

Clustering (Part II)

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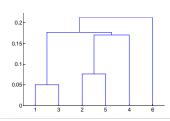


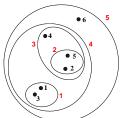
Hierarchical Clustering

Produces a set of nested clusters organized as a hierarchical tree

Can be visualized as a dendrogram

A tree like diagram that records the sequences of merges or splits







Strengths of Hierarchical Clustering

Do not have to assume any particular number of clusters

Any desired number of clusters can be obtained by 'cutting' the dendogram at the proper level

They may correspond to meaningful taxonomies

Example in biological sciences (e.g., animal kingdom, phylogeny reconstruction, ...)



Hierarchical Clustering

Two main types of hierarchical clustering

Agglomerative:

Start with the points as individual clusters At each step, merge the closest pair of clusters until only one cluster (or k clusters) left

Divisive:

Start with one, all-inclusive cluster At each step, split a cluster until each cluster contains a point (or there are k clusters)

Traditional hierarchical algorithms use a similarity or distance matrix

Merge or split one cluster at a time

Agglomerative Clustering Algorithm



More popular hierarchical clustering technique

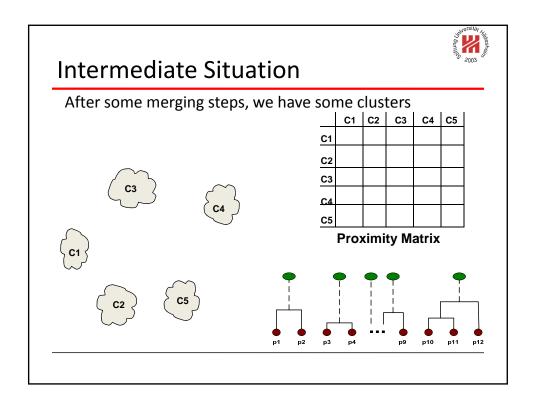
Basic algorithm is straightforward

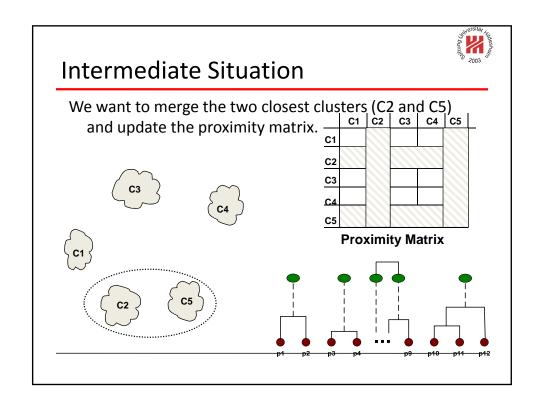
- 1. Compute the proximity matrix
- 2. Let each data point be a cluster
- 3. Repeat
- 4. Merge the two closest clusters
- 5. Update the proximity matrix
- **6. Until** only a single cluster remains

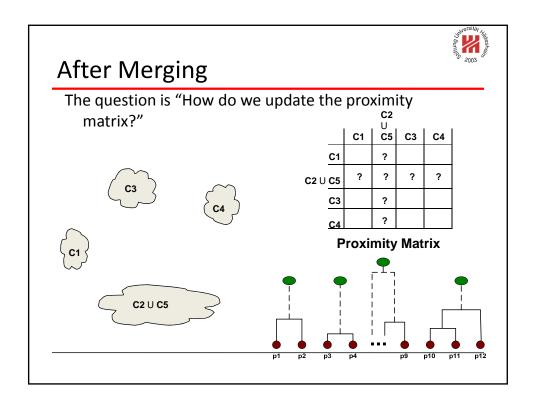
Key operation is the computation of the proximity of two clusters

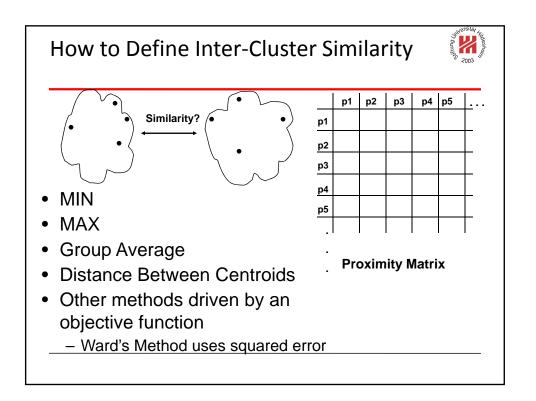
Different approaches to defining the distance between clusters distinguish the different algorithms

Starting Situat	ion					ountiles 2003
Start with clusted proximity matr		dividua 	l poir	1 1	and a	<u> </u>
	0	p2 p3 p4 p5	Proxi	mity	Matrix	
		• • • p1 p2 p;	• • • • • • • • • • • • • • • • • • •	p9	• p10 p	• • 111 p12









Proximity Matrix

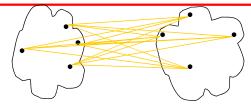
Distance Between Centroids
Other methods driven by an objective function

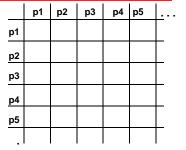
- Ward's Method uses squared error

How to Define Inter-Cluster Similarity р1 p2 рЗ p4 p5 р1 **p2** рЗ p4 MIN **MAX Group Average Proximity Matrix** Distance Between Centroids • Other methods driven by an objective function Ward's Method uses squared error

How to Define Inter-Cluster Similarity







Proximity Matrix

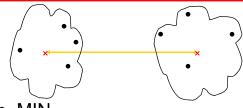
- MIN
- MAX
- Group Average

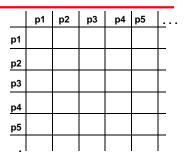
objective function

- Distance Between Centroids
- Other methods driven by an
 - Ward's Method uses squared error

How to Define Inter-Cluster Similarity

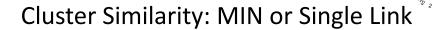






- MIN
- MAX
- Group Average
- Distance Between Centroids
- Other methods driven by an
- Other methods driven by an objective function
 - Ward's Method uses squared error

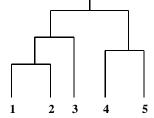
Proximity Matrix

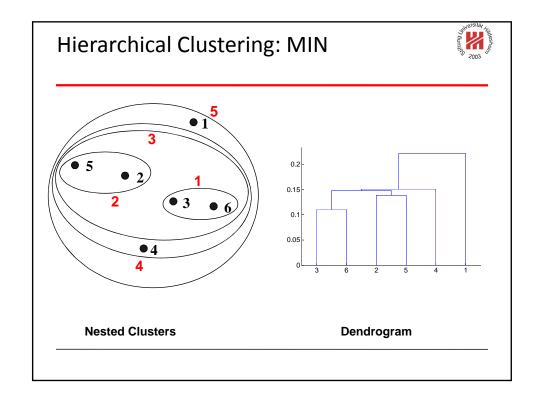


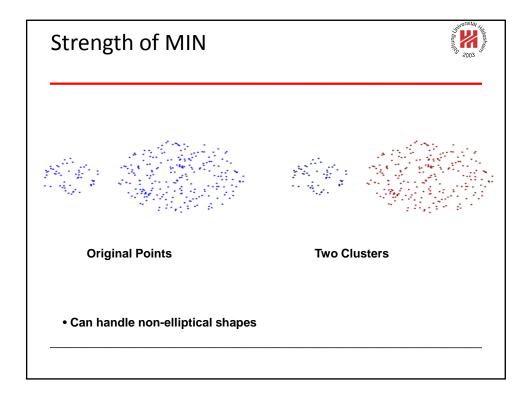
Similarity of two clusters is based on the two most similar (closest) points in the different clusters

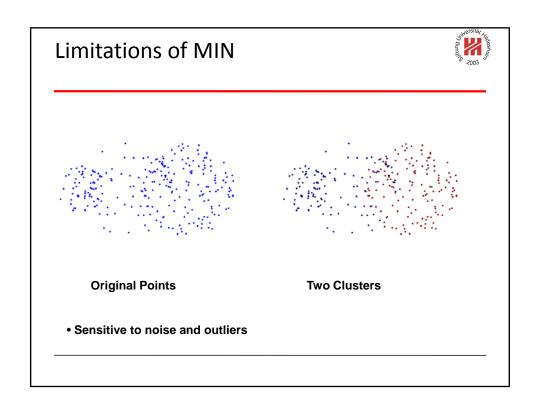
Determined by one pair of points, i.e., by one link in the proximity graph.

	_		_	- /	0 - 1
	I 1	12	13	14	15
11	1.00	0.90 1.00 0.70 0.60 0.50	0.10	0.65	0.20
12	0.90	1.00	0.70	0.60	0.50
13	0.10	0.70	1.00	0.40	0.30
14	0.65	0.60	0.40	1.00	0.80
15	0.20	0.50	0.30	0.80	1.00









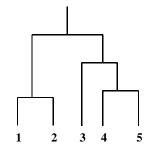
Cluster Similarity: MAX or Complete Linkage

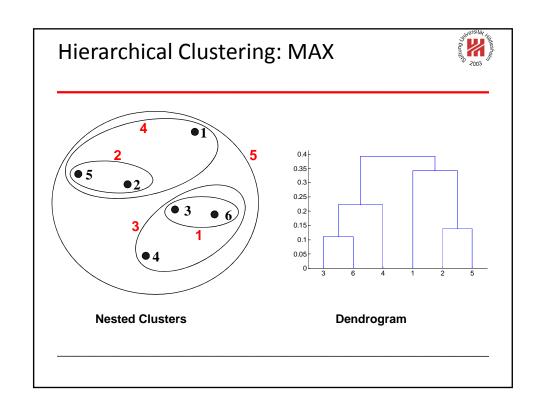


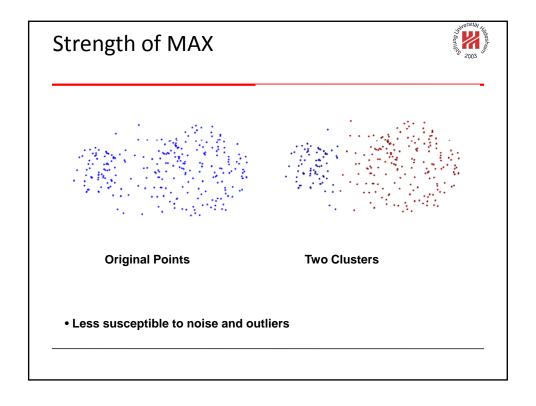
Similarity of two clusters is based on the two least similar (most distant) points in the different clusters

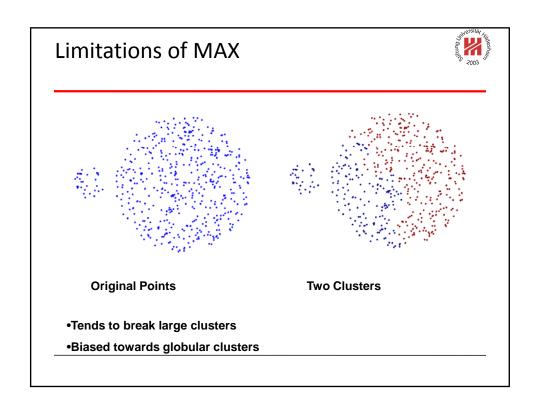
Determined by all pairs of points in the two

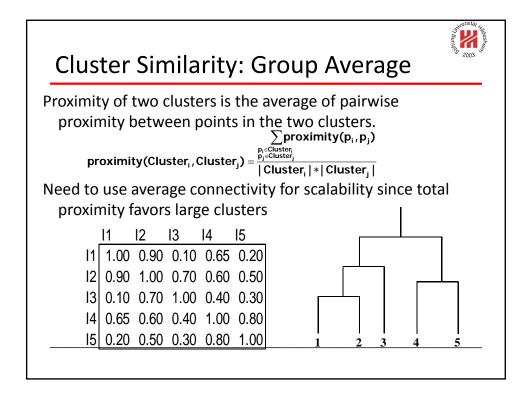
	ciusters					
	<u> 11 </u>	12	13	14	15	
11	1.00	0.90	0.10	0.65	0.20	
12	0.90	1.00	0.70	0.60	0.50	
13	0.10	0.70	1.00	0.40	0.30	
14	0.65	0.60	0.40	1.00	0.80	
15	1.00 0.90 0.10 0.65 0.20	0.50	0.30	0.80	1.00	

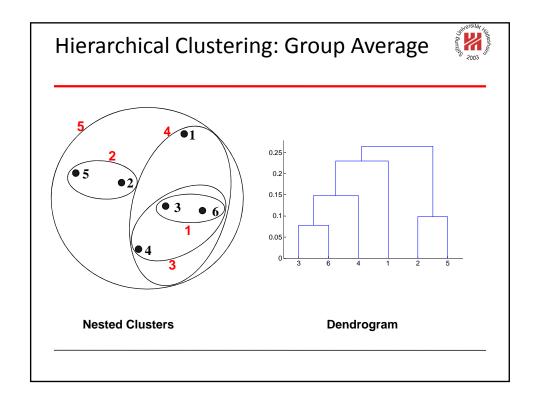














Hierarchical Clustering: Group Average

Compromise between Single and Complete Link

Strengths

Less susceptible to noise and outliers

Limitations

Biased towards globular clusters



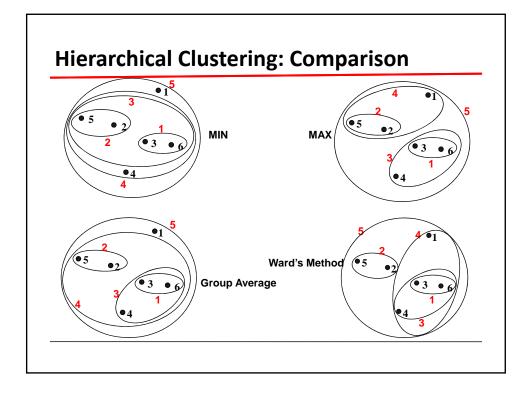
Cluster Similarity: Ward's Method

Similarity of two clusters is based on the increase in squared error when two clusters are merged Similar to group average if distance between points is distance squared

Less susceptible to noise and outliers

Biased towards globular clusters

Hierarchical analogue of K-means Can be used to initialize K-means



Hierarchical Clustering: Time and Space requirements



 $O(N^2)$ space since it uses the proximity matrix. N is the number of points.

O(N³) time in many cases

There are N steps and at each step the size, N^2 , proximity matrix must be updated and searched Complexity can be reduced to $O(N^2 \log(N))$ time for some approaches

Hierarchical Clustering: Problems and Limitations



Once a decision is made to combine two clusters, it cannot be undone

No objective function is directly minimized

Different schemes have problems with one or more of the following:

Sensitivity to noise and outliers

Difficulty handling different sized clusters and convex shapes

Breaking large clusters

Suning 2003

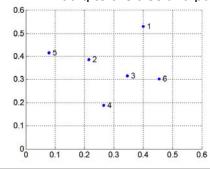
MST: Divisive Hierarchical Clustering

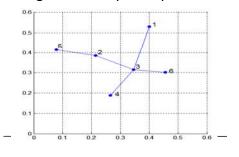
Build MST (Minimum Spanning Tree)

Start with a tree that consists of any point

In successive steps, look for the closest pair of points (p, q) such that one point (p) is in the current tree but the other (q) is not

Add q to the tree and put an edge between p and q







MST: Divisive Hierarchical Clustering

Use MST for constructing hierarchy of clusters

Algorithm 7.5 MST Divisive Hierarchical Clustering Algorithm

- 1: Compute a minimum spanning tree for the proximity graph.
- 2: repeat
- Create a new cluster by breaking the link corresponding to the largest distance (smallest similarity).
- 4: until Only singleton clusters remain



Hierarchical Clustering: Revisited

Creates nested clusters

Agglomerative clustering algorithms vary in terms of how the proximity of two clusters are computed

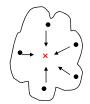
MIN (single link): susceptible to noise/outliers MAX/GROUP AVERAGE: may not work well with non-globular clusters

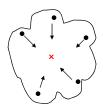
CURE algorithm tries to handle both problems

Often starts with a proximity matrix A type of graph-based algorithm



Uses a number of points to represent a cluster





Representative points are found by selecting a constant number of points from a cluster and then "shrinking" them toward the center of the cluster

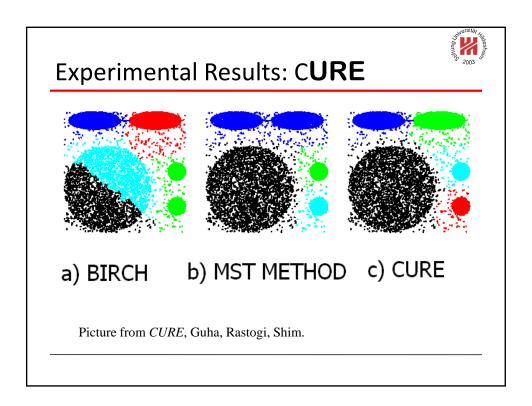
Cluster similarity is the similarity of the closest pair of representative points from different clusters

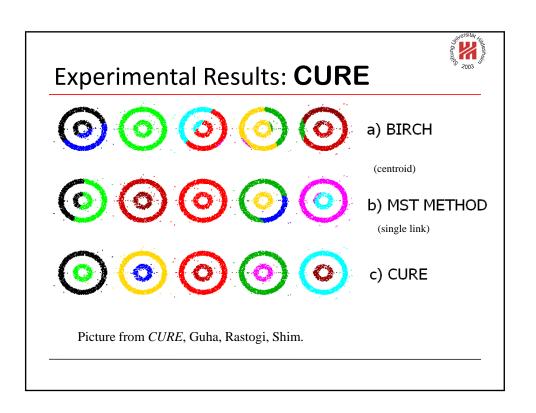
CURE



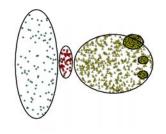
Shrinking representative points toward the center helps avoid problems with noise and outliers

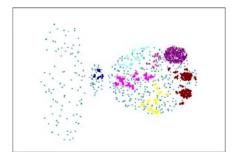
CURE is better able to handle clusters of arbitrary shapes and sizes





CURE Cannot Handle Differing Densities





Original Points

CURE

Graph-Based Clustering



Graph-Based clustering uses the proximity graph
Start with the proximity matrix
Consider each point as a node in a graph
Each edge between two nodes has a weight which is
the proximity between the two points
Initially the proximity graph is fully connected
MIN (single-link) and MAX (complete-link) can be
viewed as starting with this graph

In the simplest case, clusters are connected components in the graph.

Graph-Based Clustering: Sparsification



The amount of data that needs to be processed is drastically reduced

Sparsification can eliminate more than 99% of the entries in a proximity matrix

The amount of time required to cluster the data is drastically reduced

The size of the problems that can be handled is increased

Graph-Based Clustering: Sparsification ...



Clustering may work better

Sparsification techniques keep the connections to the most similar (nearest) neighbors of a point while breaking the connections to less similar points.

The nearest neighbors of a point tend to belong to the same class as the point itself.

This reduces the impact of noise and outliers and sharpens the distinction between clusters.

Sparsification facilitates the use of graph partitioning algorithms (or algorithms based on graph partitioning algorithms.

Chameleon and Hypergraph-based Clustering

Sparsification in the Clustering Process Data Similarity Matrix Feature Selection Sparsification Cluster 1 Cluster 2 Cluster 3



Limitations of Current Merging Schemes

Existing merging schemes in hierarchical clustering algorithms are static in nature

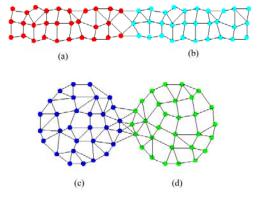
MIN or CURE:

merge two clusters based on their *closeness* (or minimum distance)

GROUP-AVERAGE:

merge two clusters based on their average connectivity

Limitations of Current Merging Schemes



Closeness schemes will merge (a) and (b)

Average connectivity schemes will merge (c) and (d)

Chameleon: Clustering Using Dynamic Modeling



Adapt to the characteristics of the data set to find the natural clusters

Use a dynamic model to measure the similarity between clusters

Main property is the relative closeness and relative interconnectivity of the cluster

Two clusters are combined if the resulting cluster shares certain *properties* with the constituent clusters

The merging scheme preserves self-similarity



One of the areas of application is spatial data

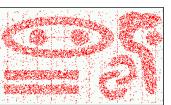


Characteristics of Spatial Data Sets

- Clusters are defined as densely populated regions of the space
- Clusters have arbitrary shapes, orientation, and non-uniform sizes
- Difference in densities across clusters and variation in density within clusters
- Existence of special artifacts (streaks) and noise

The clustering algorithm must address the above characteristics and also require minimal supervision.







Chameleon: Steps

Preprocessing Step:

Represent the Data by a Graph

Given a set of points, construct the k-nearestneighbor (k-NN) graph to capture the relationship between a point and its k nearest neighbors Concept of neighborhood is captured dynamically (even if region is sparse)

Phase 1: Use a multilevel graph partitioning algorithm on the graph to find a large number of clusters of well-connected vertices

Each cluster should contain mostly points from one "true" cluster, i.e., is a sub-cluster of a "real" cluster



Chameleon: Steps ...

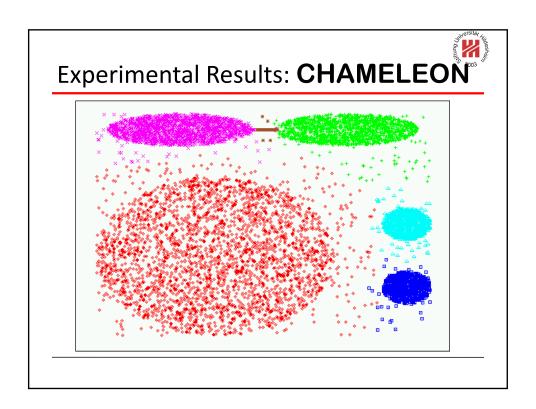
Phase 2: Use Hierarchical Agglomerative Clustering to merge sub-clusters

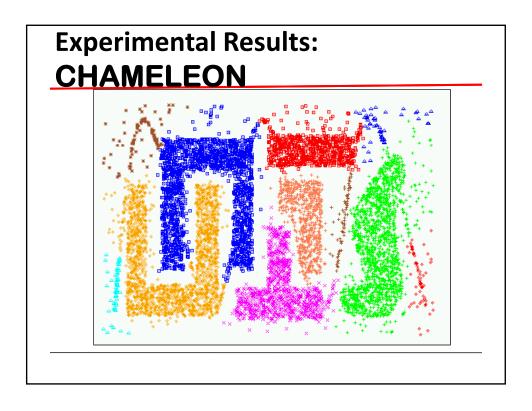
Two clusters are combined if the resulting cluster shares certain properties with the constituent clusters

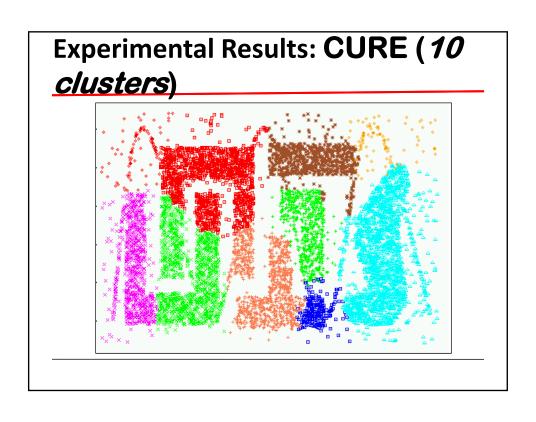
Two key properties used to model cluster similarity:

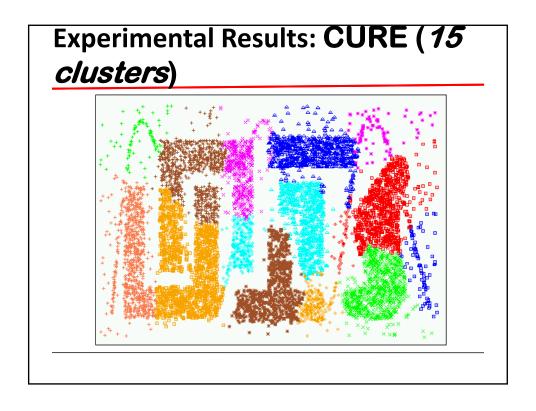
Relative Interconnectivity: Absolute interconnectivity of two clusters normalized by the internal connectivity of the clusters

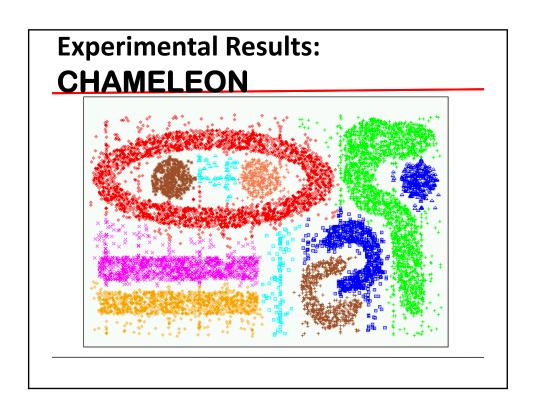
Relative Closeness: Absolute closeness of two clusters normalized by the internal closeness of the clusters

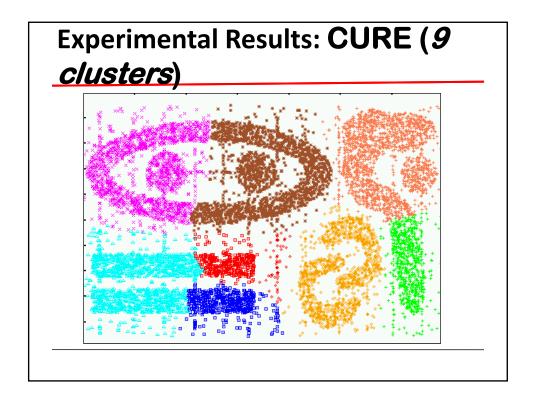


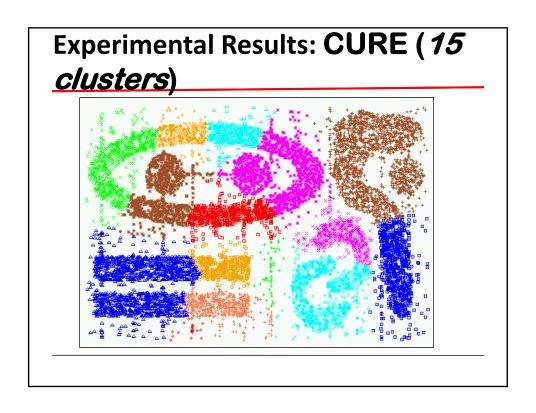






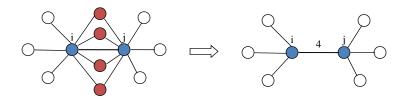




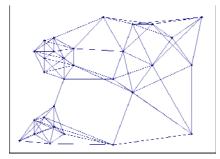


Shared Near Neighbor Approach

SNN graph: the weight of an edge is the number of shared neighbors between vertices given that the vertices are connected

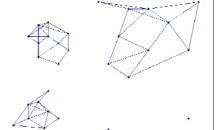


Creating the SNN Graph



Sparse Graph

Link weights are similarities between neighboring points



Shared Near Neighbor Graph

Link weights are number of Shared Nearest Neighbors



Jarvis-Patrick Clustering

First, the k-nearest neighbors of all points are found
In graph terms this can be regarded as breaking all but the k strongest
links from a point to other points in the proximity graph

A pair of points is put in the same cluster if any two points share more than T neighbors and the two points are in each others k nearest neighbor list

For instance, we might choose a nearest neighbor list of size 20 and put points in the same cluster if they share more than 10 near neighbors

Jarvis-Patrick clustering is too brittle

