

Modern Optimization Techniques

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Theory Background

Outline



- 1. Introduction
- 2. Convex Sets
- 3. Convex Functions
- 4. Optimization Problems

Outline

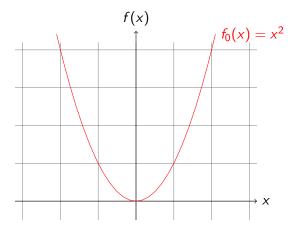


1. Introduction

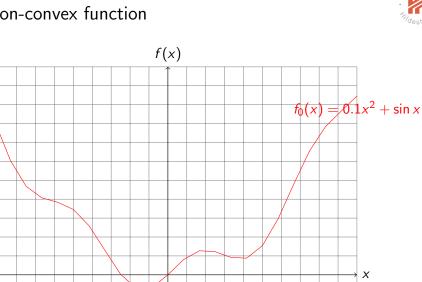
- 2. Convex Sets
- 3. Convex Functions
- 4. Optimization Problems

A convex function





A non-convex function



Lucas Rego Drumond, Information Systems and Machine Learning Lab (ISMLL), University of Hildesheim, Germany Theory Background

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Modern Optimization Techniques 1. Introduction

Convex Optimization Problem

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An optimization problem

$$\begin{array}{ll} \mbox{minimize} & f_0(x) \\ \mbox{subject to} & f_i(x) \leq 0, \quad i=1,\ldots,m \\ & Ax=b \end{array}$$

is said to be convex if $f_0, \ldots f_m$ are convex

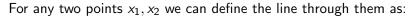
How do we know if a function is convex or not?

Outline



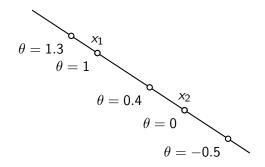
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Affine Sets



$$x= heta x_1+(1- heta)x_2 \qquad heta\in\mathbb{R}$$

Example:





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Affine Sets - Definition

An **affine set** is a set containing the line through any two distinct points in it

Examples:

- \mathbb{R}^n for $n \in \mathbb{N}^+$
- Solution set of linear equations $\{x|Ax = b\}$

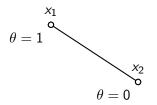
Convex Sets



The **line segment** between any two points x_1, x_2 is the set of all points:

$$x = \theta x_1 + (1 - \theta) x_2 \qquad 0 \le \theta \le 1$$

Example:

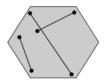


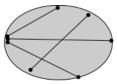
A convex set contains the line segment between any two points in the set

Modern Optimization Techniques 2. Convex Sets

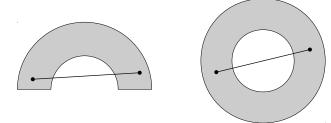


Convex Sets - Examples Convex Sets:





Non-convex Sets:



Convex Combination and Convex Hull



Given a set of points $x_1, \ldots x_n$, a **convex combination** is the set of points x such that

$$x = \theta_1 x_1 + \theta_2 x_2 + \ldots + \theta_n x_n$$
 $\theta_i \ge 0$ and $\sum_{i=1}^n \theta_i = 1$

A ${\bf convex}\ {\bf hull}$ of a set is the set of all convex combinations of points in the set

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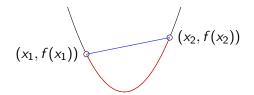
Convex Functions



A function $f : \mathbb{R}^n \to \mathbb{R}$ is convex iff:

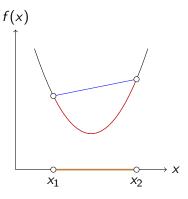
- ▶ dom f is a convex set
- ▶ for all $x_1, x_2 \in \text{dom } f$ and $0 \le \theta \le 1$ it satistfies

 $f(\theta x_1 + (1-\theta)x_2) \leq \theta f(x_1) + (1-\theta)f(x_2)$



Convex functions





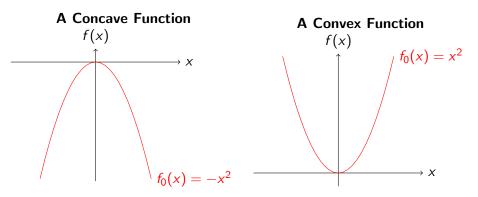
 $\bullet \ \theta x_1 + (1-\theta)x_2$

- $(\theta x_1 + (1 \theta)x_2, f(\theta x_1 + (1 \theta)x_2))$
- $(\theta x_1 + (1 \theta)x_2, \theta f(x_1) + (1 \theta)f(x_2))$

Convex Functions



A function f is called **concave** if -f is convex



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Strictly Convex Functions

A function $f : \mathbb{R}^n \to \mathbb{R}$ is strictly convex if:

- ▶ dom f is a convex set
- ▶ for all $x_1, x_2 \in \text{dom } f$, $x \neq y$ and $0 < \theta < 1$ it satistfies

$$f(\theta x_1 + (1-\theta)x_2) < \theta f(x_1) + (1-\theta)f(x_2)$$

Examples

Examples of Convex functions:

- ▶ affine: f(x) = ax + b, with dom $f = \mathbb{R}$ and $a, b \in \mathbb{R}$
- exponential: $f(x) = e^{ax}$, with $a \in \mathbb{R}$
- ▶ powers: $f(x) = x^a$, with dom $f = \mathbb{R}^{++}$ and $a \ge 1$ or $a \le 0$
- ▶ powers of absolute value: $f(x) = |x|^a$, with dom $f = \mathbb{R}$ and $a \ge 1$
- ▶ negative entropy: $f(x) = x \log x$, with dom $f = \mathbb{R}^{++}$

Examples of Concave Functions:

- ▶ affine: f(x) = ax + b, with dom $f = \mathbb{R}$ and $a, b \in \mathbb{R}$
- ▶ powers: $f(x) = x^a$, with dom $f = \mathbb{R}^{++}$ and $0 \le a \le 1$
- ▶ logarithm: $f(x) = \log x$, with dom $f = \mathbb{R}^{++}$









Examples of Convex functions:

All norms are convex!

- For $\mathbf{x} \in \mathbb{R}^n$:
- p-norms: $||\mathbf{x}||_p = (\sum_{i=1}^n |x_i|^p)^{\frac{1}{p}}$,
- ▶ for $p \ge 1$
- $\bullet \ ||\mathbf{x}||_{\infty} = \max_{k} |x_{k}|$
- Affine functions on vectors are also convex: $f(\mathbf{x}) = \mathbf{a}^T \mathbf{x} + b$

1st-order condition



f is differentiable if dom f is open and the gradient

$$\nabla f(\mathbf{x}) = \left(\frac{\partial f(\mathbf{x})}{\partial x_1}, \frac{\partial f(\mathbf{x})}{\partial x_2}, \dots, \frac{\partial f(\mathbf{x})}{\partial x_n}\right)$$

1st-order condition: a differentiable function f is convex iff

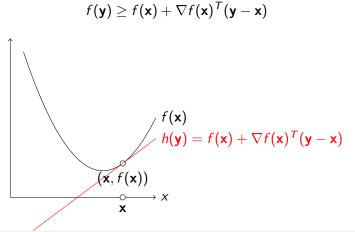
- ▶ dom f is a convex set
- ▶ for all $\mathbf{x}, \mathbf{y} \in \operatorname{dom} f$

$$f(\mathbf{y}) \geq f(\mathbf{x}) + \nabla f(\mathbf{x})^{\mathsf{T}}(\mathbf{y} - \mathbf{x})$$

1st-order condition

1st-order condition: a differentiable function f is convex iff

- ▶ dom f is a convex set
- for all $\mathbf{x}, \mathbf{y} \in \operatorname{dom} f$





2nd-order condition

f is twice differentiable if dom f is open and the Hessian $\nabla^2 f(x)$

$$abla^2 f(\mathbf{x})_{ij} = rac{\partial^2 f(\mathbf{x})}{\partial x_i \partial x_j}$$

2nd-order condition: a differentiable function f is convex iff

- ▶ dom f is a convex set
- ▶ for all $\mathbf{x} \in \operatorname{dom} f$

$$abla^2 f(\mathbf{x}) \succeq 0$$
 for all $\mathbf{x} \in \operatorname{dom} f$

• if $\nabla^2 f(\mathbf{x}) \succ 0$ for all $\mathbf{x} \in \text{dom } f$, then f is strictly convex





- There are a number of operations that preserve the convexity of a function
- If f can be obtained by applying those operations to a function, f is also convex

Nonnegative multiple:

- if f is convex and $a \ge 0$ then af is convex
- Example: $5x^2$ is convex since x^2 is convex

Sum:

- ▶ if f_1 and f_2 are convex functions then $f_1 + f_2$ is convex
- ► Example: f(x) = e^{3x} + x log x with dom f = ℝ⁺⁺ is convex since e^{3x} and x log x are convex

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Composition with the affine function:

- if f is convex then $f(A\mathbf{x} + \mathbf{b})$ is convex
- Example: norm of an affine function $||A\mathbf{x} + \mathbf{b}||$

Pointwise Maximum:

- ▶ if f₁,..., f_m are convex functions then f(x) = max{f₁(x),..., f_m(x)} is convex
- Example: $f(\mathbf{x}) = \max_{i=1,\dots,m} (a_i^T \mathbf{x} + b_i)$ is convex

Composition with scalar functions:

▶ if $g : \mathbb{R}^n \to \mathbb{R}$, $h : \mathbb{R} \to \mathbb{R}$ and

$$f(\mathbf{x}) = h(g(\mathbf{x}))$$

- ► *f* is convex if:
 - ▶ g is convex, h is convex and h is nondecreasing or
 - ▶ g is concave, h is convex and h is nonincreasing
- Examples:
 - $e^{g(\mathbf{x})}$ is convex if g is convex
 - $\frac{1}{g(\mathbf{x})}$ is convex if g is concave and positive







There are many different ways to establish the convexity of a function:

- Apply the definition
- Show that $\nabla^2 f(\mathbf{x}) \succeq 0$ for twice differentiable functions
- Show that f can be obtained from other convex functions by operations that preserve convexity

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Optimization Problem

$$\begin{array}{ll} \text{minimize} & f_0(\mathbf{x}) \\ \text{subject to} & f_i(\mathbf{x}) \leq 0, \quad i = 1, \dots, p \\ & h_i(\mathbf{x}) = 0, \quad i = 1, \dots, q \end{array}$$

- $f_0 : \mathbb{R}^n \to \mathbb{R}$ is the objective function
- $\mathbf{x} \in \mathbb{R}^n$ is the optimization variable
- ▶ $(f_i)_{i=1,...,m} : \mathbb{R}^n \to \mathbb{R}$ are the inequality constraint functions
- ▶ $(h_i)_{i=1,...,q} : \mathbb{R}^n \to \mathbb{R}$ are the equality constraint functions



Convex Optimization Problem An optimization problem

$$\begin{array}{ll} \text{minimize} & f_0(\mathbf{x}) \\ \text{subject to} & f_i(\mathbf{x}) \leq 0, \quad i = 1, \dots, p \\ & h_i(\mathbf{x}) = 0, \quad i = 1, \dots, q \end{array}$$

is said to be convex if f_0, \ldots, f_p are convex and h_1, \ldots, h_q are affine:

$$\begin{array}{ll} \text{minimize} & f_0(\mathbf{x}) \\ \text{subject to} & f_i(\mathbf{x}) \leq 0, \quad i = 1, \dots, p \\ & A\mathbf{x} = \mathbf{b} \end{array}$$

Practical Example: Household Spending

Suppose we have the following data about different households:

- Number of workers in the household (a_1)
- ► Household composition (*a*₂)
- Region (a_3)
- ► Gross normal weekly household income (*a*₄)
- ► Weekly household spending (y)

We want to create a model of the weekly household spending







Practical Example: Household Spending

If we have data about m households, we can represent it as:

$$A_{m,n} = \begin{pmatrix} 1 & a_{1,1} & a_{1,2} & a_{1,3} & a_{1,4} \\ 1 & a_{2,1} & a_{2,2} & a_{2,3} & a_{2,4} \\ \vdots & \vdots & \vdots & \vdots & \vdots \\ 1 & a_{m,1} & a_{m,2} & a_{m,3} & a_{m,4} \end{pmatrix} \mathbf{y} = \begin{pmatrix} y_1 \\ y_2 \\ \vdots \\ y_m \end{pmatrix}$$

We can model the household consumption is a linear combination of the household features with parameters β :

$$\hat{y}_i = \beta^T \mathbf{a_i} = \beta_0 1 + \beta_1 a_{i,1} + \beta_2 a_{i,2} + \beta_3 a_{i,3} + \beta_4 a_{i,4}$$



Practical Example: Household Spending

We have:

$$\begin{pmatrix} 1 & a_{1,1} & a_{1,2} & a_{1,3} & a_{1,4} \\ 1 & a_{2,1} & a_{2,2} & a_{2,3} & a_{2,4} \\ \vdots & \vdots & \vdots & \vdots & \vdots \\ 1 & a_{m,1} & a_{m,2} & a_{m,3} & a_{m,4} \end{pmatrix} \cdot \begin{pmatrix} \beta_0 \\ \beta_1 \\ \beta_2 \\ \beta_3 \\ \beta_4 \end{pmatrix} \approx \begin{pmatrix} y_1 \\ y_2 \\ \vdots \\ y_m \end{pmatrix}$$

We want to find parameters β such that the measured error of the predictions is minimal:

$$\sum_{i=1}^{m} (\beta^{\mathsf{T}} \mathbf{a}_{\mathsf{i}} - y_i)^2 = ||A\beta - \mathbf{y}||_2^2$$



The Least Squares Problem

minimize
$$||A\beta - \mathbf{y}||_2^2$$

$$||Aeta - \mathbf{y}||_2^2 = (Aeta - \mathbf{y})^T (Aeta - \mathbf{y})$$

$$\frac{d}{d\beta}(A\beta - \mathbf{y})^T(A\beta - \mathbf{y}) = 2A^T(A\beta - \mathbf{y})$$

$$2A^{T}(A\beta - \mathbf{y}) = 0$$
$$A^{T}A\beta - A^{T}\mathbf{y} = 0$$
$$A^{T}A\beta = A^{T}\mathbf{y}$$
$$\beta = (A^{T}A)^{-1}A^{T}\mathbf{y}$$

The Least Squares Problem





- Convex Problem!
- Analytical solution: $\beta^* = (A^T A)^{-1} A^T \mathbf{y}$
- Often applied for data fitting
- $A\beta \mathbf{y}$ is usually called the residual or error
- Extensions like the regularized least squares

Practical Example: Household Location

Suppose we have the following data about different households:

- Number of workers in the household (a_1)
- ► Household composition (*a*₂)
- ▶ Weekly household spending (*a*₃)
- ► Gross normal weekly household income (*a*₄)
- **Region** (y): North y = 1 or south y = 0

We want to create a model of the location of the household



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Practical Example: Household Location

If we have data about m households, we can represent it as:

$$A_{m,n} = \begin{pmatrix} 1 & a_{1,2} & \dots & a_{1,n} \\ 1 & a_{2,2} & \dots & a_{2,n} \\ \vdots & \vdots & \vdots & \vdots \\ 1 & a_{m,2} & \dots & a_{m,n} \end{pmatrix} \mathbf{y} = \begin{pmatrix} y_1 \\ y_2 \\ \vdots \\ y_m \end{pmatrix}$$

We can model the household location is a linear combination of the household features with parameters β :

$$\hat{y}_i = \sigma(\beta^T \mathbf{a_i}) = \sigma(\beta_0 1 + \beta_1 a_{i,1} + \beta_2 a_{i,2} + \beta_3 a_{i,3} + \beta_4 a_{i,4})$$

here: $\sigma(x) = \frac{1}{1 + e^{(-x)}}$





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The Logistic Regression

The logistic regression learning problem is

maximize
$$\sum_{i=1}^{m} y_i \log \sigma(\beta^T \mathbf{a_i}) + (1 - y_i) \log(1 - \sigma(\beta^T \mathbf{a_i}))$$

$$A_{m,n} = \begin{pmatrix} 1 & a_{1,1} & a_{1,2} & a_{1,3} & a_{1,4} \\ 1 & a_{2,1} & a_{2,2} & a_{2,3} & a_{2,4} \\ \vdots & \vdots & \vdots & \vdots & \vdots \\ 1 & a_{m,1} & a_{m,2} & a_{m,3} & a_{m,4} \end{pmatrix} \mathbf{y} = \begin{pmatrix} y_1 \\ y_2 \\ \vdots \\ y_m \end{pmatrix}$$



Linear Programming

minimize
$$\mathbf{c}^T \boldsymbol{\beta}$$

subject to $\mathbf{a}_i^T \boldsymbol{\beta} \leq b_i \quad i = 1, \dots, m$

- No simple analytical solution
- There are reliable algorithms available:
 - Simplex
 - Interior Points Method