

Bayesian Networks

7. Approximate Inference / Sampling

Lars Schmidt-Thieme

Information Systems and Machine Learning Lab (ISMLL)
Institute for Business Economics and Information Systems
& Institute for Computer Science
University of Hildesheim
<http://www.ismll.uni-hildesheim.de>

Lars Schmidt-Thieme, Information Systems and Machine Learning Lab (ISMLL), Institute BW/WI & Institute for Computer Science, University of Hildesheim
Course on Bayesian Networks, summer term 2010

1/20

Bayesian Networks



1. Why exact inference may not be good enough

2. Acceptance-Rejection Sampling

3. Importance Sampling

4. Self and Adaptive Importance Sampling

5. Stochastic / Loopy Propagation

bayesian network	# variables	time for exact inference
studfarm	12	0.18s
Hailfinder	56	0.36s
Pathfinder-23	135	4.04s
Link	742	307.72s ¹⁾

on a 1.6MHz Pentium-M notebook

⁽¹⁾ on a 2.5 MHz Pentium-IV)

though

- w/o optimized implementation
- with very simple triangulation heuristics (minimal degree).

1. Why exact inference may not be good enough

2. Acceptance-Rejection Sampling

3. Importance Sampling

4. Self and Adaptive Importance Sampling

5. Stochastic / Loopy Propagation

Estimating marginals from data

case	family-out	light-on	bowel-problem	dog-out	hear-bark
1	0	0	0	0	0
2	0	0	0	0	0
3	1	1	1	1	0
4	0	0	1	1	1
5	0	0	0	0	0
6	0	0	0	0	0
7	0	0	0	1	1
8	0	0	0	0	0
9	0	0	1	1	1
10	1	1	0	1	1

Figure 1: Example data for the dog-problem.

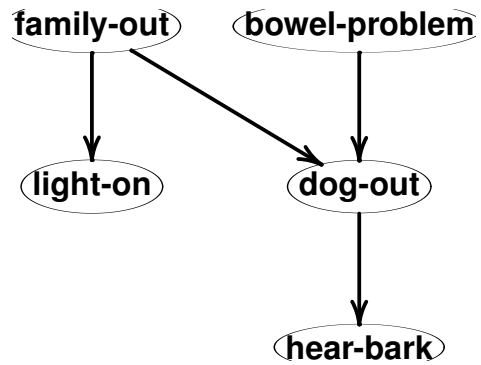


Figure 2: Bayesian network for dog-problem.

family-out	0	8
	1	2

a) counts

family-out	0	0.8
	1	0.2

b) probabilities

Figure 3: Estimating absolute probabilities (root node tables).

Estimating marginals from data

case	family-out	light-on	bowel-problem	dog-out	hear-bark
1	0	0	0	0	0
2	0	0	0	0	0
3	1	1	1	1	0
4	0	0	1	1	1
5	0	0	0	0	0
6	0	0	0	0	0
7	0	0	0	1	1
8	0	0	0	0	0
9	0	0	1	1	1
10	1	1	0	1	1

Figure 1: Example data for the dog-problem.

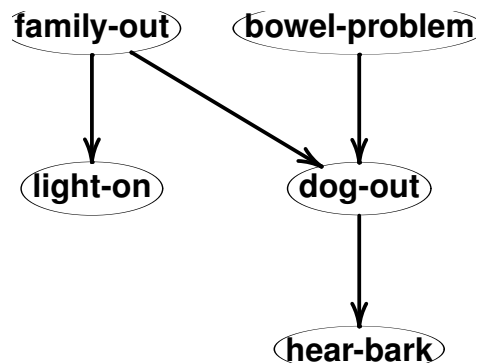


Figure 2: Bayesian network for dog-problem.

family-out	0	1			
bowel	0	1	0	1	
dog-out	0	5	0	0	0
	1	1	2	1	1

a) counts

family-out	0	1			
bowel	0	1	0	1	
dog-out	0	0.5	0	0	0
	1	0.1	0.2	0.1	0.1

b) absolute probabilities

family-out	0	1			
bowel	0	1	0	1	
dog-out	0	$\frac{5}{6}$	0	0	0
	0	$\frac{1}{6}$	1	1	1

c) cond. probabilities

Figure 4: Estimating conditional probabilities (inner node tables).

Estimating marginals from data given evidence

If we want to estimate the probabilities for **family-out** given the evidence that **dog-out** is 1, we have

- (i) identify all cases that are **compatible with the given evidence**,
- (ii) estimate the target potential $p(\text{family-out})$ from these cases.

case	family-out	light-on	bowel-problem	dog-out	hear-bark	
1	0	0	0	0	0	rejected
2	0	0	0	0	0	rejected
3	1	1	1	1	0	accepted
4	0	0	1	1	1	accepted
5	0	0	0	0	0	rejected
6	0	0	0	0	0	rejected
7	0	0	0	1	1	accepted
8	0	0	0	0	0	rejected
9	0	0	1	1	1	accepted
10	1	1	0	1	1	accepted

Figure 5: Accepted and rejected cases for evidence dog-out = 1.

family-out	0	3
	1	2

a) counts

family-out	0	0.6
	1	0.4

b) probabilities

Figure 6: Estimating target potentials given evidence, here $p(\text{family-out}|\text{dog-out} = 1)$.

Learning and inferencing

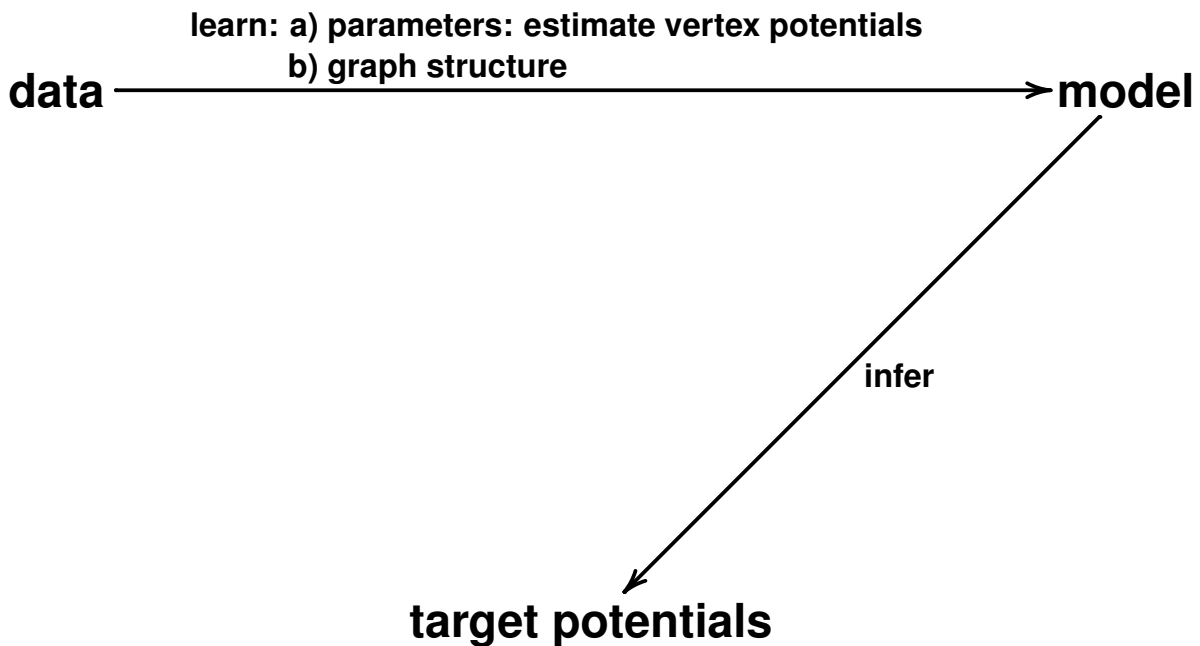


Figure 7: Learning models from data for inferencing.

Sampling and estimating

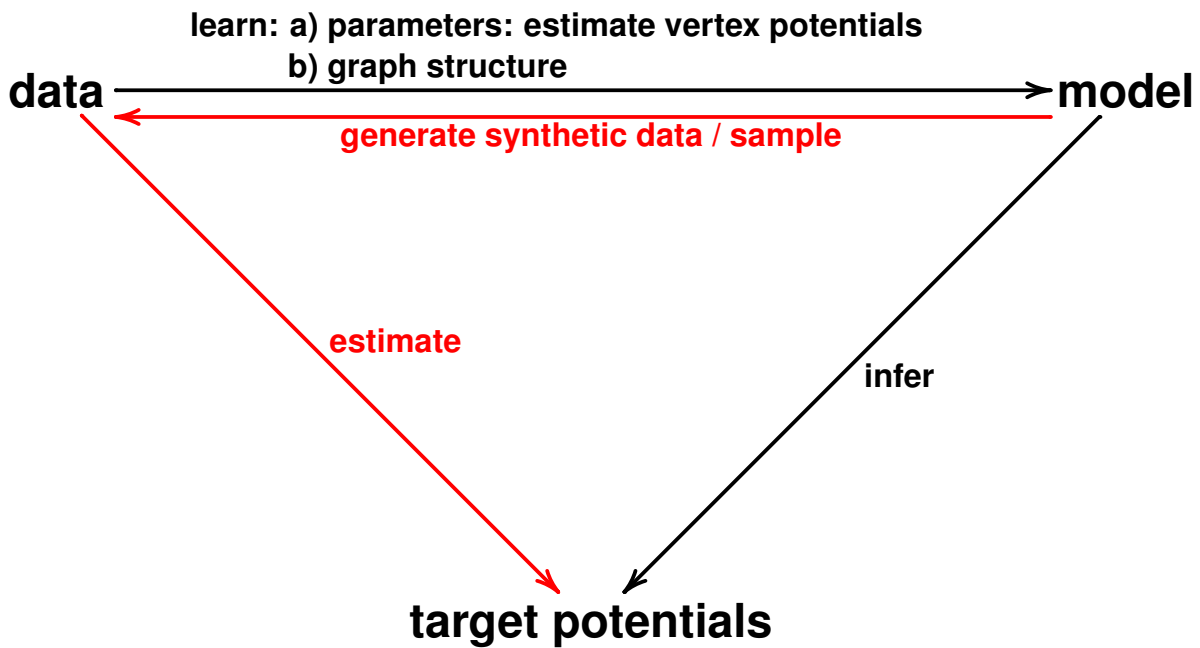


Figure 7: Learning models from data for inferencing vs. sampling from models and estimating.

Sampling a discrete distribution

Given a discrete distribution, e.g.,

	Pain				Weightloss				Vomiting			
	Y		N		Y		N		Y		N	
Adeno	.169	.210	.048	.049	.119	.112	.009	.005	.003	.009	.010	.024
					.039	.090	.044	.062				

Figure 8: Example for a discrete distribution.

How do we draw samples from this distribution?

= generate synthetic data that is distributed according to it?

Sampling a discrete distribution

(i) Fix an enumeration of all states of the distribution p , i.e.,

$$\sigma : \{1, \dots, |\Omega|\} \rightarrow \Omega \text{ bijective}$$

with Ω the set of all states,

(ii) compute the cumulative distribution function in the state index, i.e.,

$$\text{cum}_{p,\sigma} : \{1, \dots, |\Omega|\} \rightarrow [0, 1]$$

$$i \mapsto \sum_{j \leq i} p(\sigma(j))$$

(iii) draw a random real value r uniformly from $[0, 1]$,

(iv) search the state ω with

$$\text{cum}_{p,\sigma}(\omega) \leq r$$

and maximal $\text{cum}_{p,\sigma}(\omega)$.

Pain	Y					N					
Weightloss	Y					N	Y				N
Vomiting	Y	N				Y	N			Y	N
Adeno	Y	.169	.210	.048	.049	.119	.112	.009	.005		
	N	.003	.009	.010	.024	.039	.090	.044	.060		

Figure 8: Example for a discrete distribution.

Adeno	Y									N									
Pain	Y									Y					N				
Weightloss	Y					N	Y				N	Y			N				
Vomiting	Y	N	Y	N	Y	N	Y	N	Y	N	Y	N	Y	N	Y	N			
$\text{cum}_{p,\sigma}(i)$.169	.379	.427	.476	.595	.707	.716	.721	.724	.733	.743	.767	.806	.896	.940	1.000			
index i	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16			

Figure 9: Cumulative distribution function.

Sampling a Bayesian Network / naive approach

As a bayesian network encodes a discrete distribution, we can use the method from the former slide to draw samples from a bayesian network:

- (i) Compute the full JPD table from the bayesian network,
- (ii) draw a sample from the table as on the slide before.

This approach is not sensible though, as we actually used bayesian networks s.t. we **not** have to compute the full JPD (as it normally is way to large to handle).

How can we make use of the independencies encoded in the bayesian network structure?

Sampling a Bayesian Network

Idea: sample variables separately, one at a time.

If we have sampled

$$X_1, \dots, X_k$$

already and X_{k+1} is a vertex s.t.

$$\text{desc}(X_{k+1}) \cap \{X_1, \dots, X_k\} = \emptyset$$

then

$$p(X_{k+1} | X_1, \dots, X_k) = p(X_{k+1} | \text{pa}(X_{k+1}))$$

i.e., we can sample X_{k+1} from its vertex potential given the evidence of its parents (as sampled before).

```

1 sample-forward( $B := (G := (V, E), (p_v)_{v \in V})$ ) :
2  $\sigma := \text{topological-ordering}(G)$ 
3  $x := 0_V$ 
4 for  $i = 1, \dots, |\sigma|$  do
5    $v := \sigma(i)$ 
6    $q := p_v |_{x|_{\text{pa}(v)}}$ 
7   draw  $x_v \sim q$ 
8 od
9 return  $x$ 
    
```

Figure 10: Algorithm for sampling a bayesian network.

Sampling a Bayesian Network / example

Let $\sigma := (F, B, L, D, H)$.

1. $x_F \sim p_F = (0.85, 0.15)$
say with outcome 0.
2. $x_B \sim p_B = (0.8, 0.2)$
say with outcome 1.
3. $x_L \sim p_L(F = 0) = (0.95, 0.05)$
say with outcome 0.
4. $x_D \sim p_D(F = 0, B = 1) = (0.03, 0.97)$
say with outcome 1.
5. $x_H \sim p_H(D = 1) = (0.3, 0.7)$
say with outcome 1.

The result is

$$x = (0, 1, 0, 1, 1)$$

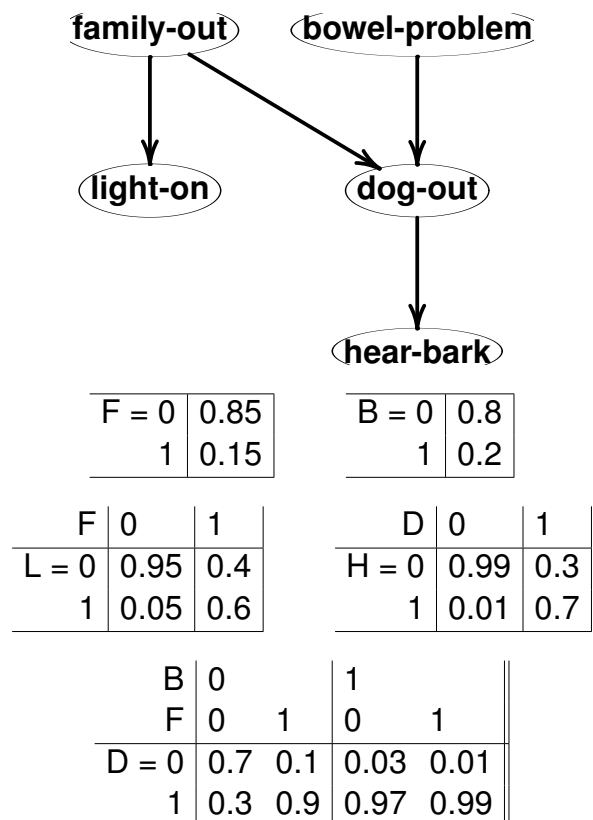


Figure 11: Bayesian network for dog-problem.

Acceptance-rejection sampling

Inferencing by **acceptance-rejection sampling** means:

- (i) draw a sample from the bayesian network (w/o evidence entered),
- (ii) drop all data from the sample that are not conformant with the evidence,
- (iii) estimate target potentials from the remaining data.

For bayesian networks sampling is done by forward-sampling. — Forward sampling is stopped as soon as an evidence variable has been instantiated that contradicts the evidence.

Acceptance-rejection sampling for bayesian networks is also called **logic sampling** [Hen88]

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Bayesian Networks

```

1 infer-acceptance-rejection( $B$  : bayesian network,
2    $W$  : target domain,  $E$  : evidence,  $n$  : sample size) :
3  $D :=$  (sample-forward( $B$ ) |  $i = 1, \dots, n$ )
4 return estimate( $D, W, E$ )

```

```

1 sample-forward( $B := (G := (V, E), (p_v)_{v \in V})$ ) :
2  $\sigma :=$  topological-ordering( $G$ )
3  $x := 0_V$ 
4 for  $i = 1, \dots, |\sigma|$  do
5    $v := \sigma(i)$ 
6    $q := p_v | x_{pa(v)}$ 
7   draw  $x_v \sim q$ 
8 od
9 return  $x$ 

```

```

1 estimate( $D$  : data,  $W$  : target domain,  $E$  : evidence) :
2  $D' := (d \in D \mid d|_{\text{dom}(E)} = \text{val}(E))$ 
3 return estimate( $D', W$ )

```

```

1 estimate( $D$  : data,  $W$  : target domain) :
2  $q :=$  zero-potential on  $W$ 
3 for  $d \in D$  do
4    $q(d)++$ 
5 od
6  $q := q / |data|$ 
7 return  $q$ 

```

Figure 12: Algorithm for acceptance-rejection sampling.

11/20

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Acceptance rate of acceptance-rejection sampling

How efficient acceptance-rejection sampling is depends on the **acceptance rate**.

Let E be evidence. Then the acceptance rate, i.e., the fraction of samples conformant with E , is

$$p(E)$$

the marginal probability of the evidence.

Thus, acceptance-rejection sampling performs poorly if the probability of evidence is small. In the studfarm example

$$p(J = aa) = 0.00043$$

i.e., from 2326 sampled cases 2325 are rejected.

Idea of importance sampling

Idea: do not sample the evidence variables, but instantiate them to the values of the evidence.

Instantiating the evidence variables first, means, we have to sample the other variables from

$$p(X_{k+1} | X_1 = x_1, \dots, X_k = x_k, E_1 = e_1, \dots, E_m = e_m)$$

even for a topological ordering of non-evidential variables.

Problem: if there is an evidence variable that is a descendant of a non-evidential variable X_{k+1} that has to be sampled, then

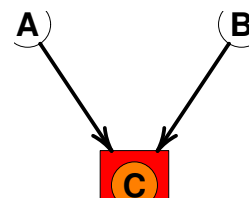


Figure 13: If C is evidential and already instantiated, say $C = c$, then A is dependent on C , so we would have to sample A from $p(A|C = c)$. Even worse, B is dependant on C and A (d-separation), so we would have to sample B from $p(B|A = a, C = c)$. But neither of these cpdfs is known in advance.

- it does neither occur among its parents nor is independent from X_{k+1} , and
- it may open dependency chains to other variables !

Inference from a stochastic point of view

Let V be a set of variables and p a pdf on $\prod \text{dom}(V)$. Inferring the marginal on a given set of variables $W \subseteq V$ and given evidence E means to compute

$$(p_E)^{\downarrow W}$$

i.e., for all $x \in \prod \text{dom}(W)$

$$\begin{aligned} (p_E)^{\downarrow W}(x) &= \sum_{y \in \prod \text{dom}(V \setminus W \setminus \text{dom}(E))} p(x, y, e) \\ &= \sum_{y \in \prod \text{dom}(V)} I_{x,e}(y) \cdot p(y) \end{aligned}$$

with the indicator function

$$I_x : \prod \text{dom}(V) \rightarrow \{0, 1\}$$

$$y \mapsto \begin{cases} 1, & \text{if } y|_{\text{dom}(x)} = x \\ 0, & \text{else} \end{cases}$$

So we can reformulate the inference problem as the problem of **averaging a given random variable f (here: $f := I_{x,e}$) over a given pdf p** , i.e., to compute / estimate the mean

$$\mathbb{E}_p(f) := \sum_{x \in \text{dom}(p)} f(x) \cdot p(x)$$

Theorem 1 (strong law of large numbers). *Let $p : \Omega \rightarrow [0, 1]$ be a pdf, $f : \Omega \rightarrow \mathbb{R}$ be a random variable with $\mathbb{E}_p(|f|) < \infty$, and $X_i \sim f, i \in \mathbb{N}$ independently.*

Then

$$\frac{1}{n} \sum_{i=1}^n X_i \rightarrow_{a.s.} \mathbb{E}_p(f)$$

Proof. See, e.g., [Sha03, p. 62] □

Sampling from the wrong distribution

Inference by sampling applies the SLLN:

$$\begin{aligned} \sum_{x \in \text{dom}(p)} f(x) \cdot p(x) &= \mathbb{E}_p(f) \\ &\approx \frac{1}{n} \sum_{\substack{x \sim p \\ (n \text{ draws})}} f(x) \end{aligned}$$

Now let q be any other pdf with

$$p(x) > 0 \implies q(x) > 0, \quad \forall x \in \text{dom}(p) = \text{dom}(q)$$

Due to

$$\begin{aligned} \sum_{x \in \text{dom}(p)} f(x) \cdot p(x) &= \sum_{x \in \text{dom}(p)} f(x) \cdot \frac{p(x)}{q(x)} \cdot q(x) \\ &= \mathbb{E}_q\left(f \cdot \frac{p}{q}\right) \\ &\approx \frac{1}{n} \sum_{\substack{x \sim q \\ (n \text{ draws})}} f(x) \cdot \frac{p(x)}{q(x)} \end{aligned}$$

we can sample from q instead from p if we adjust the function values of f accordingly.

The pdf q is called **importance function**, the function $w := p/q$ is called **score** or **case weight**.

Often we know the case weight only up to a multiplicative constant, i.e., $w' := c \cdot w \propto p/q$ with unknown constant c .

For a sample $x_1, \dots, x_n \sim q$, we then can approximate $\mathbb{E}_p(f)$ by

$$\begin{aligned} \mathbb{E}_p(f) &\approx \frac{1}{n} \sum_{i=1}^n f(x_i) \cdot w(x_i) \\ &\approx \frac{1}{\sum_i w'(x_i)} \sum_{i=1}^n f(x_i) \cdot w'(x_i) \end{aligned}$$

Case weight

Back to

sampling from the true distribution p_E

vs.

sampling from the bayesian network
with pre-instantiated evidence variables
(the wrong distribution)

The probability for a sample x from a
Bayesian network among samples con-
formant with a given evidence E is

$$p(x|E) = \frac{p(x)}{p(E)} = \frac{\prod_{v \in V} p_v(x_v | x|_{\text{pa}(v)})}{p(E)}$$

The probability for a sample x from a
Bayesian network with pre-instantiated
evidence variables is

$$q_E(x) = \prod_{v \in V \setminus \text{dom}(E)} p_v(x_v | x|_{\text{pa}(v)})$$

Thus, the case weight is

$$w(x) := \frac{p(x|E)}{q_E(x)} = \frac{\prod_{v \in \text{dom}(E)} p_v(x_v | x|_{\text{pa}(v)})}{p(E)}$$

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16/20

Likelihood weighting sampling

Inferencing by **importance sampling**
means:

- (i) choose a sampling distribution q ,
- (ii) draw a weighted sample from q ,
- (iii) estimate target potentials from
these sample data.

For bayesian networks using *sam-
pling from bayesian networks with pre-
instantiated evidence variables* and the
case weight

$$w(x) := \prod_{v \in \text{dom}(E)} p_v(x_v | x|_{\text{pa}(v)})$$

is called **likelihood weighting sam-
pling** [FC90, SP90]

```

1 infer-likelihood-weighting( $B$  : bayesian network,
2    $W$  : target domain,  $E$  : evidence,  $n$  : sample size) :
3 ( $D, w$ ) := (sample-likelihood-weighting( $B, E$ ) |  $i = 1, \dots, n$ )
4 return estimate( $D, w, W$ )

1 sample-likelihood-weighting( $B := (G, (p_v)_{v \in V_G}), E$  : evidence) :
2  $\sigma :=$  topological-ordering( $G \setminus \text{dom}(E)$ )
3  $x := 0_{V_G}$ 
4  $x|_{\text{dom}(E)} := \text{val}(E)$ 
5 for  $i = 1, \dots, |\sigma|$  do
6    $v := \sigma(i)$ 
7    $q := p_v | x|_{\text{pa}(v)}$ 
8   draw  $x_v \sim q$ 
9 od
10  $w(x) := \prod_{v \in \text{dom}(E)} p_v(x_v | x|_{\text{pa}(v)})$ 
11 return ( $x, w(x)$ )

1 estimate( $D$  : data,  $w$  : case weight,  $W$  : target domain) :
2  $q :=$  zero-potential on  $W$ 
3  $w_{\text{tot}} := 0$ 
4 for  $d \in D$  do
5    $q(d) := q(d) + w(d)$ 
6    $w_{\text{tot}} := w_{\text{tot}} + w(d)$ 
7 od
8  $q := q / w_{\text{tot}}$ 
9 return  $q$ 

```

Figure 14: Algorithm for inference by likelihood
weighting sampling.

Likelihood weighting sampling / example

Let the evidence be $D = 1$. Fix $\sigma := (F, B, L, H)$.

1. $x_F \sim p_F = (0.85, 0.15)$
say with outcome 0.
2. $x_B \sim p_B = (0.8, 0.2)$
say with outcome 1.
3. $x_L \sim p_L(F = 0) = (0.95, 0.05)$
say with outcome 0.
4. $x_H \sim p_H(D = 1) = (0.3, 0.7)$
say with outcome 1.

The result is

$$x = (0, 1, 0, 1, 1)$$

and the case weight

$$w(x) = p_D(D = 1 | F = 0, B = 1) = 0.97$$

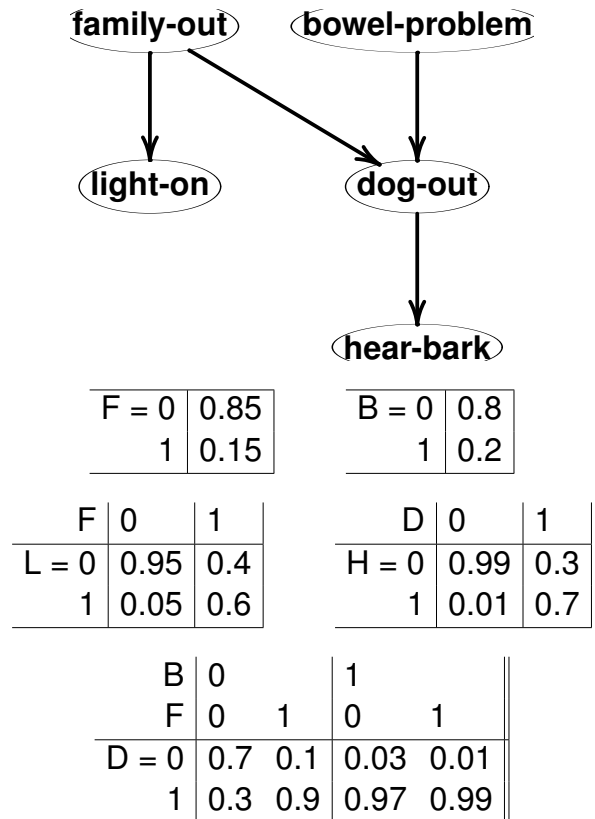


Figure 15: Bayesian network for dog-problem.

Acceptance-rejection sampling

Acceptance-rejection sampling can be viewed as another instance of importance sampling. Here, the sampling distribution is $q := p$ (i.e., the distribution without evidence entered; the target distribution is p_E !) and the case weight

$$w(x) := I_e(x) := \begin{cases} 1, & \text{if } x|_{\text{dom}(E)} = \text{val}(E) \\ 0, & \text{otherwise} \end{cases}$$

References

- [FC90] R. Fung and K. Chang. Weighting and integrating evidence for stochastic simulation in bayesian networks. In M. Henrion, R.D. Shachter, L. N. Kanal, and J. F. Lemmer, editors, *Uncertainty in Artificial Intelligence 5*, pages 209–219. North Holland, Amsterdam, 1990.
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- [Sha03] Jun Shao. *Mathematical Statistics*. Springer, 2003.
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