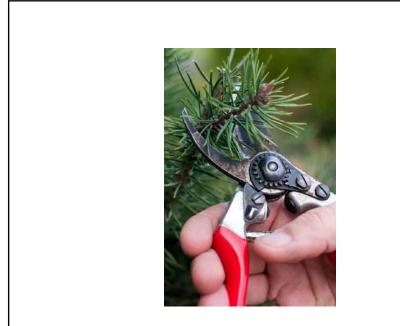
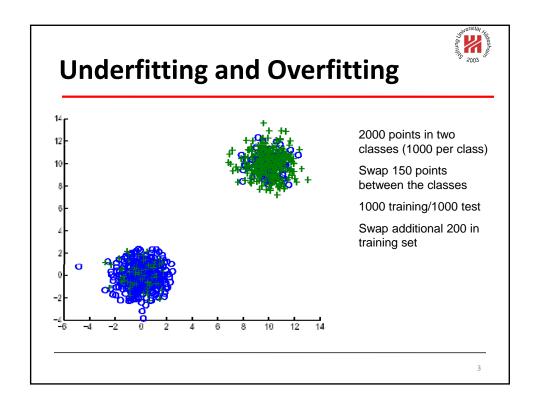


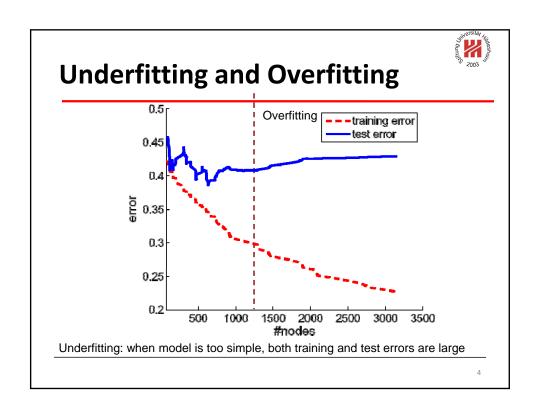
# Decision Trees (Part II: Pruning the tree)

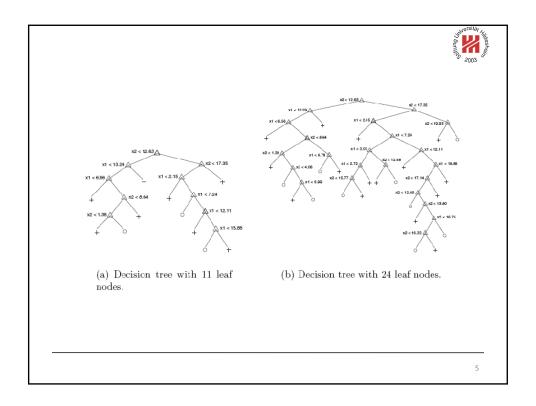
nanopoulos@ismll.de

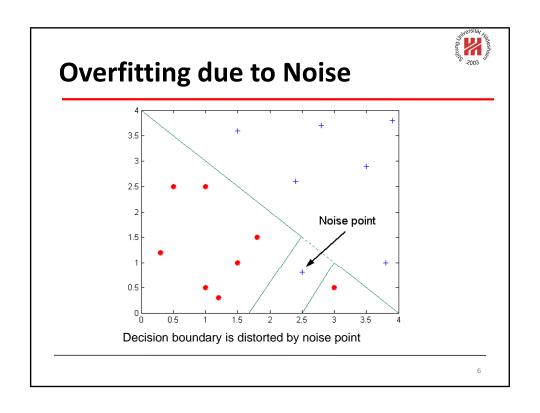
1







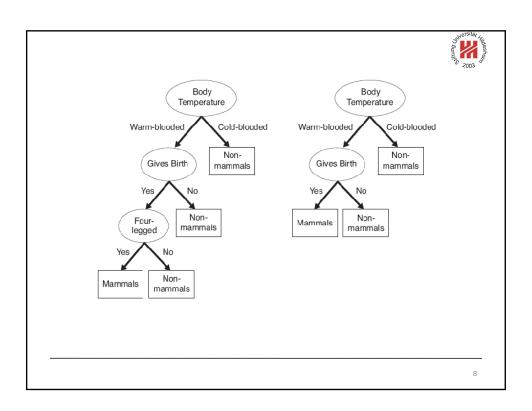






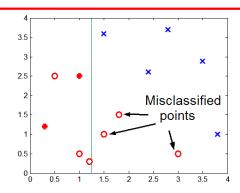
Name	Body	Gives	Four-	Hibernates	Class
	Temperature	$\operatorname{Birth}$	legged		Label
porcupine	warm-blooded	yes	yes	yes	yes
cat	warm-blooded	yes	yes	no	yes
bat	warm-blooded	yes	no	yes	$\mathrm{no}^*$
whale	warm-blooded	yes	no	no	$\mathrm{no}^*$
salamander	cold-blooded	no	yes	yes	no
komodo dragon	cold-blooded	no	yes	no	no
python	cold-blooded	no	no	yes	no
salmon	cold-blooded	no	no	no	no
eagle	warm-blooded	no	no	no	no
guppy	cold-blooded	yes	no	no	no

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#### Overfitting due to Insufficient Examples





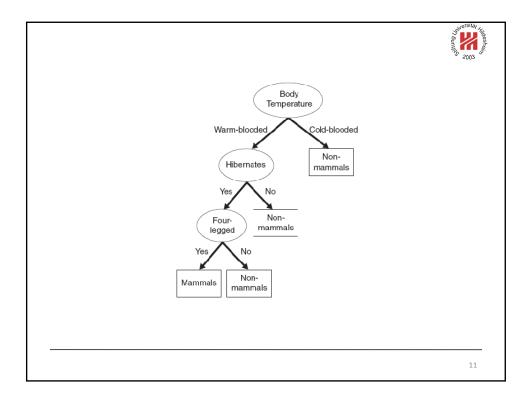
Lack of data points in the lower half of the diagram makes it difficult to predict correctly the class labels of that region

- Insufficient number of training records in the region causes the decision tree to predict the test examples using other training records that are irrelevant to the classification task



Name Body Gives Four-Hibernates Class Temperature Birth legged Label salamander cold-blooded no no yes yes cold-blooded guppy yes no no no eagle warm-blooded nonononopoorwill warm-blooded no yes nonoplatypus warm-blooded no yes yes yes

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### Notes on Overfitting



Overfitting results in decision trees that are more complex than necessary

Training error no longer provides a good estimate of how well the tree will perform on previously unseen records

Need new ways for estimating errors



#### **Estimating Generalization Errors**

Re-substitution errors: error on training ( $\Sigma$  e(t)) Generalization errors: error on testing ( $\Sigma$  e'(t))

Methods for estimating generalization errors:

Optimistic approach: e'(t) = e(t)

Pessimistic approach:

For each leaf node: e'(t) = (e(t)+0.5)Total errors:  $e'(T) = e(T) + N \times 0.5$  (N: number of leaf nodes) For a tree with 30 leaf nodes and 10 errors on training (out of 1000 instances): Training error = 10/1000 = 1%Generalization error =  $(10 + 30 \times 0.5)/1000 = 2.5\%$ 

Reduced error pruning (REP):

uses validation data set to estimate generalization error



#### Occam's Razor

Given two models of similar generalization errors, one should prefer the simpler model over the more complex model

For complex models, there is a greater chance that it was fitted accidentally by errors in data

Therefore, one should include model complexity when evaluating a model



#### How to Address Overfitting

#### Pre-Pruning (Early Stopping Rule)

Stop the algorithm before it becomes a fully-grown tree

Typical stopping conditions for a node:

Stop if all instances belong to the same class Stop if all the attribute values are the same

#### More restrictive conditions:

Stop if number of instances is less than some user-specified threshold Stop if class distribution of instances are independent of the available features (e.g., using  $\chi^2$  test)

Stop if expanding the current node does not improve impurity measures (e.g., Gini or information gain).



#### How to Address Overfitting...

#### Post-pruning

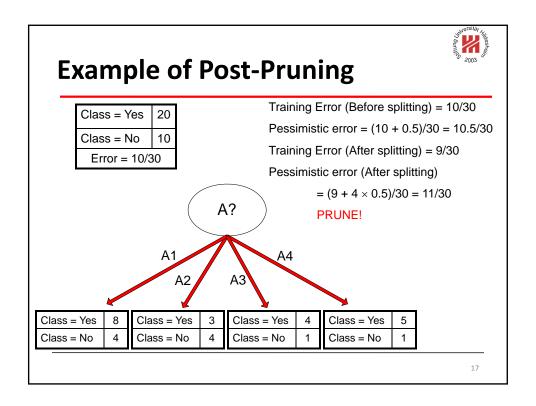
Grow decision tree to its entirety

Trim the nodes of the decision tree in a bottomup fashion

If generalization error improves after trimming, replace sub-tree by a leaf node.

Class label of leaf node is determined from majority class of instances in the sub-tree

Can use MDL for post-pruning



## **Reduced Error Pruning**

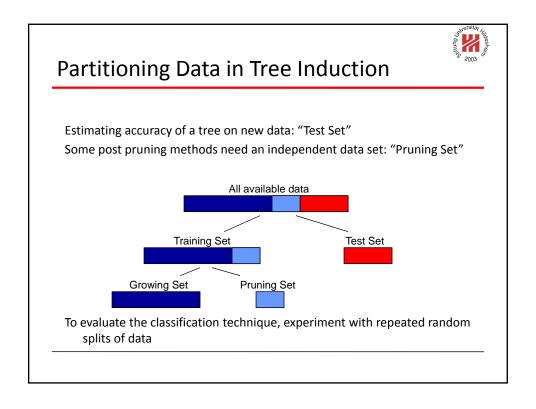


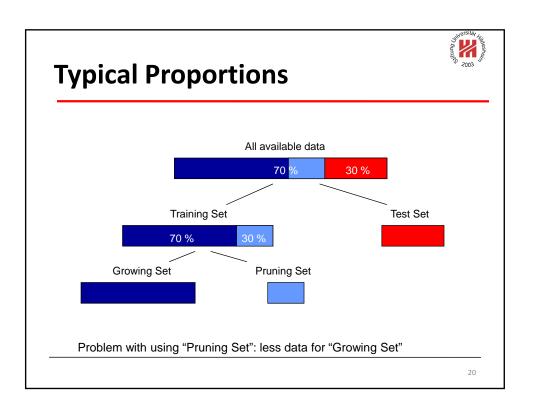
Quinlan 1978

Mingers 1978

Esposito et al. 1996

Elomaa & Kaariainen 2001







## Reduced Error Pruning (REP)

Use pruning set to estimate accuracy of sub-trees and accuracy at individual nodes

Let T be a sub-tree rooted at node v



Define:

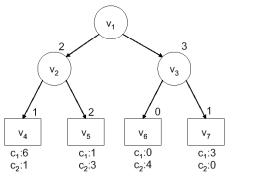
Gain from prunning at v=# misclassification in T-# misclassification at v

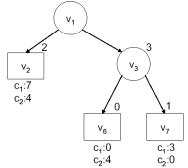
Repeat: prune at node with largest gain until until only negative gain nodes remain

"Bottom-up restriction": *T* can only be pruned if it does not contain a sub-tree with lower error than *T* 

#### **REP** example







$$E(T_{v_2}) = 3$$
,  $E(v_2) = 2$ ,  $E(T_{v_3}) = 1$ ,  $E(v_3) = 3$ .



# Real implementations

na	ame	ChAID	CART	ID3	C4.5
aı	uthor	Kass 1980	Breiman et al. 1984	Quinlan 1986	Quinlan 1993
Se	election	$\chi^2$	Gini index,	information gain	information gain ratio
m	easure		twoing index		
sp	olits	all	binary nominal,	complete	complete,
			binary quantitative,		binary nominal,
			binary bivariate quantitative		binary quantitative
st	opping	$\chi^2$ independence	minimum number	$\chi^2$ independence	lower bound on
cr	iterion	test	of cases/node	test	selection measure
pı	uning	none	error complexity pruning	pessimistic error pruning	pessimistic error pruning,
te	chnique				error based pruning



#### Example: C4.5

Simple depth-first construction.

**Uses Information Gain** 

Sorts Continuous Attributes at each node.

Needs entire data to fit in memory.

Unsuitable for Large Datasets.

Needs out-of-core sorting.

You can download the software from:

http://www.cse.unsw.edu.au/~quinlan/c4.5r8.tar.gz