

# Modern Optimization Techniques 1. Theory

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Syllabus



Mon.	30.10.	(0)	0. Overview
Mon.	6.11.	(1)	<ol> <li>Theory</li> <li>Convex Sets and Functions</li> </ol>
Mon. Mon. Mon. Mon. Mon.	13.11. 20.11. 27.11. 4.12. 11.12. 18.12.	(2) (3) (4) (5) (6) (7)	<ul> <li>2. Unconstrained Optimization</li> <li>2.1 Gradient Descent</li> <li>2.2 Stochastic Gradient Descent</li> <li>2.3 Newton's Method</li> <li>2.4 Quasi-Newton Methods</li> <li>2.5 Subgradient Methods</li> <li>2.6 Coordinate Descent</li> <li>Christmas Break —</li> </ul>
Mon. Mon.	8.1. 15.1.	(8) (9)	<ol> <li>Equality Constrained Optimization</li> <li>Duality</li> <li>Methods</li> </ol>
Mon. Mon. Mon.	22.1. 29.1. 5.2.	(10) (11) (12)	<ul><li>4. Inequality Constrained Optimization</li><li>4.1 Primal Methods</li><li>4.2 Barrier and Penalty Methods</li><li>4.3 Cutting Plane Methods</li></ul>

# Outline



- 1. Introduction
- 2. Convex Sets
- 3. Convex Functions
- 4. Optimization Problems

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#### 1. Introduction

- 2. Convex Sets
- 3. Convex Functions
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# A convex function





# A non-convex function





Modern Optimization Techniques 1. Introduction

# Convex Optimization Problem

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#### An optimization problem

$$\begin{array}{ll} \mbox{minimize} & f(x) \\ \mbox{subject to} & h_q(x) \leq 0, \quad q=1,\ldots,Q \\ & Ax=b \end{array}$$

is said to be convex if  $f, h_1 \dots h_Q$  are convex

Modern Optimization Techniques 1. Introduction

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is said to be convex if  $f, h_1 \dots h_Q$  are convex How do we know if a

function is convex or not?

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Example:

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#### Examples:

- ▶  $\mathbb{R}^N$  for  $N \in \mathbb{N}^+$
- ► Solution set of linear equations  $\{x \in \mathbb{R}^N \mid Ax = b\}$



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Example:



# A **convex set** contains the line segment between any two points in the set.



# Convex Sets - Examples Convex Sets:







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#### Non-convex Sets:





# Convex Combination and Convex Hull (standard) simplex:

$$\Delta^{\mathsf{N}} := \{ \theta \in \mathbb{R}^{\mathsf{N}} \mid \theta_n \ge 0, n = 1, \dots, \mathsf{N}; \sum_{n=1}^{\mathsf{N}} \theta_n = 1 \}$$

. .

**convex combination** of some points  $x_1, \ldots x_N \in \mathbb{R}^M$ : any point x with

$$x = \theta_1 x_1 + \theta_2 x_2 + \ldots + \theta_N x_N, \quad \theta \in \Delta^N$$

**convex hull** of a set  $X \subseteq \mathbb{R}^M$  of points:

 $\operatorname{conv}(X) := \{\theta_1 x_1 + \theta_2 x_2 + \ldots + \theta_N x_N \mid N \in \mathbb{N}, x_1, \ldots, x_N \in X, \theta \in \Delta^N\}$ 

i.e., the set of all convex combinations of points in X.

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## How are Convex Functions Related to Convex Sets?

**epigraph** of a function  $f : X \to \mathbb{R}, X \subseteq \mathbb{R}^N$ :

$$\operatorname{epi}(f) := \{(x, y) \in X \times \mathbb{R} \mid y \ge f(x)\}$$



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f is convex (as function)  $\iff epi(f)$  is convex (as set).

proof is straight-forward (try it!)

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 Immediate consequence of the triangle inequality and absolute homogeneity.



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Affine functions on vectors are also convex:  $f(\mathbf{x}) = \mathbf{a}^T \mathbf{x} + b$ 

f is **differentiable** if dom f is open and the gradient

$$\nabla f(\mathbf{x}) = \left(\frac{\partial f(\mathbf{x})}{\partial x_1}, \frac{\partial f(\mathbf{x})}{\partial x_2}, \dots, \frac{\partial f(\mathbf{x})}{\partial x_n}\right)$$

exists everywhere.

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- ▶ for all  $\mathbf{x}, \mathbf{y} \in \operatorname{dom} f$

$$f(\mathbf{y}) \geq f(\mathbf{x}) + \nabla f(\mathbf{x})^T (\mathbf{y} - \mathbf{x})$$

(the function is above any of its tangents.)



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Let dom f = X be convex.

 $f: X \to \mathbb{R} \text{ convex} \Leftrightarrow f(\mathbf{y}) \ge f(\mathbf{x}) + \nabla f(\mathbf{x})^T (\mathbf{y} - \mathbf{x}) \quad \forall \mathbf{x}, \mathbf{y}$ 



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 $= f(z) + \nabla f(z)^T z - \nabla f(z)^T z = f(z) = f(\theta x + (1 - \theta)y)$ 

# 1st-Order Condition / Strict Variant



#### strict 1st-order condition: a differentiable function f is strictly convex iff

- ▶ dom f is a convex set
- ▶ for all  $\mathbf{x}, \mathbf{y} \in \operatorname{dom} f$

$$f(\mathbf{y}) > f(\mathbf{x}) + \nabla f(\mathbf{x})^{\mathsf{T}}(\mathbf{y} - \mathbf{x})$$

## Global Minima



Let dom f = X be convex.

$$f: X \to \mathbb{R} \text{ convex} \Leftrightarrow f(\mathbf{y}) \ge f(\mathbf{x}) + \nabla f(\mathbf{x})^T (\mathbf{y} - \mathbf{x}) \quad \forall \mathbf{x}, \mathbf{y}$$

Consequence: Points x with  $\nabla f(x) = 0$  are (equivalent) global minima.

- minima form a convex set
- if f is strictly convex: there is exactly one global minimum  $x^*$ .

# 2nd-Order Condition



f is **twice differentiable** if dom f is open and the Hessian  $\nabla^2 f(x)$ 

$$\nabla^2 f(\mathbf{x})_{n,m} = \frac{\partial^2 f(\mathbf{x})}{\partial x_n \partial x_m}$$

exists everywhere.

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- if  $\nabla^2 f(\mathbf{x}) \succ 0$  for all  $\mathbf{x} \in \text{dom } f$ , then f is strictly convex
  - the converse is not true, e.g.,  $f(x) = x^4$  is strictly convex, but has 0 derivative at 0.



Positive Semidefinite Matrices (A Reminder) A symmetric matrix  $A \in \mathbb{R}^{n \times n}$  is **positive semidefinite**  $(A \succeq 0)$ :

$$x^T A x \ge 0, \quad \forall x \in \mathbb{R}^N$$

Equivalent:

- (i) all eigenvalues of A are  $\geq 0$ .
- (ii)  $A = B^T B$  for some matrix B



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A symmetric matrix  $A \in \mathbb{R}^{N \times N}$  is **positive definite**  $(A \succ 0)$ :

$$x^T A x > 0, \quad \forall x \in \mathbb{R}^N \setminus \{0\}$$

Equivalent:

- (i) all eigenvalues of A are > 0.
- (ii)  $A = B^T B$  for some nonsingular matrix B



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- Example:  $5x^2$  is convex since  $x^2$  is convex

#### Sum:

• if  $f_1$  and  $f_2$  are convex functions then  $f_1 + f_2$  is convex.



- There are a number of operations that preserve the convexity of a function.
- If f can be obtained by applying those operations to a convex function, f is also convex.

#### Nonnegative multiple:

- if f is convex and  $a \ge 0$  then af is convex.
- Example:  $5x^2$  is convex since  $x^2$  is convex

#### Sum:

- if  $f_1$  and  $f_2$  are convex functions then  $f_1 + f_2$  is convex.
- ► Example: f(x) = e<sup>3x</sup> + x log x with dom f = ℝ<sup>+</sup> is convex since e<sup>3x</sup> and x log x are convex



#### Composition with the affine function:

• if f is convex then  $f(A\mathbf{x} + \mathbf{b})$  is convex.

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▶ if f<sub>1</sub>,..., f<sub>m</sub> are convex functions then f(x) = max{f<sub>1</sub>(x),..., f<sub>m</sub>(x)} is convex.



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#### **Pointwise Maximum:**

- ▶ if f<sub>1</sub>,..., f<sub>m</sub> are convex functions then f(x) = max{f<sub>1</sub>(x),..., f<sub>m</sub>(x)} is convex.
- Example:  $f(\mathbf{x}) = \max_{i=1,\dots,l} (a_i^T \mathbf{x} + b_i)$  is convex

#### Composition with scalar functions:

▶ if 
$$g : \mathbb{R}^N \to \mathbb{R}$$
,  $h : \mathbb{R} \to \mathbb{R}$  and

$$f(\mathbf{x}) = h(g(\mathbf{x}))$$



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- ► *f* is convex if:
  - ▶ g is convex, h is convex and nondecreasing or
  - ▶ g is concave, h is convex and nonincreasing



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- ► *f* is convex if:
  - ▶ g is convex, h is convex and nondecreasing or
  - g is concave, h is convex and nonincreasing
- ► Examples:
  - $e^{g(\mathbf{x})}$  is convex if g is convex
  - $\frac{1}{g(\mathbf{x})}$  is convex if g is concave and positive



Modern Optimization Techniques 3. Convex Functions

#### Recognizing Convex Functions



There are many different ways to establish the convexity of a function:

Apply the definition



There are many different ways to establish the convexity of a function:

- Apply the definition
- Show that  $\nabla^2 f(\mathbf{x}) \succeq 0$  for twice differentiable functions



There are many different ways to establish the convexity of a function:

- Apply the definition
- Show that  $\nabla^2 f(\mathbf{x}) \succeq 0$  for twice differentiable functions
- Show that f can be obtained from other convex functions by operations that preserve convexity

#### Outline



- 1. Introduction
- 2. Convex Sets
- 3. Convex Functions
- 4. Optimization Problems

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#### **Optimization Problem**

$$\begin{array}{ll} \mbox{minimize} & f(\mathbf{x}) \\ \mbox{subject to} & g_p(\mathbf{x}) = 0, \quad p = 1, \dots, P \\ & h_q(\mathbf{x}) \leq 0, \quad q = 1, \dots, Q \end{array}$$

- $f : \mathbb{R}^N \to \mathbb{R}$  is the objective function
- $\mathbf{x} \in \mathbb{R}^N$  are the optimization variables
- ▶  $g_p : \mathbb{R}^N \to \mathbb{R}, p = 1, ..., P$  are the equality constraint functions
- ▶  $h_q : \mathbb{R}^N \to \mathbb{R}, q = 1, \dots, Q$  are the inequality constraint functions



#### Convex Optimization Problem An optimization problem

$$\begin{array}{ll} \text{minimize} & f(\mathbf{x}) \\ \text{subject to} & g_p(\mathbf{x}) = 0, \quad p = 1, \dots, P \\ & h_q(\mathbf{x}) \leq 0, \quad q = 1, \dots, Q \end{array}$$

is said to be **convex** if

- ► f is convex,
- $g_1, \ldots, g_P$  are affine and
- $h_1, \ldots h_Q$  are convex.

$$\begin{array}{ll} \text{minimize} & f(\mathbf{x})\\ \text{subject to} & A\mathbf{x} = a\\ & h_q(\mathbf{x}) \leq 0, \quad q = 1, \dots, Q \end{array}$$



# Example 1: Linear Regression / Household Spending

Suppose we have the following data about different households:

- Number of workers in the household  $(a_1)$
- ▶ Household composition (*a*<sub>2</sub>)
- Region  $(a_3)$
- ► Gross normal weekly household income (*a*<sub>4</sub>)
- ► Weekly household spending (y)



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- ► Weekly household spending (y)

We want to create a model of the weekly household spending

#### Example 1: Linear Regression

If we have data about M households, we can represent it as:

$$A = \begin{pmatrix} 1 & a_{1,1} & a_{1,2} & a_{1,3} & a_{1,4} \\ 1 & a_{2,1} & a_{2,2} & a_{2,3} & a_{2,4} \\ \vdots & \vdots & \vdots & \vdots & \vdots \\ 1 & a_{M,1} & a_{M,2} & a_{M,3} & a_{M,4} \end{pmatrix}, \quad \mathbf{y} = \begin{pmatrix} y_1 \\ y_2 \\ \vdots \\ y_M \end{pmatrix}$$

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We can model the household consumption is a linear combination of the household features with parameters  $\beta$ :

$$\hat{y}_m = \beta^T A_{m,.} = \beta_0 1 + \beta_1 a_{m,1} + \beta_2 a_{m,2} + \beta_3 a_{m,3} + \beta_4 a_{m,4}, \quad m = 1, \dots, M$$

Modern Optimization Techniques 4. Optimization Problems

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#### Example 1: Linear Regression

We have:

$$\begin{pmatrix} 1 & a_{1,1} & a_{1,2} & a_{1,3} & a_{1,4} \\ 1 & a_{2,1} & a_{2,2} & a_{2,3} & a_{2,4} \\ \vdots & \vdots & \vdots & \vdots & \vdots \\ 1 & a_{M,1} & a_{M,2} & a_{M,3} & a_{M,4} \end{pmatrix} \cdot \begin{pmatrix} \beta_0 \\ \beta_1 \\ \beta_2 \\ \beta_3 \\ \beta_4 \end{pmatrix} \approx \begin{pmatrix} y_1 \\ y_2 \\ \vdots \\ y_M \end{pmatrix}$$

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#### Example 1: Linear Regression

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We want to find parameters  $\beta$  such that the measured error of the predictions is minimal:

$$\sum_{m=1}^{M} (\beta^{T} A_{m,.} - y_{m})^{2} = ||A\beta - \mathbf{y}||_{2}^{2}$$

minimize  $||A\beta - \mathbf{y}||_2^2$ 

$$||A\beta - \mathbf{y}||_2^2 = (A\beta - \mathbf{y})^T (A\beta - \mathbf{y})$$

minimize  $||A\beta - \mathbf{y}||_2^2$ 

$$||Aeta - \mathbf{y}||_2^2 = (Aeta - \mathbf{y})^T (Aeta - \mathbf{y})$$

$$\frac{d}{d\beta}(A\beta - \mathbf{y})^T(A\beta - \mathbf{y}) = 2A^T(A\beta - \mathbf{y})$$

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$$2A^T(A\beta - \mathbf{y}) = 0$$

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$$rac{d}{deta}(Aeta-\mathbf{y})^{T}(Aeta-\mathbf{y})=2A^{T}(Aeta-\mathbf{y})$$

$$2A^{T}(A\beta - \mathbf{y}) = 0$$
$$A^{T}A\beta - A^{T}\mathbf{y} = 0$$

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$$2A^{T}(A\beta - \mathbf{y}) = 0$$
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$$A^{T}A\beta = A^{T}\mathbf{y}$$
$$\beta = (A^{T}A)^{-1}A^{T}\mathbf{y}$$

Modern Optimization Techniques 4. Optimization Problems



minimize 
$$||A\beta - \mathbf{y}||_2^2$$

Modern Optimization Techniques 4. Optimization Problems

# Example 1: Linear Regression / Least Squares Problem

minimize 
$$||A\beta - \mathbf{y}||_2^2$$

- Convex Problem!
- Analytical solution:  $\beta^* = (A^T A)^{-1} A^T \mathbf{y}$
- Often applied for data fitting
- $A\beta \mathbf{y}$  is usually called the residual or error
- Extensions such as regularized least squares



### Example 2: Linear Classification / Household Location

Suppose we have the following data about different households:

- Number of workers in the household  $(a_1)$
- ► Household composition (*a*<sub>2</sub>)
- ▶ Weekly household spending (*a*<sub>3</sub>)
- ► Gross normal weekly household income (*a*<sub>4</sub>)
- **Region** (y): north y = 1 or south y = 0


Suppose we have the following data about different households:

- ▶ Number of workers in the household (*a*<sub>1</sub>)
- ► Household composition (*a*<sub>2</sub>)
- ▶ Weekly household spending (*a*<sub>3</sub>)
- ► Gross normal weekly household income (*a*<sub>4</sub>)
- **Region** (y): north y = 1 or south y = 0

We want to create a model of the location of the household



## Example 2: Linear Classification

If we have data about M households, we can represent it as:

$$A = \begin{pmatrix} 1 & a_{1,1} & \dots & a_{1,4} \\ 1 & a_{2,1} & \dots & a_{2,4} \\ \vdots & \vdots & \vdots & \vdots \\ 1 & a_{M,1} & \dots & a_{M,4} \end{pmatrix}, \quad \mathbf{y} = \begin{pmatrix} y_1 \\ y_2 \\ \vdots \\ y_M \end{pmatrix}$$



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We can model the probability of the household location to be north (y = 1) as a linear combination of the household features with parameters  $\beta$ :

$$\hat{y}_{m} = \sigma(\beta^{T} A_{m,.}) = \sigma(\beta_{0} 1 + \beta_{1} a_{m,1} + \beta_{2} a_{m,2} + \beta_{3} a_{m,3} + \beta_{4} a_{m,4}), \quad m = 1, \dots, M$$

where:  $\sigma(x) := \frac{1}{1+e^{-x}}$  (logistic function)

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## Example 2: Linear Classification / Logistic Regression

The logistic regression learning problem is

maximize 
$$\sum_{m=1}^{M} y_m \log \sigma(\beta^T A_{m,.}) + (1 - y_m) \log(1 - \sigma(\beta^T A_{m,.}))$$

$$A = \begin{pmatrix} 1 & a_{1,1} & a_{1,2} & a_{1,3} & a_{1,4} \\ 1 & a_{2,1} & a_{2,2} & a_{2,3} & a_{2,4} \\ \vdots & \vdots & \vdots & \vdots & \vdots \\ 1 & a_{M,1} & a_{M,2} & a_{M,3} & a_{M,4} \end{pmatrix}, \quad \mathbf{y} = \begin{pmatrix} y_1 \\ y_2 \\ \vdots \\ y_M \end{pmatrix}$$

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## Example 3: Linear Programming



$$\begin{array}{ll} \mbox{minimize} & \mathbf{c}^T \mathbf{x} \\ \mbox{subject to} & \mathbf{a}_q^T \mathbf{x} \leq b_q & q = 1, \dots, Q \\ & \mathbf{x} \geq 0 \\ \mathbf{c}, \mathbf{a}_q, \mathbf{x} \in \mathbb{R}^N, b_q \in \mathbb{R} \end{array}$$

- ► No simple analytical solution.
- There are reliable algorithms available:
  - Simplex
  - Interior Points Method

# Summary (1/2)



- **Convex sets** are closed under line segments (convex combinations).
- Convex functions are defined on a convex domain and
  - ▶ are below any of their secant segments / chords (definition)
  - ► are globally above their tangents (1st-order condition)
  - ▶ have a positive semidefinite Hessian (2nd-order condition)
- For convex functions, points with vanishing gradients are (equivalent) global minima.
- Operations that preserve convexity:
  - scaling with a nonnegative constant
  - ► sums
  - pointwise maximum
  - composition with an affine function
  - composition with a nondecreasing convex scalar function
  - composition of a nonincreasing convex scalar function with a concave function
    - esp. -g for a concave g

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# Summary (2/2)

- General optimization problems consist of
  - an objective function,
  - equality constraints.
  - inequality constraints and

#### Convex optimization problems have

- a convex objective function,
- affine equality constraints and
- convex inequality constraints.
- Examples for convex optimization problems:
  - Inear regression / least squares
  - ► linear classification / logistic regression
  - linear programming
  - quadratic programming



# Further Readings



- Convex sets:
  - ▶ Boyd and Vandenberghe [2004], chapter 2, esp. 2.1
  - see also ch. 2.2 and 2.3
- Convex functions:
  - ► Boyd and Vandenberghe [2004], chapter 3, esp. 3.1.1–7, 3.2.1–5
- Convex optimization:
  - ► Boyd and Vandenberghe [2004], chapter 4, esp. 4.1–3
  - ▶ see also ch. 4.4

#### References I

Stephen Boyd and Lieven Vandenberghe. Convex Optimization. Cambridge Univ Press, 2004.

