

Machine Learning 2

2. (Advanced) Support Vector Machines (SVMs)

Lars Schmidt-Thieme

Information Systems and Machine Learning Lab (ISMLL)
Institute for Computer Science
University of Hildesheim, Germany





A. Advanced Supervised Learning

- Tue. 5.4. (1) A.1 Generalized Linear Models
- Tue. 12.4. (2) A.2 Gaussian Processes
- Tue. 19.4. (3) A.2b Gaussian Processes (ctd.)
- Tue. 26.4. (4) A.3 Advanced Support Vector Machines
 - Tue. 3.5. (5) A.4 Neural Networks
- Tue. 10.5. (6) A.5 Ensembles
- Tue. 17.5. (7) A.5b Ensembles (ctd.)
- Tue. 24.5. Pentecoste Break —
- Tue. 31.5. (8) A.6 Sparse Linear Models L1 regularization
- Tue. 7.6. (9) A.6b Sparse Linear Models L1 regularization (ctd.)
- Tue. 14.6. (10) A.7. Sparse Linear Models Further Methods

B. Complex Predictors

- Tue. 21.6. (11) B.1 Latent Dirichlet Allocation (LDA)
- Tue. 28.6. (12) B.2 Deep Learning
- Tue. 5.7. (13) Questions and Answers

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Outline

1. Stochastic (Sub)gradient Descent

2. Dual Coordinate Descent

3. The Adaptive Multi Hyperplane Machine

Stochastic (Sub)gradient Descent

2. Dual Coordinate Descent

3. The Adaptive Multi Hyperplane Machine

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SVM Optimization Problem / Slack Variables

minimize
$$\frac{1}{2}||\beta||^2 + \gamma \sum_{n=1}^{N} \xi_n$$

w.r.t. $y_i(\beta_0 + \beta^T x_n) \ge 1 - \xi_n, \quad n = 1, \dots, N$
 $\xi \ge 0$
 $\beta \in \mathbb{R}^p, \quad \beta_0 \in \mathbb{R}$



SVM Optimization Problem / Slack Variables

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$$\frac{1}{2}||\beta||^2 + \gamma \sum_{n=1}^{N} \xi_n$$

w.r.t. $y_i(\beta_0 + \beta^T x_n) \ge 1 - \xi_n, \quad n = 1, \dots, N$
 $\xi \ge 0$
 $\beta \in \mathbb{R}^p, \quad \beta_0 \in \mathbb{R}$

can be rewritten:

minimize
$$f(\beta) := \frac{1}{2} ||\beta||^2 + \gamma \sum_{n=1}^{N} \max(0, 1 - y_n(\beta_0 + \beta^T x_n))$$

$$\propto \frac{1}{N} \sum_{n=1}^{N} \max(0, 1 - y_n(\beta_0 + \beta^T x_n)) + \frac{1}{2} \lambda ||\beta||^2, \quad \lambda := \frac{\gamma}{N}$$



SVM Optimization Problem / Hinge Loss

can be rewritten (ctd.):

minimize
$$f(\beta) := \frac{1}{2} ||\beta||^2 + \gamma \sum_{n=1}^{N} \max(0, 1 - y_n(\beta_0 + \beta^T x_n))$$

$$\propto \frac{1}{N} \sum_{n=1}^{N} \max(0, 1 - y_n(\beta_0 + \beta^T x_n)) + \frac{1}{2} \lambda ||\beta||^2, \quad \lambda := \frac{\gamma}{N}$$

$$= \frac{1}{N} \sum_{n=1}^{N} \ell_{\text{hinge}}(y_n, \beta_0 + \beta^T x_n) + \frac{1}{2} \lambda ||\beta||^2$$

with

$$\ell_{\mathsf{hinge}}(y,\hat{y}) := \mathsf{max}(0,1-y\hat{y})$$



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(Sub)gradients

$$f(\beta) := \frac{1}{N} \sum_{n=1}^{N} \max(0, 1 - y_n(\beta_0 + \beta^T x_n)) + \frac{1}{2} \lambda ||\beta||^2$$
$$= \frac{1}{N} \sum_{\substack{n=1 \ y_n(\beta_0 + \beta^T x_n) < 1}}^{N} 1 - y_n(\beta_0 + \beta^T x_n) + \frac{1}{2} \lambda ||\beta||^2$$





(Sub)gradients

$$f(\beta) := \frac{1}{N} \sum_{n=1}^{N} \max(0, 1 - y_n(\beta_0 + \beta^T x_n)) + \frac{1}{2} \lambda ||\beta||^2$$

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subgradients:

$$\frac{\partial f}{\partial \beta} = \frac{1}{N} \sum_{\substack{n=1\\y_n(\beta_0 + \beta^T x_n) < 1}}^{N} -y_n x_n + \lambda \beta$$



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(Sub)gradients

$$f(\beta) := \frac{1}{N} \sum_{n=1}^{N} \max(0, 1 - y_n(\beta_0 + \beta^T x_n)) + \frac{1}{2} \lambda ||\beta||^2$$

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subgradients:

$$\frac{\partial f}{\partial \beta} = \frac{1}{N} \sum_{\substack{n=1\\y_n(\beta_0 + \beta^T x_n) < 1}}^{N} -y_n x_n + \lambda \beta$$

stochastic subgradients:

$$\frac{\partial f}{\partial \beta}|_{\mathcal{D}^{(t)}} = \frac{1}{|\mathcal{D}^{(t)}|} \sum_{\substack{(x,y) \in \mathcal{D}^{(t)} \\ y \neq \beta = 1, y \leq 1}}^{N} -yx + \lambda \beta, \quad \mathcal{D}^{(t)} \subseteq \mathcal{D}^{\mathsf{train}}, \mathsf{iteration} \ t$$

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Bound on Parameter Norm

The optimal parameters are bound from above:

$$||\beta^*|| \le \frac{1}{\sqrt{\lambda}}$$

Trivially,

$$\frac{1}{2}\lambda||\beta^*||^2 \le f(\beta^*) \le f(0) = 1$$

$$\rightsquigarrow ||\beta^*|| \le \frac{\sqrt{2}}{\sqrt{\lambda}}$$

[SSSS07] have a more complex proof to show the tighter bound (p. 4, end of proof of theorem 1).

Primal Estimated Subgradient Solver for SVMs (Pegasos)

▶ use stochastic (sub)gradient descent

$$\tilde{\beta}^{(t+1)} := \beta^{(t)} - \eta^{(t)} \frac{\partial f}{\partial \beta}|_{\mathcal{D}^{(t)}}$$

- ► use gradient sample size *K*
 - lacktriangle though no empirical evidence that K>1 has any benefits
- ▶ after each SGD step, reproject/rescale β :

$$\beta^{(t+1)} := \tilde{\beta}^{(t+1)} \frac{1}{\min(\sqrt{\lambda}, ||\tilde{\beta}^{(t+1)}||)}$$

▶ use fixed hyperbola schedule as learning rate:

$$\eta^{(t)} := \frac{1}{\lambda t}$$

▶ see [SSSS07]



Performance Comparison

Table 1 Training time in CDI seconds

Pegasos SVM-Perf SVM-Light									
	Pegasos	SVM-Perf	SVM-Light						
CCAT	2	77	20,075						
Covertype	6	85	25,514						
astro-ph	2	5	80						

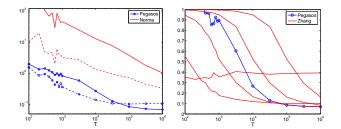


Figure 2. Comparisons of Pegasos to Norma (left) and Pegasos to stochastic gradient descent with a fixed learning rate (right) on the Astro-Physics datset. In the left plot, the solid lines designate the objective value and the dashed lines depict the loss on the test set.



Performance Comparison (2/2)

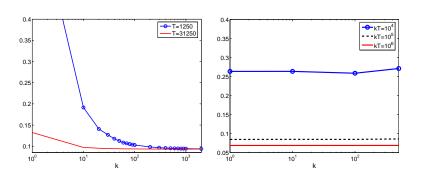


Figure 3. The effect of k on the objective value of Pegasos on the Astro-Physics dataset. Left: T is fixed. Right: kT is fixed.



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(Non-Linear) Kernels

SGD in the primal first works for linear kernels.

Any linear model can be kernelized by **representing instances in terms** of kernel features:

original feature representation:

$$x_n \in \mathbb{R}^M$$
, $n \in \{1, \ldots, N\}$

kernel feature representation:

$$\tilde{x}_n \in \mathbb{R}^N, x_{n,m} := k(x_n, x_m), \quad m \in \{1, \dots, N\}$$

then:

$$\hat{y}_{\text{linear}}(\tilde{x}_n; \beta) = \beta^T \tilde{x}_n = \sum_{m=1}^N \beta_m \tilde{x}_{n,m}$$

$$= \sum_{m=1}^N \alpha_m k(x_m, x_n) = \hat{y}_{\text{kernel } k}(x_n; \alpha), \quad \alpha_m := \beta_m$$

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Dual Problem

Remember, the dual problem was:

minimize
$$f(\alpha) := \frac{1}{2} \alpha^T Q \alpha - 1^T \alpha$$
, $Q_{n,m} := y_n y_m x_n^T x_m$
w.r.t. $\alpha \in [0, \frac{1}{N\lambda}]$

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Dual Problem

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w.r.t. $\alpha \in [0, \frac{1}{N\lambda}]$

coordinate descent w.r.t. coordinate α_n :

$$f_{n}(\alpha_{n}) := f(\alpha_{n}; \alpha_{-n}) \propto \frac{1}{2} Q_{n,n} \alpha_{n}^{2} + Q_{n,-n} \alpha_{-n} \alpha_{n} - \alpha_{n}$$

$$\frac{\partial f_{n}}{\partial \alpha_{n}} = Q_{n,n} \alpha_{n} + Q_{n,-n} \alpha_{-n} - 1 \stackrel{!}{=} 0$$

$$\approx \alpha_{n} = \frac{1 - Q_{n,-n} \alpha_{-n}}{Q_{n,n}}$$

possibly clip α_n :

$$\alpha_n = \max(0, \min(\frac{1}{N\lambda}, \frac{1 - Q_{n,-n}\alpha_{-n}}{Q_{n,n}}))$$

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Avoid Computing $Q_{n,-n}\alpha_{-n}$

$$\alpha_n^{(t+1)} := \frac{1 - Q_{n,-n} \alpha_{-n}^{(t)}}{Q_{n,n}}$$

$$= \frac{1 - Q_{n,-n} \alpha_{-n}^{(t)} + Q_{n,n} \alpha_{n}^{(t)}}{Q_{n,n}}$$

$$= \alpha_n^{(t)} - \frac{Q_{n,-n} \alpha_{-n}^{(t)} - 1}{Q_{n,n}}$$

$$= \alpha_n^{(t)} - \frac{y_n \hat{y}_n - 1}{Q_{n,n}}$$

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Avoid Computing $Q_{n,-n}\alpha_{-n}$

$$\alpha_n^{(t+1)} = \alpha_n^{(t)} - \frac{y_n \hat{y}_n - 1}{Q_{n,n}}$$

with

$$\hat{y}_n = \beta^T x_n$$

and due to

$$\beta = \sum_{n=1}^{N} \alpha_n y_n x_n$$

as only α_n changes:

$$\beta^{(t+1)} := \beta^{(t)} + (\alpha_n^{(t+1)} - \alpha_n^{(t)}) y_n x_n$$

- \blacktriangleright accelerates from O(N) to O(M)
- even $O(M_{nz})$ for sparse predictor vectors x (M_{nz} being the average number of nonzeros)

Jan Silversia

Performance Comparison

Table 2. On the right training time for a solver to reduce the primal objective value to within 1% of the optimal value; see (20). Time is in seconds. The method with the shortest running time is boldfaced. Listed on the left are the statistics of data sets: l is the number of instances and n is the number of features.

Data set	Data statistics			Li	near L1-S	VМ	Linear L2-SVM		
	l	n	# nonzeros	DCDL1	Pegasos	SVM ^{perf}	DCDL2	PCD	TRON
a9a	32,561	123	451,592	0.2	1.1	6.0	0.4	0.1	0.1
astro-physic	62,369	99,757	4,834,550	0.2	2.8	2.6	0.2	0.5	1.2
real-sim	72,309	20,958	3,709,083	0.2	2.4	2.4	0.1	0.2	0.9
news20	19,996	1,355,191	9,097,916	0.5	10.3	20.0	0.2	2.4	5.2
yahoo-japan	176,203	832,026	23,506,415	1.1	12.7	69.4	1.0	2.9	38.2
rcv1	677,399	47,236	49,556,258	2.6	21.9	72.0	2.7	5.1	18.6
yahoo-korea	460,554	3,052,939	156,436,656	8.3	79.7	656.8	7.1	18.4	286.1

Performance Comparison (2/2)

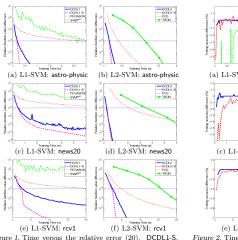


Figure 1. Time versus the relative error (20). DCDL1-S. DCDL2-S are DCDL1, DCDL2 with shrinking. The dotted line indicates the relative error 0.01. Time is in seconds.

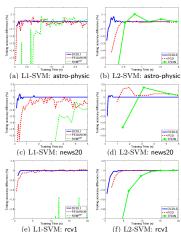


Figure 2. Time versus the difference of testing accuracy between the current model and the reference model (obtained using strict stopping conditions). Time is in seconds.



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Multi-Class SVM



multi-class SVM:

$$\begin{split} \hat{y}(x) &:= \arg\max_{y \in \mathcal{Y}} s_y(x) \\ s_y(x; \beta) &:= \beta_y^T x, \quad \beta_y \in \mathbb{R}^M \quad \forall y \in \mathcal{Y} = \{y_1, \dots, y_L\} \\ f(\beta) &:= \frac{1}{N} \sum_{n=1}^N \ell(y_n, x_n) + \frac{\lambda}{2} ||\beta||^2, \quad \beta := (\beta_{y_1}, \beta_{y_2}, \dots, \beta_{y_L}) \end{split}$$

margin-based loss:

$$\ell(y,x;\beta) := \max(0, \quad 1 + \max_{y' \in \mathcal{V}, y' \neq y} s_{y'}(x) - s_y(x))$$



Multi-Hyperplane Machine

multi-hyperplane score function:

$$s_y(x; \beta) := \max_{k=1,...,K} \beta_{y,k}^T x, \quad \beta_{y,k} \in \mathbb{R}^M, k \in \{1,...,K\}$$

margin-based loss:

$$\ell(y, x; \beta) := \max(0, 1 + \max_{y' \in \mathcal{Y}, y' \neq y} s_{y'}(x) - s_y(x))$$

relaxation / convex upper bound:

$$\ell(y_n, x_n; \beta, z_n) := \max(0, 1 + \max_{y' \in \mathcal{Y}, y' \neq y_n} s_{y'}(x_n) - \beta_{y_n, z_n}^T x_n)$$

- ▶ block coordinate descent / EM type training (β, z)
- ▶ use SGD to train β .



SGD for Training the Multi-Hyperplane Machine

relaxation / convex upper bound:

$$\ell(y_n,x_n;\beta,z_n) := \max(0, \quad 1 + \max_{y' \in \mathcal{Y}, y' \neq y_n} s_{y'}(x_n) - \beta_{y_n,z_n}^T x_n)$$

gradient:

$$\frac{\partial \ell}{\partial \beta_{y,k}}(y_n,x_n;z_n) = \begin{cases} x_n, & \text{if } (y,k) = \arg\max_{y' \in \mathcal{Y}, y' \neq y_n} \beta_{y',k'}^T x_n \\ -x_n, & \text{if } (y,k) = (y_n,z_n) \\ 0, & \text{otherwise} \end{cases}$$

Adaptive Multi-Hyperplane Machine:

- ▶ initialize $\beta \equiv 0$.
- ▶ if all $\beta_{y',k'}^T x < 0^T x = 0$, create a new hyperplane K + 1 with $\beta_{v,K+1} = 0.$

(conceptually infinite number of hyperplanes)

Performance Comparison



Table 3: Error rate and training time comparison with large-scale algorithms (RBF SVM is solved by LibSVM unless specified otherwise. Poly2 and LibSVM results are from [5]).

	Error rate (%)				Training time (seconds) ¹					
Datasets	AMM	AMM	Linear	Poly2	RBF	AMM	AMM	Linear	Poly2	RBF
	batch	online	(Pegasos)	SVM	SVM	batch	online	(Pegasos)	SVM	SVM
a9a	15.03 ± 0.11	16.44 ± 0.23	15.04 ± 0.07	14.94	14.97	2	0.2	1	2	99
ijenn	2.40 ± 0.11	3.02 ± 0.14	7.76 ± 0.19	2.16	1.31	2	0.1	1	11	27
webspam	4.50 ± 0.24	6.14 ± 1.08	7.28 ± 0.09	1.56	0.80	80	4	12	3,228	15,571
mnist_bin	0.53 ± 0.05	0.54 ± 0.03	2.03 ± 0.04	NA	0.43^{2}	3084	300	277	NA	2 days^2
mnist_mc	3.20 ± 0.16	3.36 ± 0.20	8.41 ± 0.11	NA	0.67^{3}	13864	1200	1180	NA	8 days ³
rcv1_bin	2.20 ± 0.01	2.21 ± 0.02	2.29 ± 0.01	NA	NA	1100	80	25	NA	NA
url	1.34 ± 0.21	2.87 ± 1.49	1.50 ± 0.39	NA	NA	400	24	100	NA	NA

¹ excludes data loading time.



² achieved by parallel training P-packSVMs on 512 processors; results from [28].

³ achieved by LaSVM; results from [12].



See [DLVW13] for

- ▶ two further scalable learning algorithms for non-linear SVMs,
- ► an implementation, and
- ► an evaluation

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Further Readings

► See the cited original papers.

References





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