])
4 b = tf.constant([4.0, 5.1, -1.7])
5 x = tf.add(a, b)
6
7 print(a)
8 print(b)
9 print(x)
10
11 sess = tf.Session()
12 x_val = sess.run(x)
13 print(x_val)
```

Output:

```
1 Tensor("Const_2:0", shape=(3,), dtype=float32)
2 Tensor("Const_3:0", shape=(3,), dtype=float32)
3 Tensor("Add_1:0", shape=(3,), dtype=float32)
4 [ 7.0  2.4  -0.5 ]
```

Tensor Types

- Different element types are represented by `tf.DType`:

dtype	description
<code>tf.float16</code>	16-bit half-precision floating-point
<code>tf.float32</code>	32-bit single-precision floating-point
<code>tf.float64</code>	64-bit double-precision floating-point
<code>tf.bfloat16</code>	16-bit truncated floating-point
<code>tf.complex64</code>	64-bit single-precision complex
<code>tf.complex128</code>	128-bit double-precision complex
<code>tf.int8</code>	8-bit signed integer
<code>tf.uint8</code>	8-bit unsigned integer
<code>tf.uint16</code>	16-bit unsigned integer
<code>tf.int16</code>	16-bit signed integer
<code>tf.int32</code>	32-bit signed integer
<code>tf.int64</code>	64-bit signed integer
<code>tf.bool</code>	Boolean
<code>tf.string</code>	String
<code>tf.qint8</code>	Quantized 8-bit signed integer
<code>tf.quint8</code>	Quantized 8-bit unsigned integer
<code>tf.qint16</code>	Quantized 16-bit signed integer
<code>tf.quint16</code>	Quantized 16-bit unsigned integer
<code>tf.qint32</code>	Quantized 32-bit signed integer
<code>tf.resource</code>	Handle to a mutable resource

- if omitted, inferred from values:

```

1 a = tf.constant(4.0)
2 b = tf.constant(4)
3 print(a)
4 print(b)
  
```

Output:

```

1 Tensor("Const:0", shape=(), dtype=float32)
2 Tensor("Const_1:0", shape=(), dtype=int32) ⏪ | ⏴ ⏵ ⏷ ⏸ ⏹ ⏺
  
```

Operations: Overloaded Operators

```
1 import tensorflow as tf
2
3 a = tf.constant(3.0)
4 b = tf.constant(4.0)
5 x = a + b
6
7 print(x)
8
9 sess = tf.Session()
10 x_val = sess.run(x)
11 print(x_val)
```

Output:

```
1 Tensor("add_1:0", shape=(), dtype=float32)
2 7
```

operator	operation node
+	tf.add
-	tf.subtract
*	tf.multiply
/	tf.divide

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```
v = tf.Variable(initial_value = None, ..., name = None, ...,
                 dtype = None)
```

- ▶ has immutable element type
- ▶ has mutable shape (**set_shape**).
- ▶ has mutable element values.
 - ▶ set by **tf.assign**, **tf.assign_add** (operations)
 - ▶ separate values in each session
- ▶ has to be initialized before first use:
 - ▶ run **v.initializer** operation or
 - ▶ run initializers of all variables:

```
1     init = tf.global_variables_initializer()
2     sess.run(init)
```

Variables

```
1 import tensorflow as tf
2
3 x = tf.Variable(3.0)
4 sess = tf.Session()
5 sess.run( x.initializer )
6 x_val = sess.run(x)
7 print(x_val)
8
9 x_plus_one = tf.assign_add(x, 1.0)
10
11 for t in range(5):
12     x_val = sess.run(x_plus_one)
13     print(t, x_val)
```

Output:

```
1 3.0
2
3 0 4.0
4 1 5.0
5 2 6.0
6 3 7.0
7 4 8.0
```

Initializing from Other Variables

```
1 import tensorflow as tf
2
3 x = tf.Variable(3.0)
4 y = tf.Variable( tf.multiply(tf.constant(2.0),
5                   x.initialized_value()) )
6 init = tf.global_variables_initializer()
7 sess = tf.Session()
8 sess.run(init)
9 y_val = sess.run(y)
10 print(y_val)
```

Output:

```
1 6.0
```

- ▶ **v.initialized_value** assures that a variable has been initialized before
 - ▶ do not use

```
1 y = tf.Variable( tf.multiply(tf.constant(2.0), x) )
```

as x may be selected to be initialized after y .

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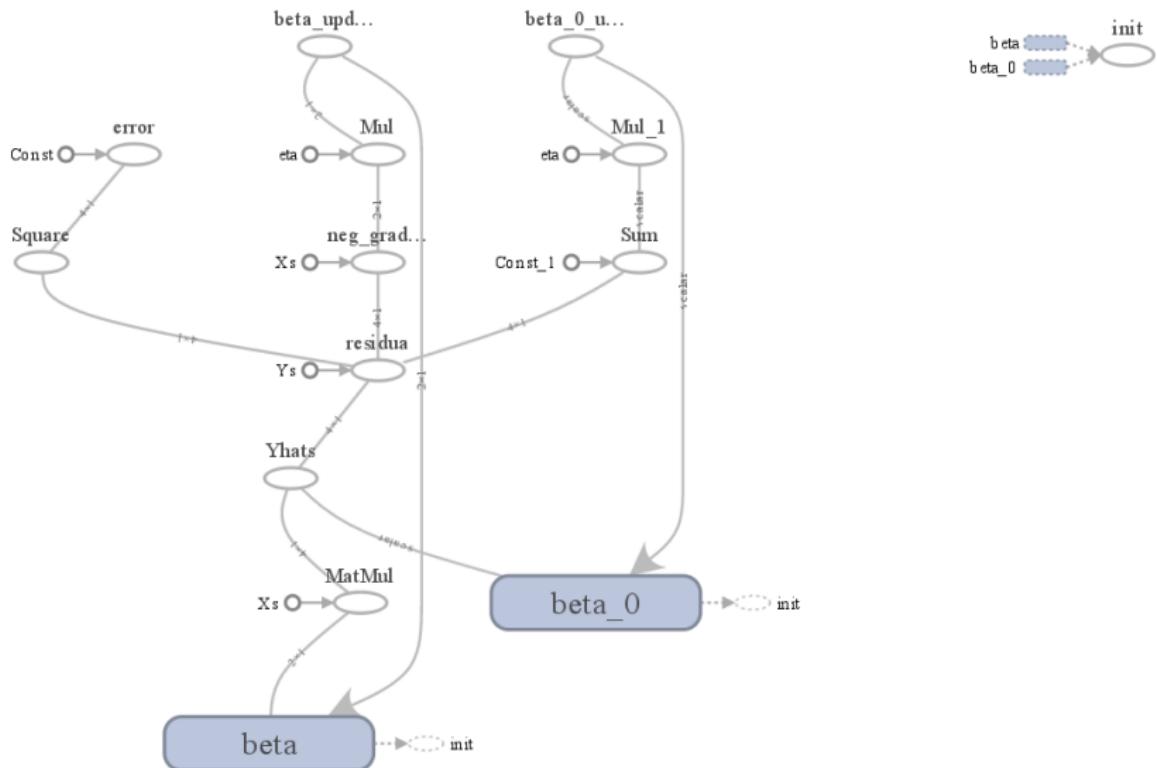
Example: Linear Regression

$\hat{y} := \beta_0 + X\beta$	prediction
$r := y - \hat{y}$	residuum
$\ell := \frac{1}{2} \sum_{n=1}^N r_n^2$	loss/error
$-\frac{\partial \ell}{\partial \beta} := X^T r$	negative gradient w.r.t. β
$-\frac{\partial \ell}{\partial \beta_0} := \sum_{n=1}^N r_n$	negative gradient w.r.t. β_0
$\beta^{\text{next}} := \beta - \eta \frac{\partial \ell}{\partial \beta}$	update of β
$\beta_0^{\text{next}} := \beta_0 - \eta \frac{\partial \ell}{\partial \beta_0}$	update of β_0

Example: Linear Regression

```
1 import tensorflow as tf
2
3 Xs_data = [[2,1], [1,2], [4,3], [3,4]]
4 Ys_data = [[+1], [+1], [-1], [-1]]
5 eta_data = 0.01
6
7 Xs = tf.constant(Xs_data, dtype=tf.float32)
8 Ys = tf.constant(Ys_data, dtype=tf.float32)
9 eta = tf.constant(eta_data)
10
11 beta = tf.Variable([[0], [0]], dtype=tf.float32)
12 beta_0 = tf.Variable(0, dtype=tf.float32)
13
14 Yhats = tf.add(beta_0, tf.matmul(Xs, beta))
15 residua = tf.subtract(Ys, Yhats)
16 error = tf.reduce_sum(tf.square(residua))
17
18 neg_grad_beta = tf.matmul(Xs, residua, adjoint_a=True)
19 beta_update = tf.assign_add(beta, tf.multiply(eta, neg_grad_beta))
20 beta_0_update = tf.assign_add(beta_0, tf.multiply(eta, tf.reduce_sum(residua)))
21
22 init = tf.global_variables_initializer()
23 sess = tf.Session()
24 sess.run( init )
25
26 for t in range(100):
27     error_val, beta_val, beta_0_val = sess.run([error,beta_update,beta_0_update])
28     print(t, error_val, beta_0_val, beta_val[0,0], beta_val[1,0])
```

Example: Linear Regression / Computational Graph



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```
tf.gradients(ys, xs, ...)
```

- ▶ create operations whose final node computes all the gradients

$$\left(\frac{\partial y_n}{\partial x_m} \right)_{n=1,\dots,N, m=1,\dots,M} \quad ys = (y_1, \dots, y_N), xs = (x_1, \dots, x_M)$$

Example: Linear Regression w. Automatic Gradients

```
1 import tensorflow as tf
2
3 Xs_data = [[2,1], [1,2], [4,3], [3,4]]
4 Ys_data = [[+1], [+1], [-1], [-1]]
5 eta_data = 0.01
6
7 Xs = tf.constant(Xs_data, dtype=tf.float32)
8 Ys = tf.constant(Ys_data, dtype=tf.float32)
9 eta = tf.constant(eta_data)
10
11 beta = tf.Variable([[0], [0]], dtype=tf.float32)
12 beta_0 = tf.Variable(0, dtype=tf.float32)
13
14 Yhats = tf.add(beta_0, tf.matmul(Xs, beta))
15 error = tf.reduce_sum(tf.square(tf.subtract(Ys, Yhats)))
16
17 grads = tf.gradients(error, [beta, beta_0])
18 beta_update = tf.assign_sub(beta, tf.multiply(eta, grads[0]))
19 beta_0_update = tf.assign_sub(beta_0, tf.multiply(eta, grads[1]))
20
21 init = tf.global_variables_initializer()
22 sess = tf.Session()
23 sess.run( init )
24
25 for t in range(100):
26     error_val, beta_val, beta_0_val = sess.run([error,beta_update,beta_0_update])
27     print(t, error_val, beta_0_val, beta_val[0,0], beta_val[1,0])
```

How do Automatic Gradients Work?

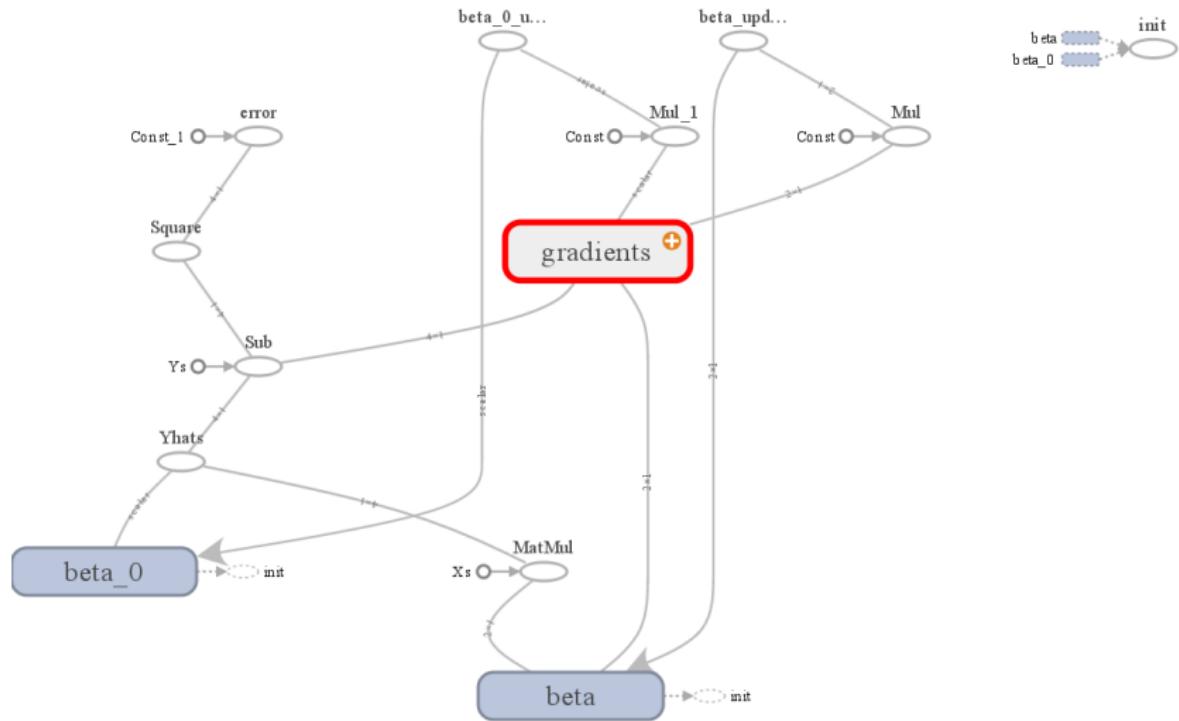
to compute $\frac{\partial y}{\partial x}$:

- ▶ find all paths $p^1, \dots, p^K \in G^*$ in the graph G from x to y
- ▶ use chain rule:

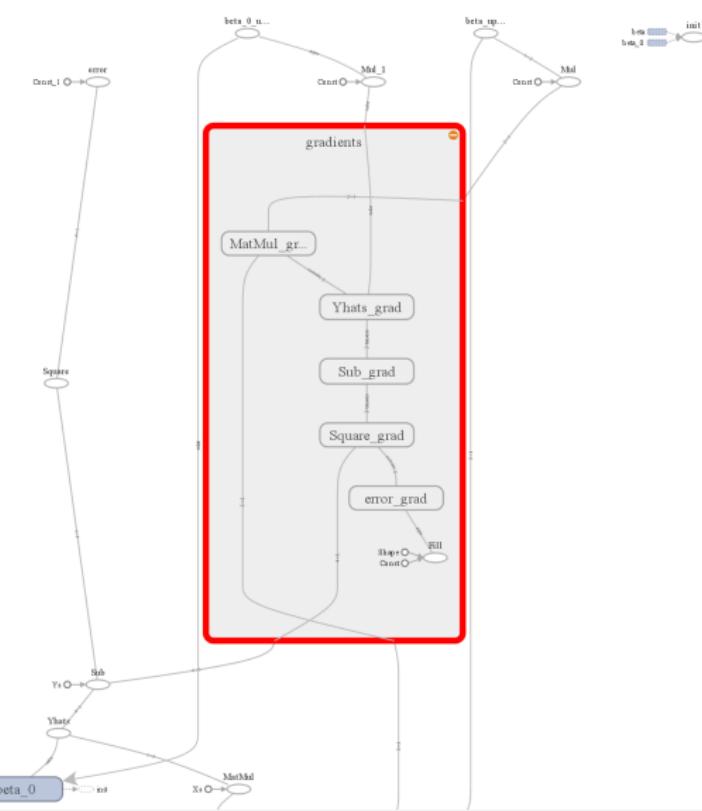
$$\frac{\partial y}{\partial x} = \sum_{k=1}^K \prod_{l=|p^k|}^2 \frac{\partial p_l^k}{\partial p_{l-1}^k}$$

- ▶ each operation $p_l^k =: o$ has to provide its gradient $\frac{\partial o}{\partial i}$ for each of its inputs i .
 - ▶ then $\frac{\partial p_l^k}{\partial p_{l-1}^k} = \frac{\partial o}{\partial i}$ for $i = p_{l-1}^k$.

Example: LinReg w. Auto Grads / Computational Graph



Example: LinReg w. Auto Grads / Computational Graph



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- ▶ representing large data as a whole as a constant is not so useful
 - ▶ e.g., if its size exceeds GPU memory, it cannot be deployed to GPU at all.
- ▶ better break data into smaller pieces
 - ▶ e.g., single instances or minibatches
 - ▶ batch GD → SGD
- ▶ build a graph for a single instance / minibatch
- ▶ create placeholder nodes for the instance / minibatch
- ▶ placeholders are filled with the `feed_dict` parameter of `run`.

Placeholder Nodes and Feeding

```
1 import tensorflow as tf
2
3 a = tf.placeholder(shape=(), dtype=tf.float32)
4 b = tf.placeholder(shape=(), dtype=tf.float32)
5 x = a + b
6
7 sess = tf.Session()
8 print( sess.run(x, {a: 3, b: 7}) )
9 print( sess.run(x, {a: -2, b: 4}) )
```

Output:

```
1 10.0
2 2.0
```

Example: Feeding SGD

```
1 import tensorflow as tf
2
3 Xs_data = [[2,1], [1,2], [4,3], [3,4]]
4 Ys_data = [+1, +1, -1, -1]
5 eta_data = 0.01
6
7 X = tf.placeholder(shape=(2), dtype=tf.float32)
8 Y = tf.placeholder(shape=(), dtype=tf.float32)
9 eta = tf.constant(eta_data)
10
11 beta = tf.Variable([0, 0], dtype=tf.float32)
12 beta_0 = tf.Variable(0, dtype=tf.float32)
13
14 Yhat = tf.add(beta_0, tf.reduce_sum(tf.multiply(X, beta)))
15 error = tf.reduce_sum(tf.square(tf.subtract(Y, Yhat)))
16
17 grads = tf.gradients(error, [beta, beta_0])
18 beta_update = tf.assign_sub(beta, tf.multiply(eta, grads[0]))
19 beta_0_update = tf.assign_sub(beta_0, tf.multiply(eta, grads[1]))
20
21 init = tf.global_variables_initializer()
22 sess = tf.Session()
23 sess.run( init )
24
25 for t in range(100):
26     error_epoch = 0
27     for X_data, Y_data in zip(Xs_data, Ys_data):
28         error_val, beta_val, beta_0_val = sess.run([error,beta_update,beta_0_update],
29                                         { X: X_data, Y: Y_data })
30         error_epoch += error_val
31     print(t, error_epoch, beta_0_val[0], beta_val[1])
```



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Reader Node

```

1 import tensorflow as tf
2
3 data_files = ['lr-data.csv']; eta_data = 0.01
4
5 filename_queue = tf.train.string_input_producer(data_files)
6 reader = tf.TextLineReader(skip_header_lines=1)
7 _, line = reader.read(filename_queue)
8
9 sess = tf.Session()
10 coord = tf.train.Coordinator()
11 threads = tf.train.start_queue_runners(coord=coord, sess=sess)
12
13 for t in range(6):
14     line_val = sess.run(line)
15     print(t, line_val)
16
17 coord.request_stop()
18 coord.join(threads)

```

file lr-data.csv:

```

1 X1, X2, Y
2 2, 1, +1
3 1, 2, +1
4 4, 3, -1
5 3, 4, -1

```

Output:

```

1 0 b'2,1,+1'
2 1 b'1,2,+1'
3 2 b'4,3,-1'
4 3 b'3,4,-1'
5 4 b'2,1,+1'
6 5 b'1,2,+1'

```

Example: SGD Reading On The Fly

```
1 import tensorflow as tf
2 data_files = ['lr-data.csv']; eta_data = 0.01
3
4 filename_queue = tf.train.string_input_producer(data_files)
5 reader = tf.TextLineReader(skip_header_lines=1)
6 key, value = reader.read(filename_queue)
7 X1, X2, Y = tf.decode_csv(value, record_defaults=[[0.0],[0.0],[0.0]])
8 X = tf.stack([X1, X2])
9 eta = tf.constant(eta_data)
10
11 beta = tf.Variable([0, 0], dtype=tf.float32)
12 beta_0 = tf.Variable(0, dtype=tf.float32)
13 Yhat = tf.add(beta_0, tf.reduce_sum(tf.multiply(X, beta)))
14 error = tf.reduce_sum(tf.square(tf.subtract(Y, Yhat)))
15 grads = tf.gradients(error, [beta, beta_0])
16 beta_update = tf.assign_sub(beta, tf.multiply(eta, grads[0]))
17 beta_0_update = tf.assign_sub(beta_0, tf.multiply(eta, grads[1]))
18 init = tf.global_variables_initializer()
19 sess = tf.Session(); sess.run(init)
20 coord = tf.train.Coordinator()
21 threads = tf.train.start_queue_runners(coord=coord, sess=sess)
22
23 error_epoch = 0
24 for t in range(400):
25     error_val, beta_val, beta_0_val = sess.run([error, beta_update, beta_0_update])
26     error_epoch += error_val
27     if t % 10 == 0:
28         print(t, error_epoch, beta_0_val, beta_val[0], beta_val[1])
29         error_epoch = 0
30 coord.request_stop()
31 coord.join(threads)
```



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Debugging: Visualize Computational Graph

1. Create a **summary.FileWriter** for the session and graph before running the session:

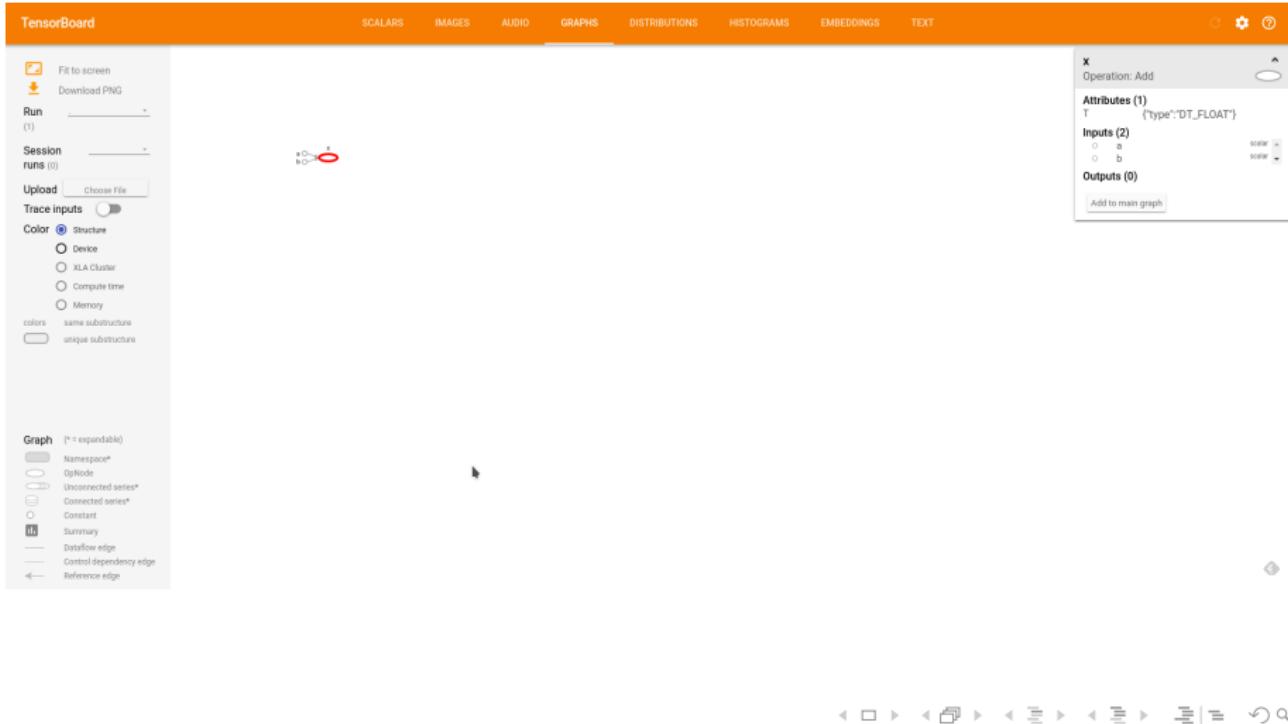
```
1 import tensorflow as tf
2
3 a = tf.constant(3.0, name='a')
4 b = tf.constant(4.0, name='b')
5 x = tf.add(a, b, name='x')
6
7 print(a)
8
9 sess = tf.Session()
10 log = tf.summary.FileWriter('logs/add-two-constants.log', sess.graph)
11 x_val = sess.run(x)
12 log.close()
13 print(x_val)
```

2. run tensorboard on the logdir:

```
1 > tensorboard --logdir logs/add-two-constants.log
```

3. open localhost:6006 in your browser

Debugging: Visualize Computational Graph



The screenshot shows the TensorBoard interface with the 'GRAPHS' tab selected. On the left, there is a sidebar with various configuration options like 'Run', 'Session', 'Upload', 'Trace inputs', 'Color', and a legend for the graph elements. The main area displays a computational graph with nodes 'a' and 'b' connected by an edge labeled 'x'. A red oval highlights the edge 'x'. To the right of the graph, a detailed view of the 'Add' operation is shown, including its attributes (type: DT_FLOAT), inputs (a and b), and outputs (empty). There is also a button to 'Add to main graph'.

Summary (1/3)

- ▶ TensorFlow represents computations as **graphs**.
 - ▶ nodes representing (a list of) **tensors**.
 - ▶ stored:
 - immutable: **constant**, **placeholder**
 - mutable: **variable**
 - ▶ computed: **operation**
 - ▶ edges representing dependencies
 - ▶ $x \rightarrow y$: y is computed and x is one of its inputs
- ▶ Two phases:
 - ▶ graph construction
 - ▶ executing (parts of) the graph (**running**)

Summary (2/3)

- ▶ Nodes can be **distributed over different devices**.
 - ▶ cores of a CPU, GPUs, different compute nodes
 - ▶ **automatic placement** based on cost heuristics
 - ▶ eligible: sufficient memory available
 - ▶ expected runtime
 - based on cost heuristics
 - possibly also based on past runs
 - ▶ expected time for data movement between devices
- ▶ Operations can be assembled from dozens of **elementary operations**.
 - ▶ elementary math: add, subtract, multiply, divide
 - ▶ elementwise functions: log, exp, etc.
 - ▶ matrix operations: matrix product, inversion, etc.
 - ▶ structural tensor operations: slicing, stacking etc.

Summary (3/3)

- ▶ **Gradients** can be computed automatically.
 - ▶ simply using the chain rule
 - ▶ and explicit gradients for all elementary operations.
 - ▶ gradients add nodes to the graph.
- ▶ Medium-sized data should be broken into parts and **fed into a placeholder** for parts
 - ▶ e.g., SGD: single instances or minibatches
 - ▶ medium-sized data:
 - ▶ too large for the GPU
 - ▶ still can be read on a single data node
- ▶ Large data must be read by **reader nodes** as part of the graph execution.
 - ▶ large data: must be read on different data nodes in a distributed fashion

Further Readings

- ▶ TensorFlow white paper:
 - ▶ Abadi et al. [2016]
 - ▶ not yet fully complete: evaluation section is missing

References |

Martín Abadi, Ashish Agarwal, Paul Barham, Eugene Brevdo, Zhifeng Chen, Craig Citro, Greg S Corrado, Andy Davis, Jeffrey Dean, Matthieu Devin, et al. Tensorflow: Large-scale machine learning on heterogeneous distributed systems. *arXiv preprint arXiv:1603.04467*, 2016.