# Modern Optimization Techniques <br> 1. Theory 

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## Syllabus

| Mon. 30.10. | (0) | 0. Overview |
| :---: | :---: | :---: |
|  |  | 1. Theory |
| Mon. 6.11. | (1) | 1. Convex Sets and Functions |
|  |  | 2. Unconstrained Optimization |
| Mon. 13.11. | (2) | 2.1 Gradient Descent |
| Mon. 20.11. | (3) | 2.2 Stochastic Gradient Descent |
| Mon. 27.11. | (4) | 2.3 Newton's Method |
| Mon. 4.12. | (5) | 2.4 Quasi-Newton Methods |
| Mon. 11.12. | (6) | 2.5 Subgradient Methods |
| Mon. 18.12. | (7) | 2.6 Coordinate Descent <br> - Christmas Break - |
| Mon. 8.1. | (8) | 3. Equality Constrained Optimization <br> 3.1 Duality |
| Mon. 15.1. | (9) | 3.2 Methods |
|  |  | 4. Inequality Constrained Optimization |
| Mon. 22.1. | (10) | 4.1 Primal Methods |
| Mon. 29.1. | (11) | 4.2 Barrier and Penalty Methods |
| Mon. 5.2. | (12) | 4.3 Cutting Plane Methods |

## Outline

1. Introduction
2. Convex Sets

## 3. Convex Functions

4. Optimization Problems

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## A convex function



## A non-convex function

$$
f(x)
$$



## Convex Optimization Problem

## An optimization problem

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\begin{aligned}
\operatorname{minimize} & f(x) \\
\text { subject to } & h_{q}(x) \leq 0, \quad q=1, \ldots, Q \\
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is said to be convex if $f, h_{1} \ldots h_{Q}$ are convex How do we know if a
function is convex or not?

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Example:

$x_{2}$
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## Examples:

- $\mathbb{R}^{N}$ for $N \in \mathbb{N}^{+}$
- Solution set of linear equations $\left\{x \in \mathbb{R}^{N} \mid A x=b\right\}$


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Example:


A convex set contains the line segment between any two points in the set.

## Convex Sets - Examples

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Convex Sets:


Non-convex Sets:


## Convex Combination and Convex Hull

 (standard) simplex:$$
\Delta^{N}:=\left\{\theta \in \mathbb{R}^{N} \mid \theta_{n} \geq 0, n=1, \ldots, N ; \sum_{n=1}^{N} \theta_{n}=1\right\}
$$

convex combination of some points $x_{1}, \ldots x_{N} \in \mathbb{R}^{M}$ : any point $x$ with

$$
x=\theta_{1} x_{1}+\theta_{2} x_{2}+\ldots+\theta_{N} x_{N}, \quad \theta \in \Delta^{N}
$$

convex hull of a set $X \subseteq \mathbb{R}^{M}$ of points:

$$
\operatorname{conv}(X):=\left\{\theta_{1} x_{1}+\theta_{2} x_{2}+\ldots+\theta_{N} x_{N} \mid N \in \mathbb{N}, x_{1}, \ldots, x_{N} \in X, \theta \in \Delta^{N}\right\}
$$

i.e., the set of all convex combinations of points in $X$.

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f\left(\theta x_{1}+(1-\theta) x_{2}\right) \leq \theta f\left(x_{1}\right)+(1-\theta) f\left(x_{2}\right)
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(the function is below of its secant segments/chords.)

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## How are Convex Functions Related to Convex Sets?

epigraph of a function $f: X \rightarrow \mathbb{R}, X \subseteq \mathbb{R}^{N}$ :

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$f$ is convex (as function) $\Longleftrightarrow$ epi(f) is convex (as set).
proof is straight-forward (try it!)

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- logarithm: $f(x)=\log x$, with $\operatorname{dom} f=\mathbb{R}^{+}$


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All norms are convex!

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Affine functions on vectors are also convex: $f(\mathbf{x})=\mathbf{a}^{T} \mathbf{x}+b$

## 1st-Order Condition

$f$ is differentiable if $\operatorname{dom} f$ is open and the gradient

$$
\nabla f(\mathbf{x})=\left(\frac{\partial f(\mathbf{x})}{\partial x_{1}}, \frac{\partial f(\mathbf{x})}{\partial x_{2}}, \ldots, \frac{\partial f(\mathbf{x})}{\partial x_{n}}\right)
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- for all $\mathbf{x}, \mathbf{y} \in \operatorname{dom} f$

$$
f(\mathbf{y}) \geq f(\mathbf{x})+\nabla f(\mathbf{x})^{T}(\mathbf{y}-\mathbf{x})
$$

(the function is above any of its tangents.)

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## 1st-Order Condition / Proof

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& f(y) \geq \frac{f(x+t(y-x))-f(x)}{t}+f(x) \xrightarrow{t \rightarrow 0^{+}} \nabla f(x)^{T}(y-x)+f(x)
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& \rightsquigarrow \theta f(x)+(1-\theta) f(y) \geq f(z)+\nabla f(z)^{T}(\theta x+(1-\theta) y)-\nabla f(z)^{T} z \\
& \quad=f(z)+\nabla f(z)^{T} z-\nabla f(z)^{T} z=f(z)=f(\theta x+(1-\theta) y)
\end{aligned}
$$

## 1st-Order Condition / Strict Variant

strict 1st-order condition: a differentiable function $f$ is strictly convex iff

- $\operatorname{dom} f$ is a convex set
- for all $\mathbf{x}, \mathbf{y} \in \operatorname{dom} f$

$$
f(\mathbf{y})>f(\mathbf{x})+\nabla f(\mathbf{x})^{T}(\mathbf{y}-\mathbf{x})
$$

## Global Minima

Let $\operatorname{dom} f=X$ be convex.

$$
f: X \rightarrow \mathbb{R} \text { convex } \Leftrightarrow f(\mathbf{y}) \geq f(\mathbf{x})+\nabla f(\mathbf{x})^{T}(\mathbf{y}-\mathbf{x}) \quad \forall \mathbf{x}, \mathbf{y}
$$

Consequence: Points $x$ with $\nabla f(x)=0$ are (equivalent) global minima.

- minima form a convex set
- if $f$ is strictly convex: there is exactly one global minimum $x^{*}$.


## 2nd-Order Condition

$f$ is twice differentiable if dom $f$ is open and the Hessian $\nabla^{2} f(x)$

$$
\nabla^{2} f(\mathbf{x})_{n, m}=\frac{\partial^{2} f(\mathbf{x})}{\partial x_{n} \partial x_{m}}
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exists everywhere.

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\nabla^{2} f(\mathbf{x}) \succeq 0 \quad \text { for all } \mathbf{x} \in \operatorname{dom} f
$$

- if $\nabla^{2} f(\mathbf{x}) \succ 0$ for all $\mathbf{x} \in \operatorname{dom} f$, then $f$ is strictly convex
- the converse is not true, e.g., $f(x)=x^{4}$ is strictly convex, but has 0 derivative at 0 .


## Positive Semidefinite Matrices (A Reminder)

A symmetric matrix $A \in \mathbb{R}^{n \times n}$ is positive semidefinite $(A \succeq 0)$ :

$$
x^{T} A x \geq 0, \quad \forall x \in \mathbb{R}^{N}
$$

Equivalent:
(i) all eigenvalues of $A$ are $\geq 0$.
(ii) $A=B^{T} B$ for some matrix $B$

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x^{T} A x \geq 0, \quad \forall x \in \mathbb{R}^{N}
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Equivalent:
(i) all eigenvalues of $A$ are $\geq 0$.
(ii) $A=B^{T} B$ for some matrix $B$

A symmetric matrix $A \in \mathbb{R}^{N \times N}$ is positive definite $(A \succ 0)$ :

$$
x^{T} A x>0, \quad \forall x \in \mathbb{R}^{N} \backslash\{0\}
$$

Equivalent:
(i) all eigenvalues of $A$ are $>0$.
(ii) $A=B^{T} B$ for some nonsingular matrix $B$

## Recognizing Convex Functions

- There are a number of operations that preserve the convexity of a function.
- If $f$ can be obtained by applying those operations to a convex function, $f$ is also convex.


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## Sum:

- if $f_{1}$ and $f_{2}$ are convex functions then $f_{1}+f_{2}$ is convex.
- Example: $f(x)=e^{3 x}+x \log x$ with $\operatorname{dom} f=\mathbb{R}^{+}$is convex since $e^{3 x}$ and $x \log x$ are convex


## Recognizing Convex Functions

## Composition with the affine function:

- if $f$ is convex then $f(A \mathbf{x}+\mathbf{b})$ is convex.


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## Pointwise Maximum:

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## Pointwise Maximum:

- if $f_{1}, \ldots, f_{m}$ are convex functions then $f(\mathbf{x})=\max \left\{f_{1}(\mathbf{x}), \ldots, f_{m}(\mathbf{x})\right\}$ is convex.
- Example: $f(\mathbf{x})=\max _{i=1, \ldots, l}\left(a_{i}^{T} \mathbf{x}+b_{i}\right)$ is convex


## Recognizing Convex Functions

## Composition with scalar functions:

- if $g: \mathbb{R}^{N} \rightarrow \mathbb{R}, h: \mathbb{R} \rightarrow \mathbb{R}$ and

$$
f(\mathbf{x})=h(g(\mathbf{x}))
$$

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f(\mathbf{x})=h(g(\mathbf{x}))
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- $f$ is convex if:
- $g$ is convex, $h$ is convex and nondecreasing or
- $g$ is concave, $h$ is convex and nonincreasing


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- $f$ is convex if:
- $g$ is convex, $h$ is convex and nondecreasing or
- $g$ is concave, $h$ is convex and nonincreasing
- Examples:
- $e^{g(x)}$ is convex if $g$ is convex
- $\frac{1}{g(x)}$ is convex if $g$ is concave and positive


## Recognizing Convex Functions

There are many different ways to establish the convexity of a function:

- Apply the definition


## Recognizing Convex Functions

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- Apply the definition
- Show that $\nabla^{2} f(\mathbf{x}) \succeq 0$ for twice differentiable functions


## Recognizing Convex Functions

There are many different ways to establish the convexity of a function:

- Apply the definition
- Show that $\nabla^{2} f(\mathbf{x}) \succeq 0$ for twice differentiable functions
- Show that $f$ can be obtained from other convex functions by operations that preserve convexity


## Outline

## 1. Introduction

## 2. Convex Sets

3. Convex Functions

## 4. Optimization Problems

## Optimization Problem

$$
\begin{aligned}
\operatorname{minimize} & f(\mathbf{x}) \\
\text { subject to } & g_{p}(\mathbf{x})=0, \quad p=1, \ldots, P \\
& h_{q}(\mathbf{x}) \leq 0, \quad q=1, \ldots, Q
\end{aligned}
$$

- $f: \mathbb{R}^{N} \rightarrow \mathbb{R}$ is the objective function
- $\mathbf{x} \in \mathbb{R}^{N}$ are the optimization variables
- $g_{p}: \mathbb{R}^{N} \rightarrow \mathbb{R}, p=1, \ldots, P$ are the equality constraint functions
- $h_{q}: \mathbb{R}^{N} \rightarrow \mathbb{R}, q=1, \ldots, Q$ are the inequality constraint functions


## Convex Optimization Problem An optimization problem

$$
\begin{aligned}
\operatorname{minimize} & f(\mathbf{x}) \\
\text { subject to } & g_{p}(\mathbf{x})=0, \quad p=1, \ldots, P \\
& h_{q}(\mathbf{x}) \leq 0, \quad q=1, \ldots, Q
\end{aligned}
$$

is said to be convex if

- $f$ is convex,
- $g_{1}, \ldots, g_{P}$ are affine and
- $h_{1}, \ldots h_{Q}$ are convex.

$$
\begin{aligned}
\operatorname{minimize} & f(\mathbf{x}) \\
\text { subject to } & A \mathbf{x}=a \\
& h_{q}(\mathbf{x}) \leq 0, \quad q=1, \ldots, Q
\end{aligned}
$$

## Example 1: Linear Regression / Household Spending

Suppose we have the following data about different households:

- Number of workers in the household ( $a_{1}$ )
- Household composition ( $a_{2}$ )
- Region ( $a_{3}$ )
- Gross normal weekly household income (a4)
- Weekly household spending (y)


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- Household composition ( $a_{2}$ )
- Region ( $a_{3}$ )
- Gross normal weekly household income (a4)
- Weekly household spending (y)

We want to create a model of the weekly household spending

## Example 1: Linear Regression

If we have data about $M$ households, we can represent it as:

$$
A=\left(\begin{array}{ccccc}
1 & a_{1,1} & a_{1,2} & a_{1,3} & a_{1,4} \\
1 & a_{2,1} & a_{2,2} & a_{2,3} & a_{2,4} \\
\vdots & \vdots & \vdots & \vdots & \vdots \\
1 & a_{M, 1} & a_{M, 2} & a_{M, 3} & a_{M, 4}
\end{array}\right), \quad \mathbf{y}=\left(\begin{array}{c}
y_{1} \\
y_{2} \\
\vdots \\
y_{M}
\end{array}\right)
$$

## Example 1: Linear Regression

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\vdots & \vdots & \vdots & \vdots & \vdots \\
1 & a_{M, 1} & a_{M, 2} & a_{M, 3} & a_{M, 4}
\end{array}\right), \quad \mathbf{y}=\left(\begin{array}{c}
y_{1} \\
y_{2} \\
\vdots \\
y_{M}
\end{array}\right)
$$

We can model the household consumption is a linear combination of the household features with parameters $\beta$ :
$\hat{y}_{m}=\beta^{T} A_{m, .}=\beta_{0} 1+\beta_{1} a_{m, 1}+\beta_{2} a_{m, 2}+\beta_{3} a_{m, 3}+\beta_{4} a_{m, 4}, \quad m=1, \ldots, M$

## Example 1: Linear Regression

We have:

$$
\left(\begin{array}{ccccc}
1 & a_{1,1} & a_{1,2} & a_{1,3} & a_{1,4} \\
1 & a_{2,1} & a_{2,2} & a_{2,3} & a_{2,4} \\
\vdots & \vdots & \vdots & \vdots & \vdots \\
1 & a_{M, 1} & a_{M, 2} & a_{M, 3} & a_{M, 4}
\end{array}\right) \cdot\left(\begin{array}{c}
\beta_{0} \\
\beta_{1} \\
\beta_{2} \\
\beta_{3} \\
\beta_{4}
\end{array}\right) \approx\left(\begin{array}{c}
y_{1} \\
y_{2} \\
\vdots \\
y_{M}
\end{array}\right)
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\vdots & \vdots & \vdots & \vdots & \vdots \\
1 & a_{M, 1} & a_{M, 2} & a_{M, 3} & a_{M, 4}
\end{array}\right) \cdot\left(\begin{array}{c}
\beta_{0} \\
\beta_{1} \\
\beta_{2} \\
\beta_{3} \\
\beta_{4}
\end{array}\right) \approx\left(\begin{array}{c}
y_{1} \\
y_{2} \\
\vdots \\
y_{M}
\end{array}\right)
$$

We want to find parameters $\beta$ such that the measured error of the predictions is minimal:

$$
\sum_{m=1}^{M}\left(\beta^{T} A_{m, .}-y_{m}\right)^{2}=\|A \beta-\mathbf{y}\|_{2}^{2}
$$

# Example 1: Linear Regression / Least Squares Problem 

deshos

$$
\operatorname{minimize} \quad\|A \beta-\mathbf{y}\|_{2}^{2}
$$

$$
\|A \beta-\mathbf{y}\|_{2}^{2}=(A \beta-\mathbf{y})^{T}(A \beta-\mathbf{y})
$$

## Example 1: Linear Regression / Least Squares Problem

$$
\begin{gathered}
\text { minimize } \quad\|A \beta-\mathbf{y}\|_{2}^{2} \\
\|A \beta-\mathbf{y}\|_{2}^{2}=(A \beta-\mathbf{y})^{T}(A \beta-\mathbf{y}) \\
\frac{d}{d \beta}(A \beta-\mathbf{y})^{T}(A \beta-\mathbf{y})=2 A^{T}(A \beta-\mathbf{y})
\end{gathered}
$$

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2 A^{T}(A \beta-\mathbf{y})=0 \\
A^{T} A \beta-A^{T} \mathbf{y}=0 \\
A^{T} A \beta=A^{T} \mathbf{y}
\end{gathered}
$$

## Example 1: Linear Regression / Least Squares Problem

$$
\text { minimize } \quad\|A \beta-y\|_{2}^{2}
$$

$$
\begin{aligned}
&\|A \beta-\mathbf{y}\|_{2}^{2}=(A \beta-\mathbf{y})^{T}(A \beta-\mathbf{y}) \\
& \frac{d}{d \beta}(A \beta-\mathbf{y})^{T}(A \beta-\mathbf{y})=2 A^{T}(A \beta-\mathbf{y}) \\
& 2 A^{T}(A \beta-\mathbf{y})=0 \\
& A^{T} A \beta-A^{T} \mathbf{y}=0 \\
& A^{T} A \beta=A^{T} \mathbf{y} \\
& \beta=\left(A^{T} A\right)^{-1} A^{T} \mathbf{y}
\end{aligned}
$$

## Example 1: Linear Regression / Least Squares Problem

$$
\text { minimize } \quad\|A \beta-\mathbf{y}\|_{2}^{2}
$$

## Example 1: Linear Regression / Least Squares Problem

$$
\text { minimize } \quad\|A \beta-\mathbf{y}\|_{2}^{2}
$$

- Convex Problem!
- Analytical solution: $\beta^{*}=\left(A^{T} A\right)^{-1} A^{T} \mathbf{y}$
- Often applied for data fitting
- $A \beta-\mathbf{y}$ is usually called the residual or error
- Extensions such as regularized least squares


## Example 2: Linear Classification / Household Location

Suppose we have the following data about different households:

- Number of workers in the household ( $a_{1}$ )
- Household composition ( $a_{2}$ )
- Weekly household spending ( $a_{3}$ )
- Gross normal weekly household income ( $a_{4}$ )
- Region (y): north $y=1$ or south $y=0$


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- Weekly household spending ( $a_{3}$ )
- Gross normal weekly household income ( $a_{4}$ )
- Region (y): north $y=1$ or south $y=0$

We want to create a model of the location of the household

## Example 2: Linear Classification

If we have data about $M$ households, we can represent it as:

$$
A=\left(\begin{array}{cccc}
1 & a_{1,1} & \ldots & a_{1,4} \\
1 & a_{2,1} & \ldots & a_{2,4} \\
\vdots & \vdots & \vdots & \vdots \\
1 & a_{M, 1} & \cdots & a_{M, 4}
\end{array}\right), \quad \mathbf{y}=\left(\begin{array}{c}
y_{1} \\
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\end{array}\right)
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\vdots & \vdots & \vdots & \vdots \\
1 & a_{M, 1} & \cdots & a_{M, 4}
\end{array}\right), \quad \mathbf{y}=\left(\begin{array}{c}
y_{1} \\
y_{2} \\
\vdots \\
y_{M}
\end{array}\right)
$$

We can model the probability of the household location to be north $(y=1)$ as a linear combination of the household features with parameters $\beta$ :

$$
\begin{aligned}
\hat{y}_{m} & =\sigma\left(\beta^{\top} A_{m,}\right) \\
& =\sigma\left(\beta_{0} 1+\beta_{1} a_{m, 1}+\beta_{2} a_{m, 2}+\beta_{3} a_{m, 3}+\beta_{4} a_{m, 4}\right), \quad m=1, \ldots, M
\end{aligned}
$$

where: $\sigma(x):=\frac{1}{1+e^{-x}}$ (logistic function)

## Example 2: Linear Classification / Logistic Regression

The logistic regression learning problem is

$$
\begin{aligned}
\operatorname{maximize} & \sum_{m=1}^{M} y_{m} \log \sigma\left(\beta^{T} A_{m, .}\right)+\left(1-y_{m}\right) \log \left(1-\sigma\left(\beta^{T} A_{m, .}\right)\right) \\
A= & \left(\begin{array}{ccccc}
1 & a_{1,1} & a_{1,2} & a_{1,3} & a_{1,4} \\
1 & a_{2,1} & a_{2,2} & a_{2,3} & a_{2,4} \\
\vdots & \vdots & \vdots & \vdots & \vdots \\
1 & a_{M, 1} & a_{M, 2} & a_{M, 3} & a_{M, 4}
\end{array}\right), \quad \mathbf{y}=\left(\begin{array}{c}
y_{1} \\
y_{2} \\
\vdots \\
y_{M}
\end{array}\right)
\end{aligned}
$$

## Example 3: Linear Programming

$$
\begin{aligned}
& \text { minimize } \mathbf{c}^{\top} \mathbf{x} \\
& \text { subject to } \mathbf{a}_{q}^{T} \mathbf{x} \leq b_{q} \quad q=1, \ldots, Q \\
& \mathbf{x} \geq 0 \\
& \mathbf{c}, \mathbf{a}_{q}, \mathbf{x} \in \mathbb{R}^{N}, b_{q} \in \mathbb{R}
\end{aligned}
$$

- No simple analytical solution.
- There are reliable algorithms available:
- Simplex
- Interior Points Method


## Summary (1/2)

- Convex sets are closed under line segments (convex combinations).
- Convex functions are defined on a convex domain and
- are below any of their secant segments / chords (definition)
- are globally above their tangents (1st-order condition)
- have a positive semidefinite Hessian (2nd-order condition)
- For convex functions, points with vanishing gradients are (equivalent) global minima.
- Operations that preserve convexity:
- scaling with a nonnegative constant
- sums
- pointwise maximum
- composition with an affine function
- composition with a nondecreasing convex scalar function
- composition of a nonincreasing convex scalar function with a concave function
- esp. - $g$ for a concave $g$


## Summary (2/2)

- General optimization problems consist of
- an objective function,
- equality constraints.
- inequality constraints and
- Convex optimization problems have
- a convex objective function,
- affine equality constraints and
- convex inequality constraints.
- Examples for convex optimization problems:
- linear regression / least squares
- linear classification / logistic regression
- linear programming
- quadratic programming


## Further Readings

- Convex sets:
- Boyd and Vandenberghe [2004], chapter 2, esp. 2.1
- see also ch. 2.2 and 2.3
- Convex functions:
- Boyd and Vandenberghe [2004], chapter 3, esp. 3.1.1-7, 3.2.1-5
- Convex optimization:
- Boyd and Vandenberghe [2004], chapter 4, esp. 4.1-3
- see also ch. 4.4


## References I

Stephen Boyd and Lieven Vandenberghe. Convex Optimization. Cambridge Univ Press, 2004.

